

# Vibration of angle-ply laminated composite circular and annular plates

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**Abstract.** In the present paper, free vibration analysis of angle-ply laminated composite annular and circular plates is performed by numerical methods. First-order shear deformation plate theory is used for kinematic relations. The related governing equations of motion are discretized via differential quadrature and discrete singular convolution methods. Frequency values are obtained for different lamina scheme, thickness-to-radius ratio, and mode numbers. The advantages and accuracy of these two methods are also tested in detail.

**Keywords:** laminated composites; annular plates; circular plate; discrete singular convolution

## 1. Introduction

Circular and annular plates are widely used as an essential structural component in many important engineering applications like aerospace, marine, automobile, rocket, components of pressure vessels, and petro-chemical industries. For different purposes and usage aim, they are made of different composite materials. Anisotropic, laminated, and functionally graded composites are well known material types in application areas. During the 50 years of engineering applications, material properties and new materials have also been taken into consideration for modeling. It is known that, laminated composite materials have been widely chosen in many engineering applications. High strength-to-weight ratio is the best for design. In the literature, some plate and shell theories have been used during the past years Qatu (2004), Soedel (2004), Reddy (2003), Civalek (2004), Bisadi *et al.* (2012), Akgoz and Civalek (2012, 2017). At first, mathematical model is derived via any plate theories. Secondly, it is required to solve these differential equations for mechanical model. Also, there are large numbers of numerical methods for solution of the governing equations (Leissa 1993), Tornabene *et al.* (2014), Civalek (1998). Plate and shell components are generally subjected to some dynamic loads or free motion. By this time, free vibration analysis of annular and circular plates has received great attention by design engineers. Su *et al.* (2014, 2015) applied numerical technique for vibration analysis of laminated sector and annular plates. Stability and vibration analysis of composite sector plates have been made by Sharma *et al.* (2005). Three-dimensional frequency response of thick laminated annular sector plates has been investigated by Malekzadeh

(2009) via differential quadrature method. Tornabene *et al.* (2013, 2014, 2016) gave detailed formulation and solution of curved plates and shells. Strong form finite element method (FEM) formulation for plates has also been derived by Fantuzzi and Tornabene (2014). Civalek (2006a, b, 2007, 2008a, b, 2013a, b, 2017) presented discrete singular convolution (DSC) solution for vibration problems of shells and plates. Detailed unified formulation and solution for beams, plates, and shells have given by Wang *et al.* (2016a, b), Avcar (2015, 2019). Free vibration of functionally graded moderately thick annular sector plates has been made by Saidi *et al.* (2011) and Pang *et al.* (2017). Viswanathan *et al.* (2009) discussed free vibration of layered annular circular plate of variable thickness using spline function approximation. Kahare and Mittal (2016, 2017) presented some solutions of circular and annular plates via FEM. Arefi *et al.* (2018) have been supplied numerical solution for carbon nanotube reinforced (CNTR) cylindrical pressure under thermals effect. Effect of thermal gradients on stress/strain distributions in a thin circular symmetric plate was analyzed by Aleksandrova (2016). Hyperbolic shear deformation theory for bending, buckling, and free vibration of sandwich plates made of functionally graded materials (FGM) was adopted by Abdelaziz *et al.* (2017). Hamzehkolaei *et al.* (2011) presented a numerical solution for thermal effect on axisymmetric bending of functionally graded circular and annular plates using differential quadrature method (DQM). Thermal stresses and deflections of functionally graded sandwich plates using a new refined hyperbolic shear deformation theory have been investigated by Bouchafa *et al.* (2015). Boudierba *et al.* (2016) analyzed the thermal stability of functionally graded sandwich plates using a simple shear deformation theory. Benchohra *et al.* (2018) also gave a detailed solution for functionally graded plates via new quasi-3D sinusoidal shear deformation theory. Natural vibration characteristics of a clamped circular plate in contact with fluid have been

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solved by Jung *et al.* (2005) and Azimi (1988). Tahouneh (2014) presented some numerical solution for free vibration analysis of bi-directional functionally graded annular plates resting on elastic foundations. Yousefzadeh *et al.* (2018) examined the dynamic response of functionally graded annular/circular plate in contact with bounded fluid under harmonic load. Quasi-3D static analysis of two-directional functionally graded circular plates was solved by Wu and Yu (2018). Also, state space meshless method for the 3D analysis of FGM axisymmetric circular plates has been applied by Wu and Yu (2016). Civalek and Demir (2011, 2016) and Demir and Civalek (2017) used numerical methods for nano modeling.

In this manuscript, free vibration analysis of laminated composite circular plate is performed via differential quadrature (DQ) and discrete singular convolution (DSC). The related governing equations of motion for circular plate are obtained via conical shell equations. Effects of different lay-up on frequencies of circular and annular laminated plates are discussed. Also, performance of DSC method is investigated in detail.

