Hygro-thermo-mechanical bending analysis of FGM plates using a new HSDT

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Abstract. In this paper, a novel higher-order shear deformation theory (HSDT) is proposed for the analysis of the hygrothermo-mechanical behavior of functionally graded (FG) plates resting on elastic foundations. The developed model uses a novel kinematic by considering undetermined integral terms and only four variables are used in this model. The governing equations are deduced based on the principle of virtual work and the number of unknown functions involved is reduced to only four, which is less than the first shear deformation theory (FSDT) and others HSDTs. The Navier-type exact solutions for static analysis of simply supported FG plates subjected to hygro-thermo-mechanical loads are presented. The accuracy and efficiency of the present model is validated by comparing it with various available solutions in the literature. The influences of material properties, temperature, moisture, plate aspect ratio, side-to-thickness ratios and elastic coefficients parameters on deflections and stresses of FG plates are also investigated.

Keywords: bending; functionally graded materials; plate theory; hygro-thermo-mechanical loads

1. Introduction

Functionally graded materials (FGMs) are the novel generation of advanced composite materials in the area of engineering composites, whose characteristics are changed smoothly in the spatial direction microscopically to improve the overall structural performance. These materials provide great promise in important temperature environments, e.g., wear-resistant linings for handling large heavy abrasive ore particles, rocket heat shields, heat exchanger tubes, thermoelectric generators, heat engine components, plasma facings for fusion reactors, and electrically insulating metal/ceramic joints and also these are widely employed in many structural applications such as mechanics, civil engineering, optical, electronic, chemical, biomedical, energy sources, nuclear, automotive fields, and ship building industries to minimize thermo mechanical mismatch in metal-ceramic bonding (Reddy 2011, Yaghoobi and Yaghoobi 2013, Swaminathan and Naveenkumar 2014, Ahmed 2014, Darilmaz 2015, Kar and Panda 2015a, b, Belkorissat et al. 2015, Hadji and Adda Bedia 2015, Ait Yahia 2015, Akavci 2015, Bounouara et al. 2016, Kolahchi et al. 2016, Belabed et al. 2014, Aldousari 2017, Rahmani et al. 2017, Hirwani et al. 2018a, b,

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Copyright © 2018 Techno-Press, Ltd. http://www.techno-press.com/journals/sss&subpage=7 Abualnour et al. 2018).

Presently, various investigations are carried out for theoretically studying the thermo-mechanical response behavior of FG structures. Zhang et al. (1994) proposed an analytical method for FG cylinder with axial symmetry based on thermal elasticity theory. Reddy and Chen (2001) developed a three-dimensional model for a FG plate under mechanical and thermal loads, both applied at the top of the plate. The analysis of the thermo-mechanical response of hollow circular cylinders fabricated with FGM was studied by Liew et al. (2003). Vel and Batra (2003) presented a three-dimensional solution for transient thermal stresses in FG rectangular plates. The buckling analysis of shear deformable FG rectangular plates subjected to thermomechanical loads was studied by Shukla et al. (2007) using FSDT. The thermal bending behavior of a piezoelectric circularly curved FG actuator under an applied electric force is investigated by Zaman et al. (2010). Golmakani and Kadkhodayan (2011) studied a large deflection behavior of shear deformable FG plates subjected to thermo-mechanical loads and under various boundary conditions via the dynamic relaxation method. Fallah and Nosier (2012) used two parameter perturbation technique and Fourier series method to examine nonlinear response of FG circular plates with various clamped and simply supported boundary conditions. Bouderba et al. (2013) discussed thermomechanical static response of FG thick plates resting on Winkler-Pasternak elastic foundations based on a refined trigonometric shear deformation theory. Zhu et al. (2014)

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analyzed a geometrically nonlinear thermo-mechanical analysis of moderately thick FG plates by employing a local meshless method with Kriging interpolation procedure. Tung and Duc (2014) investigated the nonlinear behavior of thick FG doubly curved shallow panels resting on elastic foundations and under some conditions of mechanical, thermal, and thermo-mechanical loads. Tounsi et al. (2013) presented a thermo-elastic bending analysis of FG sandwich plates by employing a refined trigonometric shear deformation theory. In their work, the core layer is FGM and two face sheets have different material properties. Houari et al. (2013) proposed a novel higher order shear and normal deformation theory for thermo-elastic bending of FG sandwich plates. Zidi et al. (2014) discussed the static response of FG plates under hygro-thermomechanical loading using a four variable refined plate theory. Attia et al. (2015) presented a free vibration analysis of FG plates with temperature-dependent properties using various four variable refined plate theories. Akbaş (2015) examined the wave propagation of a functionally graded beam in thermal environments. Sobhy (2015) studied the thermo-elastic behavior of FG plates with temperaturedependent properties resting on variable elastic foundations. Mantari and Granados (2015) investigated a thermo-elastic bending behavior of two types of FGM sandwich plates by using a new quasi-3D hybrid type higher order shear deformation theory with 5 unknowns. Li et al. (2016) investigated the thermo-mechanical bending behavior of FG sandwich plates using four-variable refined plate theory. Laoufi et al. (2016) examined the mechanical and hygrothermal response of FG plates using a hyperbolic shear deformation theory. Beldjelili et al. (2016) studied the hygro-thermo-mechanical bending of S-FGM plates resting on variable elastic foundations using a four-variable trigonometric plate theory. Mehar and Panda (2017) presented a numerical investigation of nonlinear thermomechanical deflection of functionally graded CNT reinforced doubly curved composite shell panel under different mechanical loads. Recent works on flexural behavior of the composite structure using HSDT are presented by Benchohra et al. (2018), Youcef et al. (2018), Mahapatra et al. (2017), Abdelaziz et al. (2017), Chikh et al. (2017), Draiche et al. (2016), Bouafia et al. (2017), Benadouda et al. (2017, Hirwani et al. (2016), Bennoun et al. (2016), Hirwani et al. (2017), Bellifa et al. (2017a), Mahapatra et al. (2016a, b), Kar and Panda (2015c, 2016a,b,c), Barati and Shahverdi (2016), Barka et al. (2016), and Kar et al. (2015).

The purpose of this article is to investigate the bending response of FG plates resting on variable two-parameter elastic foundations and subjected to hygro-thermomechanical loads. The use of the integral term in the kinematic led to a reduction in the number of variables and equilibrium equations. These latter are deduced using the new proposed HSDT containing the hygro-thermomechanical effect and the interaction between the plate and the elastic foundations. The results obtained by the present theory are compared with those reported by other HSDTs available in the open literature. Some numerical examples are offered to demonstrate the influences of various parameters on the hygro-thermo-mechanical bending response of the FG plates.

2. Mathematical formulation

Consider a rectangular FG plate with sides $a \times b$ and uniform thickness h, referred to the rectangular Cartesian coordinates (x, y, z), where (x, y) plane coincides with middle surface of the plate and (z) is the thickness coordinate $(-h/2 \le z \le h/2)$, as presented in Fig. 1.

The FG plate is subjected to a transverse load q(x, y) and a temperature field T(x, y, z) as well as a moisture concentration C(x, y, z). The material characteristics of the plate are supposed to change within the thickness of the plate. By applying a simple power law distribution, the volume fractions (V) of metal and ceramic are defined as (Bessaim *et al.* 2013, Ait Amar Meziane *et al.* 2014, Bellifa *et al.* 2016, Ahouel *et al.*, 2016, Boukhari *et al.* 2016, Hanifi Hachemi Amar *et al.* 2017).

$$V_{c}(z) = \left(\frac{z}{h} + \frac{1}{2}\right)^{p}, \quad (0 \le p \le \infty), \quad V_{c}(z) + V_{m}(z) = 1 \quad (1)$$

where *p* is the power-law index and the subscripts *c* and *m* represent ceramic and metal, respectively. The material properties *P* of the FG plate, such as Young's modulus *E*, Poisson's ratio *v*, and thermal coefficient α and moisture expansion β are expressed as (Mouffoki *et al.* 2017, El-Haina *et al.* 2017, Bouderba *et al.* 2016, Saidi *et al.* 2016, Bousahla *et al.* 2016, Hamidi *et al.* 2015, Larbi Chaht *et al.* 2015, Al-Basyouni *et al.* 2015)

$$P(z) = \left(P_c - P_m\right)V_c(z) + P_m \tag{2}$$

2.1 Displacement base field

The displacement field of the novel theory is proposed as follows (Bellifa *et al.* 2017b, Besseghier *et al.* 2017, Khetir *et al.* 2017, Menasria *et al.* 2017, Yazid *et al.* 2018, Bousahla *et al.* 2018)



Fig. 1 Geometry and coordinates of the rectangular FG plate resting on elastic foundation

$$u(x, y, z) = u_0(x, y) - z \frac{\partial w_0}{\partial x} + k_1 f(z) \int \theta(x, y) dx$$
$$v(x, y, z) = v_0(x, y) - z \frac{\partial w_0}{\partial y} + k_2 f(z) \int \theta(x, y) dy \quad (3a,b,c)$$

 $w(x, y, z) = w_0(x, y)$

Where $u_0(x, y)$, $v_0(x, y)$, $w_0(x, y)$ and $\theta(x, y)$ are the four variable displacement functions of middle plane of the plate. The last variable is a mathematical term that allows determining the rotations of the normal to the mid plate about the x and y axes (as in the ordinary HSDT). Note that the integrals do not have limits. In the present work is considered terms with integrals instead of terms with derivatives. In this work, the present HSDT is obtained by setting

$$f(z) = \frac{z \cosh(\pi/2) - (h/\pi) \sinh\left(\frac{\pi}{h}z\right)}{\cosh(\pi/2) - 1}$$
(4)

It can be observed that the kinematic in Eq. (3) employs only four variables $(u_0, v_0, w_0 \text{ and } \theta)$. The nonzero strains associated with the kinematic in Eq. (3) are

$$\begin{cases} \boldsymbol{\varepsilon}_{x} \\ \boldsymbol{\varepsilon}_{y} \\ \boldsymbol{\gamma}_{xy} \end{cases} = \begin{cases} \boldsymbol{\varepsilon}_{x}^{0} \\ \boldsymbol{\varepsilon}_{y}^{0} \\ \boldsymbol{\gamma}_{xy}^{0} \end{cases} + z \begin{cases} \boldsymbol{k}_{x}^{0} \\ \boldsymbol{k}_{y}^{0} \\ \boldsymbol{k}_{xy}^{0} \end{cases} + f(z) \begin{cases} \boldsymbol{L}_{x}^{0} \\ \boldsymbol{L}_{y}^{0} \\ \boldsymbol{L}_{xy}^{0} \end{cases} \\ \begin{cases} \boldsymbol{\gamma}_{yz} \\ \boldsymbol{\gamma}_{xz} \end{cases} = g(z) \begin{cases} \boldsymbol{\gamma}_{yz}^{0} \\ \boldsymbol{\gamma}_{xz}^{0} \end{cases} \end{cases}$$
(5a)

Where

$$\begin{cases} \varepsilon_{x}^{0} \\ \varepsilon_{y}^{0} \\ \gamma_{xy}^{0} \end{cases} = \begin{cases} \frac{\partial u_{0}}{\partial x} \\ \frac{\partial v_{0}}{\partial x} \\ \frac{\partial u_{0}}{\partial y} + \frac{\partial v_{0}}{\partial x} \end{cases} \quad \begin{cases} k_{x}^{0} \\ k_{y}^{0} \\ k_{xy}^{0} \end{cases} = \begin{cases} -\frac{\partial^{2} w_{0}}{\partial x^{2}} \\ -\frac{\partial^{2} w_{0}}{\partial y^{2}} \\ -2\frac{\partial^{2} w_{0}}{\partial x \partial y} \end{cases}$$
(5b)

$$\begin{cases} L_x^0 \\ L_y^0 \\ L_{xy}^0 \end{cases} = \begin{cases} k_1 \theta \\ k_2 \theta \\ k_1 \frac{\partial}{\partial y} \int \theta \, dx + k_2 \frac{\partial}{\partial x} \int \theta \, dy \end{cases}$$
$$\begin{cases} \gamma_{yz}^0 \\ \gamma_{xz}^0 \\ \chi_{xz}^0 \end{cases} = \begin{cases} k_2 \int \theta \, dy \\ k_1 \int \theta \, dx \end{cases}$$

 $g(z) = \frac{df(z)}{dz}$ (5c)

The integrals used in the above equations shall be resolved by a Navier type procedure and can be expressed as follows

$$\frac{\partial}{\partial y} \int \theta \, dx = A' \frac{\partial^2 \theta}{\partial x \partial y}, \quad \frac{\partial}{\partial x} \int \theta \, dy = B' \frac{\partial^2 \theta}{\partial x \partial y},$$

$$\int \theta \, dx = A' \frac{\partial \theta}{\partial x}, \quad \int \theta \, dy = B' \frac{\partial \theta}{\partial y} \tag{6}$$

Where, the coefficients A' and B' are defined according to the type of solution employed, in this case via Navier solution. Therefore, A', B', k_1 and k_2 are defined as follows

$$A' = -\frac{1}{\lambda^2}, \quad B' = -\frac{1}{\mu^2}, \quad k_1 = \lambda^2, \quad k_2 = \mu^2$$
(7)

where λ and μ are defined in expression (24).

2.2 Constitutive equations

For the FG plate, the stress - strain relationships can be expressed as

$$\begin{cases} \sigma_{x} \\ \sigma_{y} \\ \tau_{xy} \\ \tau_{yz} \\ \tau_{xz} \end{cases} = \begin{bmatrix} C_{11} & C_{12} & 0 & 0 & 0 \\ C_{12} & C_{22} & 0 & 0 & 0 \\ 0 & 0 & C_{66} & 0 & 0 \\ 0 & 0 & 0 & C_{44} & 0 \\ 0 & 0 & 0 & 0 & C_{55} \end{bmatrix} \begin{bmatrix} \varepsilon_{x} - \alpha \, \Delta T - \beta \, \Delta C \\ \varepsilon_{y} - \alpha \, \Delta T - \beta \, \Delta C \\ \gamma_{xy} \\ \gamma_{yz} \\ \gamma_{xz} \end{bmatrix}$$
(8)

Where $(\sigma_x, \sigma_y, \tau_{xy}, \tau_{yz}, \tau_{xz})$ and $(\varepsilon_x, \varepsilon_y, \gamma_{xy}, \tau_{yz})$

 γ_{yz} , γ_{xz}) are the stress and strain components, respectively. Using the material properties defined in Eq. (2), stiffness coefficients, C_{ij} , can be given as

$$C_{11} = C_{22} = \frac{E(z)}{1 - v^2}, \ C_{12} = \frac{v E(z)}{1 - v^2},$$

$$C_{44} = C_{55} = C_{66} = \frac{E(z)}{2(1 + v)},$$
(9)

Where $\Delta T = T - T_0$ and $\Delta C = C - C_0$ in which T_0 is the reference temperature and C_0 is the reference moisture concentration. In the present work, the moisture concentration C(x, y, z) and the temperature distribution field T(x, y, z) are expressed as (Bouderba *et al.* 2013)

$$T(x, y, z) = T_1(x, y) + \frac{z}{h} T_2(x, y) + \overline{\Psi}(z) T_2(x, y)$$
(10a)

$$C(x, y, z) = C_1(x, y) + \frac{z}{h}C_2(x, y) + \overline{\Psi}(z)C_2(x, y)$$
(10b)

And

In which $\overline{\Psi}(z) = \frac{1}{\pi} \sin\left(\frac{\pi}{h}z\right)$ in the case of sinusoidal temperature distribution, $\overline{\Psi}(z) = \frac{z}{h} \left(1 - \frac{4}{3} \left(\frac{z}{h}\right)^2\right)$ in the case of cubic temperature distribution and $\overline{\Psi}(z) = \frac{z}{h} e^{-2\left(\frac{z}{h}\right)^2}$ in the case of exponential temperature distribution.