## 2. Solution methodology

Two different methods are used for solution. Firstly, differential quadrature is used. In DQ, differential equation transforms into a set of analogous algebraic equations as below

$$\left. \frac{\partial^r u}{\partial x^r} \right|_{x=x_i} = \sum_{k=1}^{N_x} A_{ik}^{(r)} u(x_k, y_j); \quad r=1,2,\dots,N_x-1 \quad (1)$$

$$\left. \frac{\partial^s u}{\partial y^s} \right|_{y=y_j} = \sum_{k=1}^{N_y} B_{jk}^{(s)} u(x_i, y_k); \quad s=1,2,\dots,N_y-1 \quad (2)$$

$$\left. \frac{\partial^{(r+s)} u}{\partial x^r \partial y^s} \right|_{x_i y_j} = \frac{\partial^r}{\partial x^r} \left( \frac{\partial^s u}{\partial y^s} \right)_{x_i y_j} = \sum_{k=1}^{N_x} A_{ik}^{(r)} \cdot \sum_{m=1}^{N_y} B_{jm}^{(s)} u(x_k, y_m) \quad (3)$$

The second, third, and fourth-order derivatives are calculated via

$$B_{ij} = \sum_{k=1}^N A_{ik} A_{kj}, \quad C_{ij} = \sum_{k=1}^N A_{ik} B_{kj}, \quad D_{ij} = \sum_{k=1}^N A_{ik} C_{kj} \quad (4)$$

Discrete singular convolution (DSC) is suggested by Wei (2001a, b) for the first time in order to fast solution of the mathematical physics problems (Wang *et al.* 2012, Civalek and Akgoz 2013, Gürses *et al.* 2012, Civalek and Acar 2007, Demir *et al.* 2016, Civalek *et al.* 2016, Hou *et al.* 2005, Civalek *et al.* 2010, Mercan and Civalek 2017). As similar the other discrete numerical methods, the function  $f(x)$  and its derivatives with respect to  $x$  coordinate at a grid point  $x_i$  are approximated by a linear sum of discrete values  $f(x_k)$  in a narrow bandwidth  $[x-x_M, x+x_M]$  in DSC. Namely

$$\left. \frac{d^n f(x)}{dx^n} \right|_{x=x_i} = f^{(n)}(x) \approx \sum_{k=-M}^M \delta_{\Delta,\sigma}^{(n)}(x_i - x_k) f(x_k) \quad (5)$$

In this paper, the detailed formulation and mathematical details of the DQ and DSC methods are not given; interested readers may refer to the works of (Wei *et al.* 2001, Wei *et al.* 2002a, Wei *et al.* 2002b, Gürses *et al.* 2009, Baltacioglu *et al.* 2010, Baltacioglu *et al.* 2011, Civalek 2008, Civalek 2013, Duan *et al.* 2014, Civalek and Akgoz 2011, Mercan and Civalek 2016). It is mentioned that the use of the regularized Shannon kernel (RSK) is very effective. This kernel is as follows

$$\delta_{\Delta,\sigma}(x-x_k) = \frac{\sin[(\pi/\Delta)(x-x_k)]}{(\pi/\Delta)(x-x_k)} \exp\left[-\frac{(x-x_k)^2}{2\sigma^2}\right] \quad (6)$$

The solution is also made by DQM (Striz *et al.* 1995, Shu and Xue 1997, Civalek 2004). Detailed formulations for DQ and HDQ can be found in open literature.

## 3. Formulations

Consider a thick laminated circular plate as shown in Fig. 1.

After using the only normal and rotary inertia ( $I_1$  and  $I_3$ ), terms, governing differential equations of motion via FSDT can be given as

$$\begin{aligned} & A_{11} \frac{\partial^2 u}{\partial x^2} + \frac{A_{11}}{R(x)} \sin \alpha \frac{\partial u}{\partial x} - \frac{A_{22}}{R^2(x)} \sin^2 \alpha \cdot u + \frac{A_{33}}{R^2(x)} \frac{\partial^2 u}{\partial s^2} + \frac{(A_{12} + A_{33})}{R(x)} \frac{\partial^2 v}{\partial x \partial s} \\ & - \frac{(A_{22} + A_{33})}{R^2(x)} \sin \alpha \frac{\partial v}{\partial s} + \frac{A_{12}}{R(x)} \cos \alpha \frac{\partial w}{\partial x} - \frac{A_{22}}{R^2(x)} \sin \alpha \cdot \cos \alpha \cdot w - B_{11} \frac{\partial^2 \varphi_x}{\partial x^2} \\ & + \frac{B_{11}}{R(x)} \sin \alpha \frac{\partial \varphi_x}{\partial x} - \frac{B_{22}}{R^2(x)} \sin^2 \alpha \cdot \varphi_x + \frac{B_{33}}{R^2(x)} \frac{\partial^2 \varphi_x}{\partial s^2} \\ & + \frac{(B_{12} + B_{33})}{R(x)} \frac{\partial^2 \varphi_s}{\partial x \partial s} - \frac{(B_{22} + B_{33})}{R^2(x)} \frac{\partial \varphi_s}{\partial s} \sin \alpha = I_1 \frac{\partial^2 u}{\partial t^2} \end{aligned} \quad (7)$$