2.3 Governing equations

The governing equations of equilibrium can be determined by using the principle of virtual displacements. The principle of virtual work in the this case yields (Zidi *et al.* 2017, Houari *et al.* 2016, Bousahla *et al.* 2014, Hebali *et al.* 2014, Bourada *et al.* 2015, Mahi *et al.* 2015, Zemri *et al.* 2015)

$$\int_{\Omega-h/2}^{h/2} \left[\sigma_x \,\delta \,\varepsilon_x + \sigma_y \,\delta \,\varepsilon_y + \tau_{xy} \,\delta \,\gamma_{xy} + \tau_{xz} \,\delta \,\gamma_{xz} + \tau_{yz} \,\delta \,\gamma_{yz} \right] dz \,d\Omega$$

$$-\int_{\Omega} (q - f_e) \delta \,w \,d\Omega = 0$$
(11)

Where Ω is the top surface, and f_e is the density of reaction force of foundation. For the Pasternak foundation model

$$f_e = K_w w - K_{sx} \frac{\partial^2 w}{\partial x^2} - K_{sy} \frac{\partial^2 w}{\partial y^2}$$
(12)

where K_w is the modulus of subgrade reaction (elastic coefficient of the foundation) and K_{sx} and K_{sy} are the shear moduli of the subgrade (shear layer foundation stiffness). If the foundation is homogeneous and isotropic, this implies that $K_{sx} = K_{sy} = K_s$. If the shear layer foundation stiffness is neglected, Pasternak foundation becomes a Winkler foundation.

Substituting Eqs. (5) and (8) into Eq. (12) and integrating across the thickness of the plate, Eq. (12) can be expressed as

$$\int_{\Omega} \left[N_x \delta \varepsilon_x^0 + N_y \delta \varepsilon_y^0 + N_{xy} \delta \gamma_{xy}^0 + M_x \delta k_x^0 + M_y \delta k_y^0 + M_{xy} \delta k_{xy}^0 + S_x \delta L_x^0 + S_y \delta L_y^0 + S_{xy} \delta L_{xy}^0 + R_y \delta \gamma_{yz}^0 + R_x \delta \gamma_{xz}^0 \right] d\Omega - \int_{\Omega} (q - f_e) \delta w d \Omega = 0$$

$$(13)$$

where the stress resultants N, M, S, and R are defined by

$$(N_i, M_i, S_i) = \int_{-h/2}^{h/2} (1, z, f) \sigma_i dz, \quad (i = x, y, xy) \text{ and}$$

$$(R_{xz}, R_{yz}) = \int_{-h/2}^{h/2} g(\tau_{xz}, \tau_{yz}) dz$$

$$(14)$$

Substituting Eq. (8) into Eq. (15) and integrating across the thickness of the plate, the stress resultants are expressed as

 $\langle \rangle$

$$\begin{cases} N_x \\ N_y \\ N_{xy} \\ M_x \\ M_y \\ M_x \\ M_y \\ S_x \\ S_y \\ S_{xy} \end{cases} = \begin{bmatrix} A_{11} & A_{12} & 0 & B_{11} & B_{12} & 0 & B_{11}^s & B_{12}^s & 0 \\ A_{12} & A_{22} & 0 & B_{12} & B_{22} & 0 & B_{12}^s & B_{22}^s & 0 \\ 0 & 0 & A_{66} & 0 & 0 & B_{66} & 0 & 0 & B_{66}^s \\ B_{11} & B_{12} & 0 & D_{11} & D_{12} & 0 & D_{11}^s & D_{12}^s & 0 \\ B_{12} & B_{22} & 0 & D_{12} & D_{22} & 0 & D_{12}^s & D_{22}^s & 0 \\ 0 & 0 & B_{66} & 0 & 0 & D_{66}^s & 0 & 0 & D_{66}^s \\ B_{11}^s & B_{12}^s & 0 & D_{11}^s & D_{12}^s & 0 & D_{16}^s \\ B_{12} & B_{22} & 0 & D_{12} & D_{22} & 0 & D_{12}^s & D_{22}^s & 0 \\ 0 & 0 & B_{66} & 0 & 0 & D_{66}^s & 0 & 0 & D_{66}^s \\ B_{11}^s & B_{12}^s & 0 & D_{11}^s & D_{12}^s & 0 & H_{11}^s & H_{12}^s & 0 \\ B_{12}^s & B_{22}^s & 0 & D_{12}^s & D_{22}^s & 0 & H_{12}^s & H_{22}^s & 0 \\ B_{11}^s & B_{12}^s & 0 & D_{12}^s & D_{22}^s & 0 & H_{12}^s & H_{22}^s & 0 \\ B_{12}^s & B_{22}^s & 0 & D_{12}^s & D_{22}^s & 0 & H_{12}^s & H_{22}^s & 0 \\ B_{11}^s & B_{12}^s & 0 & D_{12}^s & D_{22}^s & 0 & H_{13}^s & H_{22}^s & 0 \\ 0 & 0 & B_{66}^s & 0 & 0 & D_{66}^s & 0 & 0 & H_{66}^s \\ \end{bmatrix} \begin{bmatrix} A_y \\ B_y \\ B_y \\ B_y \\ B_y \\ B_y \end{bmatrix} = \begin{bmatrix} A_{11} & A_{12} & A_{1$$

$$\begin{cases} R_{yz} \\ R_{xz} \end{cases} = \begin{bmatrix} A_{44}^s & 0 \\ 0 & A_{55}^s \end{bmatrix} \begin{cases} \gamma_{yz}^0 \\ \gamma_{xz}^0 \end{cases}$$
(15b)

Where stiffness components are defined as

$$\begin{cases} A_{11} & B_{11} & D_{11} & B_{11}^{s} & D_{11}^{s} & H_{11}^{s} \\ A_{12} & B_{12} & D_{12} & B_{12}^{s} & D_{12}^{s} & H_{12}^{s} \\ A_{66} & B_{66} & D_{66} & B_{66}^{s} & D_{66}^{s} & H_{66}^{s} \\ \end{cases} = \int_{-h/2}^{h/2} C_{11} \left(1, z, z^{2}, f(z), zf(z), f^{2}(z) \right) \left\{ \begin{array}{c} 1 \\ v \\ \frac{1-v}{2} \end{array} \right\} dz \quad (16a)$$