$$\begin{aligned} & \frac{(A_{12} + A_{33})}{R(x)} \frac{\partial^2 u}{\partial x \partial s} + \frac{(A_{22} + A_{33})}{R^2(x)} \sin \alpha \frac{\partial u}{\partial s} + A_{33} \frac{\partial^2 v}{\partial x^2} + A_{33} \frac{\sin \alpha}{R(x)} \frac{\partial v}{\partial x} \\ & - \frac{A_{33}}{R^2(x)} \sin^2 \alpha \cdot v + \frac{A_{22}}{R^2(x)} \frac{\partial^2 v}{\partial s^2} - \frac{A_{44}}{R^2(x)} \cos^2 \alpha \cdot v + \frac{(A_{22} + A_{44})}{R^2(x)} \cos \alpha \frac{\partial w}{\partial s} \\ & + \frac{(B_{12} + B_{33})}{R(x)} \frac{\partial^2 \varphi_s}{\partial x \partial s} + \frac{(B_{22} + B_{33})}{R^2(x)} \sin \alpha \frac{\partial \varphi_s}{\partial s} + B_{33} \frac{\partial^2 \varphi_s}{\partial x^2} + B_{33} \frac{\sin \alpha}{R(x)} \frac{\partial \varphi_s}{\partial x} \\ & - \frac{B_{33}}{R^2(x)} \sin^2 \alpha \cdot \varphi_s + \frac{B_{22}}{R^2(x)} \frac{\partial^2 \varphi_s}{\partial s^2} + A_{44} \frac{\cos \alpha}{R(x)} \cdot \varphi_s = I_1 \frac{\partial^2 v}{\partial t^2} \end{aligned} \quad (8)$$

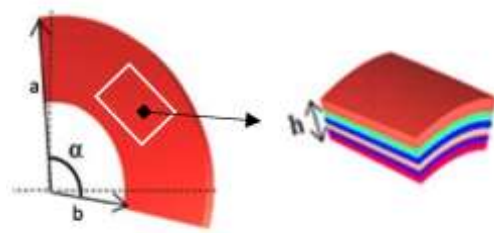


Fig. 1 Geometry and notation of an annular plate

$$\begin{aligned}
& -\frac{A_{12}}{R(x)} \cos \alpha \frac{\partial u}{\partial x} - \frac{A_{22}}{R^2(x)} \cdot u \cdot \sin \alpha \cdot \cos \alpha - \frac{(A_{22} + A_{44})}{R^2(x)} \cdot \cos \alpha \frac{\partial v}{\partial s} + A_{55} \frac{\partial^2 w}{\partial x^2} \\
& + \frac{A_{55}}{R(x)} \sin \alpha \cdot \frac{\partial w}{\partial s} + \frac{A_{44}}{R^2(x)} \frac{\partial^2 w}{\partial s^2} - \frac{A_{22}}{R^2(x)} \cdot w \cdot \cos^2 \alpha + A_{55} \frac{\partial \varphi_x}{\partial x} - \frac{B_{12}}{R(x)} \cos \alpha \cdot \frac{\partial \varphi_s}{\partial x} \\
& + \frac{A_{55}}{R(x)} \sin \alpha \cdot \varphi_x - \frac{B_{22}}{R^2(x)} \sin \alpha \cdot \cos \alpha \cdot \varphi_x + \frac{A_{44}}{R(x)} \cdot \frac{\partial \varphi_s}{\partial s} \\
& - \frac{B_{22}}{R^2(x)} \cdot \cos \alpha \frac{\partial \varphi_s}{\partial s} = I_1 \frac{\partial^2 w}{\partial t^2}
\end{aligned} \quad (9)$$

$$\begin{aligned}
& B_{11} \frac{\partial^2 u}{\partial x^2} + \frac{B_{11}}{R(x)} \sin \alpha \frac{\partial u}{\partial x} - \frac{B_{22}}{R^2(x)} \cdot u \cdot \sin^2 \alpha + \frac{B_{33}}{R^2(x)} \frac{\partial^2 u}{\partial s^2} + \frac{(B_{12} + B_{33})}{R(x)} \frac{\partial^2 v}{\partial x \partial s} \\
& - \frac{(B_{22} + B_{33})}{R^2(x)} \sin \alpha \frac{\partial v}{\partial s} - A_{55} \frac{\partial w}{\partial x} + B_{12} \frac{\cos \alpha}{R(x)} \frac{\partial w}{\partial x} - \frac{B_{22}}{R^2(x)} \cdot w \cdot \sin \alpha \cos \alpha \\
& + D_{11} \frac{\partial^2 \varphi_x}{\partial x^2} + D_{11} \frac{\sin \alpha}{R(x)} \frac{\partial \varphi_x}{\partial x} - \frac{D_{22}}{R^2(x)} \varphi_x \sin^2 \alpha + \frac{D_{33}}{R^2(x)} \frac{\partial^2 \varphi_x}{\partial s^2} - A_{55} \varphi_x \\
& + \frac{(D_{12} + D_{33})}{R(x)} \frac{\partial^2 \varphi_s}{\partial x \partial s} - \frac{(D_{22} + D_{33})}{R^2(x)} \frac{\partial \varphi_s}{\partial s} \sin \alpha = I_3 \frac{\partial^2 \varphi_x}{\partial t^2} \\
& \frac{(B_{12} + B_{33})}{R(x)} \frac{\partial^2 u}{\partial x \partial s} + \frac{(B_{22} + B_{33})}{R^2(x)} \frac{\partial u}{\partial s} \sin \alpha + B_{33} \frac{\partial^2 v}{\partial x^2} + B_{33} \frac{\sin \alpha}{R(x)} \frac{\partial v}{\partial x} \\
& - B_{33} \frac{\sin^2 \alpha}{R^2(x)} \cdot v + \frac{B_{22}}{R^2(x)} \frac{\partial^2 v}{\partial s^2} + \frac{A_{44}}{R(x)} \cdot v \cdot \cos \alpha - \frac{A_{44}}{R(x)} \frac{\partial w}{\partial s} + \frac{B_{22}}{R^2(x)} \cos \alpha \frac{\partial w}{\partial s} \\
& + \frac{(D_{12} + D_{33})}{R(x)} \frac{\partial^2 \varphi_x}{\partial x \partial s} + \frac{(D_{22} + D_{33})}{R^2(x)} \sin \alpha \frac{\partial \varphi_x}{\partial s} - D_{33} \frac{\partial^2 \varphi_s}{\partial x^2} \\
& + D_{33} \frac{\sin \alpha}{R(x)} \frac{\partial \varphi_s}{\partial x} - \frac{D_{33}}{R^2(x)} \sin^2 \alpha \cdot \varphi_s + \frac{D_{22}}{R^2(x)} \frac{\partial^2 \varphi_s}{\partial s^2} - A_{44} \cdot \varphi_s = I_3 \frac{\partial^2 \varphi_s}{\partial t^2}
\end{aligned} \quad (10)$$