 $\begin{pmatrix} A_{22}, B_{22}, D_{22}, B_{22}^{s}, D_{22}^{s}, H_{22}^{s} \end{pmatrix} = \begin{pmatrix} A_{11}, B_{11}, D_{11}, B_{11}^{s}, D_{11}^{s}, H_{11}^{s} \end{pmatrix}$ (16b) The stress and moment resultants, $N_{x}^{T} = N_{y}^{T}$, $M_{x}^{T} = M_{y}^{T}$, $S_{x}^{T} = S_{y}^{T}$, $N_{x}^{C} = N_{y}^{C}$, $M_{x}^{C} = M_{y}^{C}$, $S_{x}^{C} = S_{y}^{C}$, to thermal and hygroscopic loading are defined by

$$\begin{cases} N_x^T \\ M_x^T \\ S_x^T \end{cases} = \int_{-h/2}^{h/2} \frac{E(z)}{1-\nu} \alpha(z) T \begin{cases} 1 \\ z \\ f(z) \end{cases} dz$$
(17a)

$$\begin{cases} N_x^C \\ M_x^C \\ S_x^C \\ S_x^C \end{cases} = \int_{-h/2}^{h/2} \frac{E(z)}{1-\nu} \beta(z) C \begin{cases} 1 \\ z \\ f(z) \end{cases} dz \qquad (17b)$$

The governing equations of equilibrium can be obtained from Eq. (14) by integrating the displacement gradients by parts and setting the coefficients δu_0 , δv_0 , δw_0 and $\delta \theta$ zero separately. Thus one can obtain the governing equations associated with the present HSDT

$$\delta u_{0}: \quad \frac{\partial N_{x}}{\partial x} + \frac{\partial N_{xy}}{\partial y} = 0$$

$$\delta v_{0}: \quad \frac{\partial N_{xy}}{\partial x} + \frac{\partial N_{y}}{\partial y} = 0$$

$$\delta w_{0}: \quad \frac{\partial^{2} M_{x}}{\partial x^{2}} + 2 \frac{\partial^{2} M_{xy}}{\partial x \partial y} + \frac{\partial^{2} M_{y}}{\partial y^{2}} + f_{e} + q = 0$$
(18)

$$\delta \ \theta: \ -k_1 S_x - k_2 S_y - k_1 \frac{\partial^2 S_{xy}}{\partial x \partial y} A' - k_2 \frac{\partial^2 S_{xy}}{\partial x \partial y} B' + k_1 A' \frac{\partial R_{xz}}{\partial x} + k_2 B' \frac{\partial R_{yz}}{\partial y} = 0$$

By substituting Eq. (16) into Eq. (19), the governing equations can be expressed in terms of generalized displacements as

$$A_{11}d_{11}u_0 + A_{66}d_{22}u_0 + (A_{12} + A_{66})d_{12}v_0 - B_{11}d_{111}w_0 - (B_{12} + 2B_{66})d_{122}w_0 + (B_{66}^s(k_1A' + k_2B') + B_{12}^sk_2B')d_{122}\theta + B_{11}^sk_1A'd_{111}\theta = F_1$$
(19a)

$$A_{22} d_{22} v_0 + A_{66} d_{11} v_0 + (A_{12} + A_{66}) d_{12} u_0 - B_{22} d_{222} w_0 - (B_{12} + 2B_{66}) d_{112} w_0 + (B_{66}^s (k_1 A' + k_2 B') + B_{12}^s k_1 A') d_{112} \theta + B_{22}^s k_2 B' d_{222} \theta = F_2$$
(19b)

$$B_{11}d_{111}u_0 + (B_{12} + 2B_{66})d_{122}u_0 + (B_{12} + 2B_{66})d_{112}v_0 + B_{22}d_{222}v_0 - D_{11}d_{1111}w_0 - 2(D_{12} + 2D_{66})d_{1122}w_0$$

$$-D_{22}d_{2222}w_0 + D_{11}^sk_1A'd_{1111}\theta$$

$$+ ((D_{12}^s + 2D_{66}^s)(k_1A' + k_2B'))d_{1122}\theta + D_{22}^sk_2B'd_{2222}\theta + f_e = F_3$$

(19c)

$$-k_{1}A^{s}B_{11}^{s}d_{111}u_{0} - \left(B_{12}^{s}k_{2}B^{s} + B_{66}^{s}\left(k_{1}A^{s} + k_{2}B^{s}\right)\right)d_{122}u_{0} - \left(B_{12}^{s}k_{1}A^{s} + B_{66}^{s}\left(k_{1}A^{s} + k_{2}B^{s}\right)\right)d_{112}v_{0} - B_{22}^{s}k_{2}B^{s}d_{222}v_{0} + D_{11}^{s}k_{1}A^{s}d_{1111}w_{0} + \left(\left(D_{12}^{s} + 2D_{66}^{s}\right)\left(k_{1}A^{s} + k_{2}B^{s}\right)\right)d_{1122}w_{0} + D_{22}^{s}k_{2}B^{s}d_{2222}w_{0} - H_{11}^{s}\left(k_{1}A^{s}\right)^{2}d_{1111}\theta + H_{11}^{s}k_{1}A^{s}d_{1111}w_{0} + \left(D_{12}^{s}k_{1}A^{s}A^{s}B^{s} + \left(k_{1}A^{s} + k_{2}B^{s}\right)^{2}B_{66}^{s}\right)d_{1122}w_{0} + A_{52}^{s}k_{2}B^{s}d_{212}d_{1111}\theta + H_{11}^{s}k_{1}A^{s}d_{111}d_{1111}\theta + H_{11}^{s}k_{1}A^{s}d_{11}d_{1111}d_$$

Where d_{ij} , d_{ijl} and d_{ijlm} are the following differential operators

$$d_{ij} = \frac{\partial^2}{\partial x_i \partial x_j}, \quad d_{ijl} = \frac{\partial^3}{\partial x_i \partial x_j \partial x_l},$$

$$d_{ijlm} = \frac{\partial^4}{\partial x_i \partial x_j \partial x_l \partial x_m}, \quad d_i = \frac{\partial}{\partial x_i},$$

(i, j, l, m = 1, 2).
(20)

where $\{F\} = \{F_1, F_2, F_3, F_4\}^t$ is generalized force vector.

The components of the generalized force vector $\{F\}$ are given by

$$F_1 = \frac{\partial N_x^T}{\partial x} + \frac{\partial N_x^C}{\partial x}, \quad F_2 = \frac{\partial N_y^T}{\partial y} + \frac{\partial N_y^C}{\partial y}, \quad (21)$$

$$F_{3} = -q + \frac{\partial^{2} \left(M_{x}^{T} + M_{x}^{C} \right)}{\partial x^{2}} + \frac{\partial^{2} \left(M_{y}^{T} + M_{y}^{C} \right)}{\partial y^{2}}$$
$$F_{4} = \frac{\partial^{2} \left(S_{x}^{T} + S_{x}^{C} \right)}{\partial x^{2}} + \frac{\partial^{2} \left(S_{y}^{T} + S_{y}^{C} \right)}{\partial y^{2}}$$

3. Analytical solution for simply-supported FG plates

Rectangular plates are generally classified in accordance with the type of support employed. We are here concerned with the exact solution of Eqs. (20) for a simply supported FG plate. To solve this problem, Navier supposed that the transverse mechanical, temperature and moisture loads, q, T_i and C_i in the form of a in the double Fourier series as

$$\begin{cases} q \\ T_i \\ C_i \end{cases} = \begin{cases} q_0 \\ t_i \\ c_i \end{cases} \sin(\lambda x) \sin(\mu y), \quad (i = 1, 2, 3) \qquad (22)$$

where q_0 , t_i and c_i are constants and T_i and C_i are defined in Eq. (11). with

$$\lambda = m\pi/a \text{ and } \mu = n\pi/b$$
 (23)