For modal analysis, the below harmonic functions can be used

$$\begin{aligned}
& \begin{Bmatrix} u(x, s, t) \\ v(x, s, t) \\ w(x, s, t) \\ \varphi_x(x, s, t) \\ \varphi_s(x, s, t) \end{Bmatrix} = e^{i\omega t} \begin{Bmatrix} U(x, s, t) \\ V(x, s, t) \\ W(x, s, t) \\ \Psi_x(x, s, t) \\ \Psi_s(x, s, t) \end{Bmatrix}
\end{aligned} \quad (12)$$

If Eq. (12) is written in Eqs. (7)-(11), the final governing equations can be expressed as matrix form (Viswanathan *et al.* 2015, Mehdiatabar *et al.* 2018)

$$L_{11} + L_{12} + L_{13} + L_{14} + L_{15} - \rho h \cdot \omega^2 = 0 \quad (13a)$$

$$L_{21} + L_{22} + L_{23} + L_{24} + L_{25} - \rho h \cdot \omega^2 = 0 \quad (13b)$$

$$L_{31} \cdot U + L_{32} \cdot V + L_{33} \cdot W + L_{34} \cdot \Phi_x + L_{35} \cdot \Phi_y - \rho h \cdot \omega^2 = 0 \quad (13c)$$

$$L_{41} \cdot U + L_{42} \cdot V + L_{43} \cdot W + L_{44} \cdot \Phi_x + L_{45} \cdot \Phi_y - \rho h^3 \cdot \omega^2 / 12 = 0 \quad (13d)$$

$$L_{51} \cdot U + L_{52} \cdot V + L_{53} \cdot W + L_{54} \cdot \Phi_x + L_{55} \cdot \Phi_y - \rho h^3 \cdot \omega^2 / 12 = 0 \quad (13e)$$

Differential operators in Eqs. (13(a))-(13(e)) are listed in Appendix.

#### 4. Numerical solution of equation of motion

After adopted DSC method, the equations of motion of plate can also be written as (Viswanathan *et al.* 2015, Mehdiatabar *et al.* 2018)

$$\begin{aligned}
& {}^{DSC}L_{11} \cdot U + {}^{DSC}L_{12} \cdot V + {}^{DSC}L_{13} \cdot W + {}^{DSC}L_{14} \cdot \Phi_x + {}^{DSC}L_{15} \cdot \Phi_y - \rho h \cdot \omega^2 = 0 \\
& {}^{DSC}L_{21} \cdot U + {}^{DSC}L_{22} \cdot V + {}^{DSC}L_{23} \cdot W + {}^{DSC}L_{24} \cdot \Phi_x + {}^{DSC}L_{25} \cdot \Phi_y - \rho h \cdot \omega^2 = 0 \\
& {}^{DSC}L_{31} \cdot U + {}^{DSC}L_{32} \cdot V + {}^{DSC}L_{33} \cdot W + {}^{DSC}L_{34} \cdot \Phi_x + {}^{DSC}L_{35} \cdot \Phi_y - \rho h \cdot \omega^2 = 0 \\
& {}^{DSC}L_{41} \cdot U + {}^{DSC}L_{42} \cdot V + {}^{DSC}L_{43} \cdot W + {}^{DSC}L_{44} \cdot \Phi_x + {}^{DSC}L_{45} \cdot \Phi_y - \rho h^3 \cdot \omega^2 / 12 = 0 \\
& {}^{DSC}L_{51} \cdot U + {}^{DSC}L_{52} \cdot V + {}^{DSC}L_{53} \cdot W + {}^{DSC}L_{54} \cdot \Phi_x + {}^{DSC}L_{55} \cdot \Phi_y - \rho h^3 \cdot \omega^2 / 12 = 0
\end{aligned} \quad (14)$$