Following the Navier method, we consider the following solution form for u_0 , v_0 , w_0 and θ that satisfies the boundary conditions

$$\begin{cases} u_{0} \\ v_{0} \\ w_{0} \\ \theta \end{cases} = \begin{cases} U \cos(\lambda x) \sin(\mu y) \\ V \sin(\lambda x) \cos(\mu y) \\ W \sin(\lambda x) \sin(\mu y) \\ X \sin(\lambda x) \sin(\mu y) \end{cases}$$
(24)

where U, V, W, and X are arbitrary parameters to be determined subjected to the condition that the solution in Eq. (25) satisfies governing Eq. (20). Substituting Eq. (25) intoEqs. (20), one obtains

$$\begin{bmatrix} S_{11} & S_{12} & S_{13} & S_{14} \\ S_{12} & S_{22} & S_{23} & S_{24} \\ S_{13} & S_{23} & S_{33} & S_{34} \\ S_{14} & S_{24} & S_{34} & S_{44} \end{bmatrix} \begin{bmatrix} U \\ V \\ W \\ X \end{bmatrix} = \begin{bmatrix} F_1 \\ F_2 \\ F_3 \\ F_4 \end{bmatrix}$$
(25)

Where

$$S_{11} = -A_{11}\lambda^{2} - A_{66}\mu^{2}, \quad S_{12} = -\lambda\mu \left(A_{12} + A_{66}\right),$$

$$S_{13} = \lambda \left(B_{11}\lambda^{2} + (B_{12} + 2B_{66})\mu^{2}\right), \quad (26)$$

$$S_{14} = -\lambda \left((k_{2}B'B_{12}^{s} + (k_{1}A' + k_{2}B')B_{66}^{s})\mu^{2} + k_{1}A'B_{11}^{s}\lambda^{2}\right)$$

$$S_{22} = -A_{66}\lambda^{2} - A_{22}\mu^{2},$$

$$S_{23} = \mu \left(B_{22}\mu^{2} + (B_{12} + 2B_{66})\lambda^{2}\right),$$

$$\begin{split} S_{24} &= -\mu \Big(\big(k_1 A' B_{12}^s + \big(k_1 A' + k_2 B' \big) B_{66}^s \big) \lambda^2 + k_2 B' B_{22}^s \mu^2 \Big), \\ S_{33} &= \lambda^2 \mu^2 \Big(D_{11} k_1 B' \lambda^2 + (D_{12} + 2D_{66}) (k_1 A' + k_2 B') + D_{22} k_2 A' \mu^2 - K_w (A' B') + K_{ss} B' + K_{sy} A' \Big) \\ S_{34} &= k_1 A' D_{11}^s \lambda^4 + ((D_{12}^s + 2D_{66}^s) (k_1 A' + k_2 B')) \lambda^2 \mu^2 + k_2 B' D_{22}^s \mu^4 \\ S_{44} &= -(k_1 A')^2 H_{11}^s \lambda^4 - (2k_1 k_2 A' B' H_{12}^s + (k_1 A' + k_2 B')^2 H_{66}^s) \lambda^2 \mu^2 - (k_2 B')^2 H_{22}^s \mu^4 \\ &- (k_1 A')^2 A_{44}^s \lambda^2 - (k_2 B')^2 A_{55}^s \mu^2 \end{split}$$

The components of the generalized force vector $\{F\} = \{F_1, F_2, F_3, F_4\}^t$ are given by

$$F_{1} = \lambda \left(A^{T} t_{1} + B^{T} t_{2} + {}^{a} B^{T} t_{3} + A^{C} c_{1} + B^{C} c_{2} + {}^{a} B^{C} c_{3} \right)$$
(27a)

$$F_2 = \mu \left(A^T t_1 + B^T t_2 + {}^a B^T t_3 + A^C c_1 + B^C c_2 + {}^a B^C c_3 \right)$$
(27b)

$$F_{3} = -q_{0} - h\left(\lambda^{2} + \mu^{2}\right)\left(B^{T}t_{1} + D^{T}t_{2} + {}^{a}D^{T}t_{3} + B^{C}c_{1} + D^{C}c_{2} + {}^{a}D^{C}c_{3}\right)(27c)$$

$$F_{4} = -h(\lambda^{2} + \mu^{2})({}^{s}B^{T}t_{1} + {}^{s}D^{T}t_{2} + {}^{s}F^{T}t_{3} + {}^{s}B^{C}c_{1} + {}^{s}D^{C}c_{2} + {}^{s}F^{C}c_{3})$$
(27d)
Where

$$\left[A^{T}, B^{T}, D^{T}\right] = \int_{-h/2}^{h/2} \frac{E(z)}{1-\nu} \alpha(z) \left[1, \overline{z}, \overline{z}\right] dz \qquad (28a)$$

$$\left[A^{C}, B^{C}, D^{C}\right] = \int_{-h/2}^{h/2} \frac{E(z)}{1 - \nu} \beta(z) \left[1, \overline{z}, \overline{z}\right] dz \quad (28b)$$

$$\begin{bmatrix} {}^{a}B^{T}, {}^{a}D^{T} \end{bmatrix} = \int_{-h/2}^{h/2} \frac{E(z)}{1-\nu} \alpha(z) \overline{\Psi}(z) \begin{bmatrix} 1, \overline{z} \end{bmatrix} dz \qquad (28c)$$

$$\begin{bmatrix} {}^{a}B^{C}, {}^{a}D^{C} \end{bmatrix} = \int_{-h/2}^{h/2} \frac{E(z)}{1-\nu} \beta(z)\overline{\Psi}(z) \begin{bmatrix} 1, \overline{z} \end{bmatrix} dz \quad (28d)$$

$$\begin{bmatrix} {}^{s}B^{T}, {}^{s}D^{T}, {}^{s}F^{T} \end{bmatrix} = \int_{-h/2}^{h/2} \frac{E(z)}{1-\nu} \alpha(z)\overline{f}(z) \Big[1, \overline{z}, \overline{\Psi}(z)\Big] dz \quad (28e)$$

$$\begin{bmatrix} {}^{s}B^{C}, {}^{s}D^{C}, {}^{s}F^{C} \end{bmatrix} = \int_{-h/2}^{h/2} \frac{E(z)}{1-\nu} \beta(z)\overline{f}(z) \Big[1, \overline{z}, \overline{\Psi}(z)\Big] dz \quad (28f)$$

In which $\overline{z} = z/h$ and $\overline{f}(z) = f(z)/h$.

4. Analytical solution for simply-supported FG plates

In this section, numerical examples are proposed and discussed for checking the accuracy of the developed new theory in investigating the hygro-thermo-mechanical bending behaviours of plates. Comparisons are carried out with available solutions in literature. In order to verify the accuracy of the present analysis, some numerical examples are solved. The obtained results are compared with those of other shear deformation theories available in literature such as Laoufi *et al.* (2016), third shear deformation theory (TSDT) and sinusoidal shear deformation theory (SSDT) of Zenkour (2006). The material properties of the FGM are reported in Table 1.

In this work, the numerical results for the mechanical loading is shown in the dimensionless quantities defined as follows

$$\overline{w} = \frac{10h^{3}E_{c}}{a^{4}q_{0}} w\left(\frac{a}{2}, \frac{b}{2}\right), \overline{\sigma}_{x} = \frac{h}{aq_{0}} \sigma_{x}\left(\frac{a}{2}, \frac{b}{2}, \frac{h}{2}\right),$$

$$\overline{\tau}_{xy} = \frac{h}{aq_{0}} \tau_{xy}\left(0, 0, \frac{-h}{3}\right), \overline{\tau}_{xz} = \frac{h}{aq_{0}} \tau_{xz}\left(0, \frac{b}{2}, 0\right) (29)$$

$$k_{w} = \frac{K_{w}a^{4}}{D}, \quad k_{s} = \frac{K_{s}a^{2}}{D}, \quad D = \frac{Eh^{3}}{12(1-v?)}$$

Tables 2 and 3 list the non-dimensional transverse and stresses of a FG square plate with side-to-thickness ratio a/h = 10. It can be shown from these tables that results predicted by the proposed HSDT are in an excellent agreement with those obtained using SSDT (Zenkour 2006), of Laoufi *et al.* (2016) and TSDT (Reddy 2000).

In the second examples, a comparison study is presented and discussed for checking the accuracy of the proposed theory in investigating the bending behavior of FG plates under sinusoidal load and a temperature field T(x, y, z) as well as moisture concentration C(x, y, z). The material characteristics are considered in the investigation at the reference temperature $T_0 = 25$ °C (room temperature) and moisture concentration $C_0 = 0\%$ as shown in Table 4.

In the following, the non-dimensional quantities are defined as

$$\overline{w} = \frac{10^2 D}{a^4 q_0} w \left(\frac{a}{2}, \frac{b}{2}\right),$$

$$\overline{\sigma}_x = \frac{1}{10^2 q_0} \sigma_x \left(\frac{a}{2}, \frac{b}{2}, \frac{h}{2}\right),$$
(30)

$$\bar{\tau}_{xy} = \frac{1}{10q_0} \tau_{xy} \left(0, 0, \frac{-h}{3} \right), \quad \bar{\tau}_{xz} = -\frac{1}{10q_0} \tau_{xz} \left(0, \frac{b}{2}, 0 \right),$$
$$k_w = \frac{K_w a^4}{D} \quad , \quad k_s = \frac{K_s a^2}{D} \quad , \quad D = \frac{Eh^3}{12(1-v?)}$$

Table 1 Material properties used in the FG plate

Properties	Metal, Ti-6Al-4V	Ceramic Zerconia, ZrO ₂
E (GPa)	70	380
V	0.3	0.3

- W 3	10				
p	Theory	\overline{w}	$\overline{\sigma}_{x}$	$-\frac{1}{\tau_{xy}}$	$\overline{ au}_{xz}$
Ceramic	Present	0.29597	1.99322	0.70682	0.23101
	TSDT(Reddy 2000)	0.294	1.98915	0.70557	0.23778
	Zankour (2006)	0.296	1.9955	0.7065	0.2462
	Laoufi et al. (2015)	0.29604	2.02724	0.70678	0.23215
	Present	0.588799	3.08315	0.611186	0.23101
	TSDT(Reddy 2000)	0.58895	3.08501	0.61111	0.23817
1	Zankour (2006)	0.5889	3.087	0.611	0.2462
	Laoufi et al. (2015)	0.58893	3.12645	0.61118	0.23215
	Present	0.75696	3.60419	0.54433	0.21066
2	TSDT(Reddy 2000)	0.75747	3.60664	0.54434	0.22568
2	Zankour (2006)	0.7573	3.6094	0.5441	0.2265
	Laoufi et al. (2015)	0.75718	3.63002	0.54432	0.2119
	Present	0.83687	3.86769	0.55281	0.19413
3	Zankour (2006)	0.8377	3.8742	0.5525	0.2107
	Laoufi et al. (2015)	0.83717	3.86808	0.55278	0.19543
	Present	0.88065	4.06191	0.56713	0.18592
4	Zankour (2006)	0.8819	4.0693	0.5667	0.2029
	Laoufi et al. (2015)	0.88102	4.03991	0.5671	0.18728
	Present	0.91037	4.24082	0.57586	0.18434
5	TSDT(Reddy 2000)	0.90951	4.24293	0.57368	0.21609
5	Zankour (2006)	0.9118	4.2488	0.5755	0.2017
	Laoufi et al. (2015)	0.9108	4.20242	0.57585	0.18575
	Present	0.934029	4.41601	0.580769	0.186597
6	Zankour (2006)	0.9356	4.4244	0.5803	0.2041
	Laoufi et al. (2015)	0.93452	4.36696	0.58075	0.18807
	Present	0.954678	4.58872	0.583804	0.190548
7	Zankour (2006)	0.9562	4.5971	0.5834	0.2081
	Laoufi et al. (2015)	0.95521	4.53333	0.58378	0.19206
	Present	0.973533	4.7577	0.586039	0.194901
8	Zankour (2006)	0.975	4.7661	0.5856	0.2124
	Laoufi et al. (2015)	0.97408	4.69925	0.58602	0.19645
	Present	0.99115	4.92201	0.58796	0.19902
9	Zankour (2006)	0.9925	4.9303	0.5875	0.2164
	Laoufi et al. (2015)	0.9917	4.86294	0.58794	0.20059
	Present	1.00775	5.08083	0.58981	0.20265
10	Zankour (2006)	1.0089	5.089	0.5894	0.2198
	Laoufi et al. (2015)	1.00832	5.02282	0.58977	0.20424
	Present	1.60667	1.99322	0.70682	0.23101
Mat-1	TSDT(Reddy, 2000)	1.59724	1.98915	0.70557	0.23778
Wietai	Zankour (2006)	1.607	1.9955	0.7065	0.2462
	Laoufi <i>et al.</i> (2015)	1.57882	1.89911	0.70234	0.24229

Table 2 Effects of volume fraction exponent on the dimensionless displacements and stresses of a FG square plate $(a/h=10, k_w = k_s = 0, q_0 = 1, T = C = 0)$

Table 3 Effects of volume fraction exponent and elastic foundation parameters on the dimensionless displacements and stresses of a FGM rectangular plate (a/h = 10, b = 3a, $q_0 = 100$, $t_1 = t_3 = 0$, $t_2 = 10$, $c_1 = c_3 = 0$, $c_2 = 100$)

р	<i>k</i> _w	k_s	Theory	\overline{w}	$\overline{\sigma}_x$	$\overline{\tau}_{xy}$	$\overline{\tau}_{xz}$
			Present	0.29597	1.99322	0.70682	0.23101
	0	0	Present	1.80647	0.47165	1.55994	-0.408538
	0	0	Laoufi et al. (2015)	1.80709	0.46227	1.5599	-0.41798
			TSDT	1.80712	0.47187	1.55982	-0.42955
			SSDT	1.80708	0.472	1.55975	-0.44327
	100	0	Present	0.972134	-0.027288	0.852158	-0.011384
	100	0	Laoufi et al. (2015)	0.97215	-0.02729	0.85215	-0.01164
Commin			TSDT	0.97216	-0.0274	0.85211	-0.01197
Ceramic			Present	0.188661	-0.495817	0.187525	0.361559
	0	100	Laoufi et al. (2015)	0.1886	-0.48723	0.18797	0.36968
	0	100	TSDT	0.18861	-0.4957	0.18806	0.3799
			SSDT	0.18861	-0.49588	0.1881	0.39206
			Present	0.173143	-0.505098	0.17436	0.368946
	100	100	Laoufi et al. (2015)	0.17309	-0.49633	0.17482	0.37723
	100	100	TSDT	0.17309	-0.50498	0.1749	0.38766
			SSDT	0.17309	-0.50716	0.17495	0.40007
			Present	0.18416	-0.519873	0.182428	0.422388
0.5	100	100	Laoufi et al. (2015)	0.18409	-0.50982	0.18292	0.43981
0.5	100	100	TSDT	0.1841	-0.51975	0.18299	0.44334
			SSDT	0.18411	-0.51999	0.18301	0.45728
			Present	0.185098	-0.514645	0.155729	0.42383
1	100	100	Laoufi et al. (2015)	0.18503	-0.50181	0.15622	0.4334
1	100	100	TSDT	0.18504	-0.5145	0.15631	0.44545
			SSDT	0.18504	-0.51476	0.15635	0.45984
			Present	0.185664	-0.503584	0.133831	0.415814
2	100	100	Laoufi et al. (2015)	0.18559	-0.48892	0.13438	0.42571
2	100		TSDT	0.1856	-0.50336	0.13451	0.43831
			SSDT	0.1856	-0.50363	0.13461	0.45337
			Present	0.187038	-0.489732	0.123353	0.414022
F	100	100	Laoufi et al. (2015)	0.18696	-0.47268	0.1234	0.42443
5	100	100	TSDT	0.19696	-0.4894	0.12417	0.43754
			SSDT	0.18694	-0.48967	0.12431	0.45322
			Present	0.188464	-0.594955	0.120202	0.437745
M. (1	100	100	Laoufi et al. (2015)	0.18842	-0.4228	0.12011	0.4468
Metal	100	100	TSDT	0.1884	-0.43095	0.12087	0.45993
			SSDT	0.1884	-0.43117	0.12092	0.47465