Discrete form of these differential operators are as

$${}^{DSC}L_{11} = A_{11} \cdot \Xi_x^{(2)} + \frac{A_{11}}{R(x)} \sin \alpha \cdot \Xi_x^{(1)} - \frac{A_{22}}{R^2(x)} \cdot U(i) \cdot \sin^2 \alpha + \frac{A_{33}}{R^2(x)} \cdot \Xi_s^{(2)} \quad (15)$$

$${}^{DSC}L_{12} = \frac{(A_{12} + A_{33})}{R(x)} \sin \alpha \cdot \Xi_x^{(2)} \frac{\partial^2 V}{\partial x \partial s} - \frac{(A_{22} + A_{33})}{R^2(x)} \sin \alpha \cdot \Xi_s^{(1)} \quad (16)$$

$${}^{DSC}L_{13} = \frac{A_{12}}{R(x)} \cos \alpha \cdot \Xi_x^{(1)} - \frac{A_{22}}{R^2(x)} \cdot W(i) \cdot \sin \alpha \cdot \cos \alpha \quad (17)$$

$${}^{DSC}L_{14} = B_{11} \cdot \Xi_x^{(2)} + \frac{B_{11}}{R(x)} \sin \alpha \cdot \Xi_x^{(1)} - \frac{B_{22}}{R^2(x)} \cdot \Psi_x(i) \sin^2 \alpha + \frac{B_{33}}{R^2(x)} \cdot \Xi_s^{(2)} \quad (18)$$

$${}^{DSC}L_{15} = \frac{(B_{12} + B_{33})}{R(x)} \cdot \Xi_x^{(1)} \cdot \Xi_s^{(1)} - \frac{(B_{22} + B_{33})}{R^2(x)} \cdot \Xi_s^{(1)} \cdot \sin \alpha \quad (19)$$

$${}^{DSC}L_{21} = \frac{(A_{12} + A_{33})}{R(x)} \cdot \Xi_x^{(1)} \cdot \Xi_s^{(1)} + \frac{(A_{22} + A_{33})}{R^2(x)} \sin \alpha \cdot \Xi_s^{(1)} \quad (20)$$

$${}^{DSC}L_{22} = A_{33} \Xi_x^{(2)} + A_{33} \frac{\sin \alpha}{R(x)} \Xi_s^{(1)} - \frac{A_{33}}{R^2(x)} \cdot V(i) \cdot \sin^2 \alpha + \frac{A_{22}}{R^2(x)} \Xi_s^{(2)} - \frac{A_{44}}{R^2(x)} \cdot V(i) \cdot \cos^2 \alpha \quad (21)$$

$${}^{DSC}L_{23} = \frac{(A_{22} + A_{44})}{R^2(x)} \cdot \cos \alpha \cdot \Xi_s^{(1)} \quad (22)$$

$${}^{DSC}L_{24} = \frac{(B_{12} + B_{33})}{R(x)} \cdot \Xi_x^{(1)} \cdot \Xi_s^{(1)} + \frac{(B_{22} + B_{33})}{R^2(x)} \sin \alpha \cdot \Xi_s^{(1)} \quad (23)$$

$${}^{DSC}L_{25} = B_{33} \cdot \Xi_x^{(2)} + B_{33} \frac{\sin \alpha}{R(x)} \cdot \Xi_s^{(1)} - \frac{B_{33}}{R^2(x)} \cdot \Psi_s(i) \cdot \sin^2 \alpha + \frac{B_{22}}{R^2(x)} \cdot \Xi_s^{(2)} + A_{44} \cdot \frac{\cos \alpha}{R(x)} \cdot \Psi_s(i) \quad (24)$$

$${}^{DSC}L_{31} = -\frac{A_{12}}{R(x)} \cos \alpha \cdot \Xi_x^{(1)} - \frac{A_{22}}{R^2(x)} \cdot U(i) \cdot \sin \alpha \cdot \cos \alpha \quad (25)$$

$${}^{DSC}L_{32} = -\frac{(A_{22} + A_{44})}{R^2(x)} \cos \alpha \cdot \Xi_s^{(1)} \quad (26)$$

$${}^{DSC}L_{33} = A_{35} \cdot \Xi_s^{(2)} + \frac{A_{35}}{R(x)} \sin \alpha \cdot \Xi_s^{(1)} + \frac{A_{44}}{R^2(x)} \cdot \Xi_s^{(2)} - \frac{A_{22}}{R^2(x)} \cdot W(i) \cdot \cos^2 \alpha \quad (27)$$

$${}^{DSC}L_{34} = A_{55} \cdot \Xi_s^{(1)} - \frac{B_{12}}{R(x)} \cos \alpha \cdot \Xi_s^{(1)} \quad (28)$$

$$+ \frac{A_{55}}{R(x)} \cdot \Psi_s(i) \cdot \sin \alpha - \frac{B_{22}}{R^2(x)} \cdot \Psi_s(i) \cdot \sin \alpha \cdot \cos \alpha \quad (28)$$

$${}^{DSC}L_{35} = \frac{A_{44}}{R(x)} \cdot \Xi_s^{(1)} - \frac{B_{22}}{R^2(x)} \cdot \cos \alpha \cdot \Xi_s^{(1)} \quad (29)$$

$${}^{DSC}L_{41} = B_{11} \cdot \Xi_s^{(2)} + \frac{B_{11}}{R(x)} \sin \alpha \cdot \Xi_s^{(1)} - \frac{B_{22}}{R^2(x)} \cdot U(i) \cdot \sin^2 \alpha + \frac{B_{33}}{R^2(x)} \cdot \Xi_s^{(2)} \quad (30)$$

$${}^{DSC}L_{42} = \frac{(B_{12} + B_{33})}{R(x)} \cdot \Xi_s^{(1)} \cdot \Xi_s^{(1)} - \frac{(B_{22} + B_{33})}{R^2(x)} \sin \alpha \cdot \Xi_s^{(1)} \quad (31)$$

$${}^{DSC}L_{43} = -A_{55} \cdot \Xi_s^{(1)} + B_{12} \frac{\cos \alpha}{R(x)} \cdot \Xi_s^{(1)} - \frac{B_{22}}{R^2(x)} \cdot W(i) \cdot \sin \alpha \cos \alpha \quad (32)$$

$${}^{DSC}L_{44} = D_{11} \cdot \Xi_s^{(2)} + D_{11} \frac{\sin \alpha}{R(x)} \cdot \Xi_s^{(1)} - \frac{D_{22}}{R^2(x)} \sin^2 \alpha + \frac{D_{33}}{R^2(x)} \cdot \Xi_s^{(2)} - A_{55} \cdot \Psi_s(i) \quad (33)$$

$${}^{DSC}L_{45} = \frac{(D_{12} + D_{33})}{R(x)} \cdot \Xi_s^{(1)} \cdot \Xi_s^{(1)} - \frac{(D_{22} + D_{33})}{R^2(x)} \cdot \Xi_s^{(1)} \sin \alpha \quad (34)$$

$${}^{DSC}L_{51} = \frac{(B_{12} + B_{33})}{R(x)} \cdot \Xi_s^{(1)} \cdot \Xi_s^{(1)} + \frac{(B_{22} + B_{33})}{R^2(x)} \cdot \Xi_s^{(1)} \sin \alpha \quad (35)$$

$${}^{DSC}L_{52} = B_{33} \cdot \Xi_s^{(2)} + B_{33} \frac{\sin \alpha}{R(x)} \cdot \Xi_s^{(1)} \quad (36)$$

$$- B_{33} \cdot \frac{\sin^2 \alpha}{R^2(x)} \cdot V(i) + \frac{B_{22}}{R^2(x)} \cdot \Xi_s^{(2)} + \frac{A_{44}}{R(x)} \cdot V(i) \cdot \cos \alpha$$

$${}^{DSC}L_{53} = -\frac{A_{44}}{R(x)} \cdot \Xi_s^{(1)} + \frac{B_{22}}{R^2(x)} \cos \alpha \cdot \Xi_s^{(1)} \quad (37)$$

$${}^{DSC}L_{54} = \frac{(D_{12} + D_{33})}{R(x)} \cdot \Xi_s^{(1)} \cdot \Xi_s^{(1)} + \frac{(D_{22} + D_{33})}{R^2(x)} \sin \alpha \cdot \Xi_s^{(1)} \quad (38)$$

$${}^{DSC}L_{55} = D_{33} \cdot \Xi_s^{(1)} + D_{33} \frac{\sin \alpha}{R(x)} \cdot \Xi_s^{(1)} \quad (39)$$

$$- \frac{D_{33}}{R^2(x)} \cdot \Psi_s(i) \cdot \sin^2 \alpha + \frac{D_{22}}{R^2(x)} \cdot \Xi_s^{(2)} - A_{44} \cdot \Psi_s(i)$$

DSC operator are given as

$$\Xi_x^{(n)} = \frac{\partial^{(n)}(\cdot)}{\partial x^{(n)}} = \sum_{k=-M}^M \delta_{\Delta, \sigma}^{(n)}(k \cdot \Delta x)(\cdot)_{i+k, j} \quad (40)$$

$$\Xi_s^{(n)} = \frac{\partial^{(n)}(\cdot)}{\partial s^{(n)}} = \sum_{k=-M}^M \delta_{\Delta, \sigma}^{(n)}(k \cdot \Delta s)(\cdot)_{i, j+k} \quad (41)$$

$$\Xi_x^1 \Xi_s^{(n-1)}(\cdot) = \sum_{k=-M}^M \delta_{\Delta, \sigma}^{(1)}(k \cdot \Delta x)(\cdot)_{i+k, j} \sum_{k=-M}^M \delta_{\Delta, \sigma}^{(n-1)}(k \cdot \Delta s)(\cdot)_{i, k+j} \quad (42)$$

$$\Xi_x^{(n-1)} \Xi_s^1(\cdot) = \sum_{k=-M}^M \delta_{\Delta, \sigma}^{(n-1)}(k \cdot \Delta x)(\cdot)_{i+k, j} \sum_{k=-M}^M \delta_{\Delta, \sigma}^{(1)}(k \cdot \Delta s)(\cdot)_{i, k+j} \quad (43)$$