Table 4 Material properties used in the FG plate

Properties	Metal (Ti-6Al-4V)	Ceramic Zerconia,(ZrO ₂)
E (GPa)	66.2	117
V	1/3	1/3
$lpha \left(10^{-6} / C^0 ight)$	10.3	7.11
$etaig(10^{-6}$ / $K^0ig)$	0.33	0

			r (<i>m</i> , <i>r</i> = 0, 0		-,	-,,	
р	k_w	k_p	Theory	\overline{w}	$\overline{\sigma}_x$	$\overline{\tau}_{xy}$	$\overline{\tau}_{xz}$
			Present	2.54014	0.525163	2.20384	-0.404199
	0	0	Laoufi et al. (2015)	2.54076	0.51588	2.20381	-0.41354
	0	U	TSDT	2.54076	0.52522	2.20374	-0.42454
			SSDT	2.54068	0.52552	2.20366	-0.43753
			Present	1.36695	-0.176414	1.20861	0.154253
	100	Δ	Laoufi et al. (2015)	1.36683	-0.17281	1.20872	0.15777
	100	0	TSDT	1.36682	-0.17643	1.20877	0.16257
Coromic			SSDT	1.3668	-0.17649	1.20881	0.16834
Ceramic			Present	0.265285	-0.835229	0.274052	0.678662
	0	100	Laoufi <i>et al.</i> (2015)	0.26517	-0.8191	0.27488	0.6939
	U	100	TSDT	0.26518	-0.835	0.27507	0.71354
			SSDT	0.26518	-0.83531	0.27519	0.73692
			Present	0.243462	-0.848278	0.25554	0.689049
	100	100	Laoufi et al. (2015)	0.24336	-0.8319	0.25639	0.70452
	100	100	TSDT	0.24336	-0.84804	0.25658	0.72442
			SSDT	0.24337	-0.84835	0.2567	0.74816
			Present	0.262064	-0.872634	0.279282	0.780308
0.5	100	100	Laoufi <i>et al.</i> (2015)	0.26194	-0.86236	0.28023	0.75161
0.5	100	100	TSDT	0.26195	-0.87239	0.28034	0.81947
			SSDT	0.26196	-0.87282	0.28041	0.84586
			Present	0.263417	-0.862338	0.236503	0.781178
1	100	100	Laoufi et al. (2015)	0.2633	-0.83867	0.23741	0.79871
1 100	100	00 100	TSDT	0.2633	-0.86205	0.23762	0.82148
			SSDT	0.2633	-0.86252	0.23772	0.84866
			Present	0.264093	-0.841791	0.200059	0.764692
2	100	100	Laoufi et al. (2015)	0.26396	-0.81483	0.20107	0.78289
2	100	100	TSDT	0.26396	-0.84138	0.20133	0.80652
			SSDT	0.26395	-0.84185	0.20154	0.83484
			Present	0.266174	-0.818065	0.183053	0.759403
5	100	100	Laoufi et al. (2015)	0.26603	-0.78678	0.18423	0.77849
5	100	100	TSDT	0.26601	-0.81745	0.18459	0.80297
			SSDT	0.266	-0.81792	0.18486	0.8323
			Present	0.267874	-0.985018	0.181616	0.799027
Mar 1	100	100	Laoufi et al. (2015)	0.26729	-0.77772	0.18167	0.79866
Metal	100	100	TSDT	0.26774	-0.71656	0.18286	0.84003
			SSDT	0.26775	-0.71694	0.18298	0.86748

Table 5 Effects of volume fraction exponent and elastic foundation parameters on the dimensionless displacements and stresses of a FG rectangular plate (a/h = 10, b = 3a, q0 = 100, t1 = 0, t2 = t3 = 10, c1 = 0, c2 = c3 = 100)

The computed results using the present HSDT are compared with those reported by other higher-order shear deformation theories as is indicated in Tables 5 and 6.

An excellent agreement between the presented results is confirmed thought this study. These examples show also the influences of the gradient index k and elastic foundation on the non-dimensional deflection and stresses of FG plate, It is important to see that the stresses for a fully ceramic plate are not the same as that for a fully metal plate with elastic foundations. This is because the plate here is affected with the introduction of the temperature field. The number of primary unknowns in this model is even less than that of other HSDTs.

It can be concluded that the present theory is not only accurate but also comparatively simple and quite elegant in predicting the hygro-thermo-mechanical bending behavior of FG plates resting on elastic foundations.

$p k k_{\pi} \frac{a/h}{c}$	a/h				
$\frac{P}{Kw}$ Kp 5	10	20	50		
0 0 4.04	97 1.206	0.494059	0.294638		
100 0 3.07'	0.948305	0.391973	0.23435		
0 100 0.559	0.189501	0.0804538	0.0484757		
100 100 0.536	0.18174	0.0771806	0.0465072		
0 0 5.31	87 1.58389	0.648419	0.386365		
1 100 0 3.765	92 1.1683	0.483434	0.288933		
0 100 0.581	0.197448	0.0838112	0.0504632		
100 100 0.556	0.189065	0.0802706	0.0483342		
0 0 5.58	68 1.66861	0.685656	0.410235		
2 100 0 3.87	78 1.20963	0.502976	0.301946		
² 0 100 0.573	0.196544	0.08393	0.0507766		
100 100 0.548	0.188137	0.0803575	0.0486187		
0 0 5.72	89 1.71031	0.703206	0.420981		
2 100 0 3.92	09 1.23013	0.512163	0.307702		
³ 0 100 0.570	0.196474	0.0840838	0.0509238		
100 100 0.545	0.188043	0.0804938	0.0487525		
0 0 5.82	42 1.73958	0.715375	0.428339		
100 0 3.96	1.24461	0.518504	0.311605		
4 0 100 0.568	694 0.196565	0.0842131	0.0510253		
100 100 0.543	0.188111	0.0806106	0.0488454		
0 0 5.89	1.76305	0.725206	0.434346		
5 100 0 3.995	1.25615	0.523574	0.314763		
0 100 0.567	978 0.567978	0.0843094	0.0511038		
100 100 0.543	0.188178	0.0806969	0.0489171		
0 0 6.820	03 2.04726	0.85215	0.517368		
100 0 4.37	1.38303	0.583543	0.355662		
0 100 0.567	0.195342	0.0844888	0.051868		
100 100 0.541	0.186784	0.0808012	0.0496067		

Table 6 Effect of side to thickness ratio and elastic foundation parameters on the dimensionless deflection of an FG square plate ($q_0=100$, t1=0, t2=t3=10, c1=0, c2=c3=100)

Figs. 2 and 3 present the variation of the nondimensional center deflection \overline{w} versus the side-tothickness thickness a/h and plate aspect ratios a/brespectively. It can be seen that the deflection is maximum for the fully metallic plate and becomes minimum for the ceramic plate irrespective of the values of temperature, moisture, and elastic foundation coefficient.