Similarly, coefficients related partial derivations in DQM can also be written as

$$\Xi_x^{(n)}(\cdot) = \frac{\partial^{(n)}(\cdot)}{\partial x^{(n)}} = \sum_{k=1}^N C_{i+k, j}^{(n)}(i)(\cdot)_{i+k, j} \quad (44)$$

$$\Xi_s^{(n)}(\cdot) = \frac{\partial^{(n)}(\cdot)}{\partial s^{(n)}} = \sum_{k=1}^N C_{i, j+k}^{(n)}(j)(\cdot)_{i, j+k} \quad (45)$$

$$\Xi_x^1 \Xi_s^{(n-1)}(\cdot) = \sum_{k=1}^N C_{i+k, j}^{(1)}(i) \sum_{k=1}^N C_{i, k+j}^{(n-1)}(j)(\cdot)_{i, k+j} \quad (46)$$

$$\Xi_x^{(n-1)} \Xi_s^1(\cdot) = \frac{\partial^{(n-1)}(\cdot)}{\partial x^{(n-1)}} \frac{\partial(\cdot)}{\partial s} = \sum_{k=1}^N C_{i, k+j}^{(n-1)}(j) \sum_{k=1}^N C_{i+k, j}^{(1)}(i)(\cdot)_{i, k+j} \quad (47)$$

After discretization, the related equations in DQM form are as follows

$$\begin{aligned} {}^{DQ}L_{11} \cdot U + {}^{DQ}L_{12} \cdot V + {}^{DQ}L_{13} \cdot W + {}^{DQ}L_{14} \cdot \Phi_x + {}^{DQ}L_{15} \cdot \Phi_y - \rho h \cdot \omega^2 &= 0 \\ {}^{DQ}L_{21} \cdot U + {}^{DQ}L_{22} \cdot V + {}^{DQ}L_{23} \cdot W + {}^{DQ}L_{24} \cdot \Phi_x + {}^{DQ}L_{25} \cdot \Phi_y - \rho h \cdot \omega^2 &= 0 \\ {}^{DQ}L_{31} \cdot U + {}^{DQ}L_{32} \cdot V + {}^{DQ}L_{33} \cdot W + {}^{DQ}L_{34} \cdot \Phi_x + {}^{DQ}L_{35} \cdot \Phi_y - \rho h \cdot \omega^2 &= 0 \\ {}^{DQ}L_{41} \cdot U + {}^{DQ}L_{42} \cdot V + {}^{DQ}L_{43} \cdot W + {}^{DQ}L_{44} \cdot \Phi_x + {}^{DQ}L_{45} \cdot \Phi_y - \rho h^3 \cdot \omega^2 / 12 &= 0 \\ {}^{DQ}L_{51} \cdot U + {}^{DQ}L_{52} \cdot V + {}^{DQ}L_{53} \cdot W + {}^{DQ}L_{54} \cdot \Phi_x + {}^{DQ}L_{55} \cdot \Phi_y - \rho h^3 \cdot \omega^2 / 12 &= 0 \end{aligned} \quad (48)$$

The following boundary conditions are used  
Simply supported edge (S)

$$V=0, W=0, N_x=0, M_x=0, \Psi_s=0=0 \quad (49)$$

Clamped edge (C)

$$U=0, V=0, W=0, \Psi_x=0, \Psi_s=0 \quad (50)$$

From the above procedures, one can derive the general form of eigenvalue equation as follows

$$[G]\{X\} = \mathcal{Q}[B]\{X\} \quad (51)$$

## 5. Results

In this study, the following material properties are used

$$E_1 / E_2 = 40, \quad G_{12} = G_{13} = 0.6 E_{22}, \quad G_{12} / E_2 = 0.5$$

$$\nu_{12} = \nu_{13} = \nu_{23} = 0.25$$

All obtained results are listed in Tables 1-4 for laminated composite circular plate. Two different boundary conditions and two different lay-up (45/-45/-45/45) and (30/-30/-30/30) are also considered. Frequency values for laminated (30/-30/-30/30) and (45/-45/-45/45) circular plates with clamped edges ( $h/R = 0.1$ ,  $E_1/E_2=40$ ) and simply supported edges are tabulated in Tables 1-3, respectively. Frequency values for laminated (45/-45/-45/45) circular plates with clamped edges ( $h/R = 0.1$ ,  $E_1/E_2=40$ ) for different thickness-to-radius ratio are also listed in Table 4.

Several further examples are also solved and results are presented in Tables 5-10. For comparison purpose, frequency values of laminated (0/60/0) circular plates with clamped edges ( $a/h=5$ ) are listed in Table 5. The results obtained by using FEM is also given in Table 5 by Kahare and Mittal (2018, 2016) for comparison. It is shown that the present results are in close agreement with the data given by Kahare and Mittal (2018). Thus, the mesh size of  $11 \times 11$  is used in the next numerical examples, if otherwise is not mentioned. Other comparisons have also made for angle-ply laminated annular and results have been compared with the results by Viswanathan *et al.* (2013). For this purpose, Kevlar-49/epoxy (KGE) and Graphite Epoxy (AS4/3501-6) (AGE) materials are used and clamped-clamped boundary condition is considered. The obtained results are presented in Table 6. According to this table, it can be said that the results are in excellent agreement with the results of Viswanathan *et al.* (2013).