It is evident that for the FG plates the values of the deflections are between those of fully metallic and fully ceramic plates. In addition, the deflection is increased with the absence of the elastic foundation and the influence of moisture load may be less than that of the temperature one.

Figs. 4 to 6 present the through-the-thickness variations of the non-dimensional axial stress $\overline{\sigma}_x$, longitudinal shear stress $\overline{\tau}_{xy}$ and transversal shear stress $\overline{\tau}_{xz}$ in the rectangular FG plates on elastic foundations for different values of moistures and temperatures, respectively. In this figures, it is considered, that $q_0 = 100$ GPa, a/h = 10, b/a = 3, p = 2. As is shown in Figs. 4 and 5, the maximum compressive stresses is found at a point on the top surface and the maximum tensile stresses occur, of course, at a point on the lower surface of the FG plates. It can be observed that the shear stresses increase with the increase of both thermal and moisture load, and the maximum value is found at a point above the mid-plane of the FG plate.



Continued-



Fig. 2 Non-dimensional center deflection \overline{w} versus plate aspect ratio b/a for FG plate resting on Winkler Pasternak foundations (a/h = 10)



Continued-



Fig. 3 Non-dimensional center deflection \overline{w} versus side-to-thickness ratio a/h for FG plate on Winkler-Pasternak foundations (b/a=3)



Fig. 4 Variation of non-dimensional axial stress $\overline{\sigma}_x$ through the thickness of a rectangu- lar FG plate on elastic foundations for different values of moistures and temperatures (a/h = 10, b/a = 3, p = 2)



Fig. 5 Variation of non-dimensional in-plane shear stress τ_{xy} through the thickness of a rectangular FG plate on elastic foundations for different values of moistures and temperatures $(a/h = 10, b/a = 3, p = 2) \cdot (a/h = 10, b/a = 3, p = 2)$



Fig. 6 Variation of non-dimensional transversal shear stress τ_{xz} through the thickness of a rectangular FG plate on elastic foundations for different values of moistures and temperatures (a/h = 10, b/a = 3, p = 2)

Figs. 7 to 10 demonstrate the relation between the nondimensional center deflection \overline{w} , the axial stress $\overline{\sigma}_x$ the longitudinal shear stress $\overline{\tau}_{xy}$, the transversal shear stress $\overline{\tau}_{xz}$ and the plate aspect ratio b/a for three different thermal and moisture loading. It's can be seen from these that the three considered cases of temperature and moisture give almost the same values of the non-dimensional center deflection \overline{w} , the axial stress $\overline{\sigma}_x$, the longitudinal shear stress $\overline{\tau}_{xy}$ and the transversal shear stress $\overline{\tau}_{xz}$.

Furthermore, the sinusoidal variation provides medium value in deflection and stresses case. The cubic variation gives higher values relatively than those of the other two distributions.



Fig. 7 Dimensionless center deflection w versus side-to-thickness ratio a/h for FG plate for different distributions of $\overline{\Psi}(z)$ (b/a=3, p=2)



Fig. 8 Dimensionless axial stress $\overline{\sigma}_x$ versus side-to-thickness ratio a/h for FG plate for different distributions of $\overline{\Psi}(z)$ (b/a = 3, p = 2)

The variations of the non-dimensional center deflection \overline{w} , the in-plane shear stress $\overline{\tau}_{xy}$, the transversal shear stress $\overline{\tau}_{xz}$ versus the plate aspect ratio b/a for different values of E_m/E_c with or without hygrothermal influences are presented in Figs. 11 to 18. The deflection, the axial and the transversal shear stress increase with increasing the plate aspect ratio b/a, and this quantities take maximum values for $E_m/E_c = 0.03$ and minimum ones for $E_m/E_c = 1$ as demonstrated in Figs. 11, 12, 14 to 16 and 18.

It can be seen that when hygrothermal effects are not considered, the in-plane shear stress increases with increasing the aspect ratio for b/a less than 1.75. However, when b/a is greater than 1.75 the in-plane shear stress decreases upon increasing the aspect ratio as shown in Fig. 13. In the case where the hygrothermal effects are considered, it can be observed that the in-plane shear stress increases with increasing the aspect ratio for b/a less than 1.0.



Fig. 9 Dimensionless in-plane shear stress $\overline{\tau}_{xy}$ versus side-to-thickness ratio a/h for FG plate for different distributions of $\overline{\Psi}(z) (b/a = 3, p = 2)$



Fig. 10 Dimensionless transversal shear stress $\overline{\tau}_{xz}$ versus side-to-thickness ratio a/h for FG plate for different distributions of $\overline{\Psi}(z) (b/a = 3, p = 2)$.



Fig. 11 Dimensionless center deflection \overline{w} versus plate aspect ratio b/a for FG plate for different E_m/E_c ratios (a/h=10, p=2)



Fig 12 Dimensionless axial stress $\overline{\sigma}_x$ versus plate aspect ratio b/a for FG plate for different E_m/E_c ratios (a/h=10, p=2)



Fig. 13 Dimensionless longitudinal tangential stress $\overline{\tau}_{xy}$ versus plate aspect ratio b/a for FG plate for different E_m/E_c ratios (a/h=10, p=2)



Fig. 14 Dimensionless transversal shear stress $\overline{\tau}_{xz}$ versus plate aspect ratio b/a for FG plate for different E_m/E_c ratios (a/h=10, p=2)



Fig. 15 Dimensionless center deflection \overline{w} versus plate aspect ratio b/a for FG plate for different E_m/E_c ratios (a/h=10, p=2)



Fig. 16 Dimensionless axial stress $\overline{\sigma}_x$ versus plate aspect ratio b/a for FG plate for different E_m/E_c ratios (a/h=10, p=2)



Fig. 17 Dimensionless longitudinal tangential stress $\overline{\tau}_{xy}$ versus plate aspect ratio b/a for FG plate for different E_m/E_c ratios (a/h=10, p=2)



Fig. 18 Dimensionless transversal shear stress $\overline{\tau}_{xz}$ versus plate aspect ratio b/a for FG plate for different E_m/E_c ratios (a/h=10, p=2)

However, when b/a is greater than 1.0 the in-plane shear stress is reduced with increasing the aspect ratio. For the two cases with or without considering the hygrothermal effects, the in-plane shear stress is maximum for $E_m/E_c = 1$ and minimum for $E_m/E_c = 0.03$ as shown in Figs. 13 and 17.

5. Conclusions

This article presents the hygro-thermo-mechanical analysis for FG plates using a novel and original HSDT with 4 unknowns. The governing equations are determined through the virtual work's principle. These equations are solved via Navier's method. The results were compared with the solutions of several theories. Illustrating examples are presented to demonstrate the effects of moisture concentration parameter on thermomechanical behavior of the FG plates. The good comparisons among the proposed theoretical model, and the other analytical solutions available in the literature, demonstrate that the presented solution can accurately predict the hygro-thermo-mechanical behavior of the FG plate and be employed in the design of the solar plate.

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