Table 1 Frequency ( $\Omega_1 = \omega R^2 \sqrt{\rho/E_2}$ ) for laminated (30/-30/-30/30) circular plates with clamped edges ( $h/R=0.1$ ,  $E_1/E_2=40$ )

Modes	Present DSC results-FSDT( $N_s=9$ )				
	$N_x=9$	$N_x=11$	$N_x=13$	$N_x=15$	$N_x=17$
1	24.1030	24.1028	24.1028	24.1028	24.1028
2	36.2178	36.2175	36.2175	36.2175	36.2175
3	44.1162	44.1159	44.1159	44.1159	44.1159
4	51.2389	51.2384	51.2384	51.2384	51.2384
5	56.4077	56.4072	56.4072	56.4072	56.4072

Table 2 Frequency ( $\Omega_1 = \omega R^2 \sqrt{\rho/E_2 h^2}$ ) for laminated (45/-45/-45/45) circular plates with simply supported edges ( $h/R=0.1$ ,  $E_1/E_2=40$ )

Modes	Present DQ results- ( $N_s=9$ )				
	$N_x=9$	$N_x=11$	$N_x=13$	$N_x=15$	$N_x=17$
1	17.8034	17.8032	17.8032	17.8032	17.8032
2	32.1048	32.1045	32.1045	32.1045	32.1045
3	41.1987	41.1985	41.1985	41.1985	41.1985
4	52.0370	52.0366	52.0366	52.0366	52.0366
5	54.1032	54.1028	54.1028	54.1028	54.1028

Modes	Present DSC results-FSDT( $N_s=9$ )				
	$N_x=9$	$N_x=11$	$N_x=13$	$N_x=15$	$N_x=17$
1	17.8004	17.8004	17.8004	17.8004	17.8004
2	32.1037	32.1037	32.1037	32.1037	32.1037
3	41.1851	41.1853	41.1853	41.1853	41.1855
4	52.0340	52.0341	52.0341	52.0341	52.0343
5	53.9895	53.9903	53.9903	53.9903	53.9906

It is concluded from the results that the lamination angles and mode numbers have major effect on frequency. It is seen that for all three modes, the frequency parameter decreases when increasing the thickness-to-radius ratio and increases by the increasing value of mode numbers.

Frequency values of laminated (0/30/0) circular plates with clamped and simply supported edges are listed in Tables 7 and 8 for different thickness and modes. It can be concluded that as the value of the thickness increased frequency decreased for both of edges. It is also concluded that when the number of modes increased frequency values also increased gradually.

It is apparent from the results given in Tables 9-11 that the frequencies decrease monotonically as lamina angles increase. However, the effect of thickness is significant for circular and annular plate vibration. It is clearly shown from these tables that present DSC method converges very fast as the number of grid points increases. It can be also seen that the present DQ and DSC methods show a very good convergence, and solutions obtained from the DSC method are smaller than those produced from the DQ method.

Table 3 Frequency ( $\Omega_1 = \omega R^2 \sqrt{\rho/E_2 h^2}$ ) for laminated (45/-45/-45/45) circular plates with clamped edges ( $h/R=0.1$ ,  $E_1/E_2=40$ )

Modes	$N_x=9$	Present DSC results-FSDT( $N_s=9$ )			
		$N_x=11$	$N_x=13$	$N_x=15$	$N_x=17$
1	25.1826	25.1826	25.1826	25.1826	25.1826
2	40.1075	40.1073	40.1073	40.1073	40.1073
3	44.0850	44.0845	44.0845	44.0845	44.0845
4	57.8141	57.8137	57.8137	57.8137	57.8137
5	58.0143	58.0136	58.0134	58.0134	58.0134

Table 4 Frequency ( $\Omega_1 = \omega R^2 \sqrt{\rho/E_2 h^2}$ ) values of laminated (45/-45/-45/45) circular plates with clamped edges ( $h/R=0.1$ ,  $E_1/E_2=40$ ) for different thickness

Mod	h/R	Present DSC results ( $N_x=11$ )			
		$N_s=11$	$N_s=13$	$N_s=15$	$N_s=17$
1	0.001	46.7548	46.7548	46.7548	46.7548
	0.1	24.8539	24.8539	24.8539	24.8540
	0.2	15.0283	15.0283	15.0283	15.0284
2	0.001	71.1438	71.1438	71.1438	71.1438
	0.1	40.1047	40.1047	40.1048	40.1051
	0.2	23.2196	23.2196	23.2196	23.2198
3	0.001	111.0485	111.0485	111.0485	111.0485
	0.1	44.1173	44.1173	44.1173	44.1175
	0.2	24.6046	24.6046	24.6046	24.6050

Table 5 Comparison of frequency ( $\Omega = \omega a^2 \sqrt{\rho h / D}$ ) values of laminated (0/60/0) circular plates with clamped edges (a/h=5)

Mod	Khare and Mittal (2018)	Present DSC			
		9×11	11×11	13×13	15×13
1	6.6274	6.6402	6.6329	6.6329	6.6329
2	11.4553	11.4652	11.4639	11.4639	11.4639
3	13.2233	13.2515	13.2504	13.2504	13.2504
4	17.3143	17.3304	17.3293	17.3293	17.3293
5	18.2985	18.3125	18.3117	18.3117	18.3117
6	21.5902	21.6192	21.6185	21.6185	21.6185

Table 6 Comparison of frequency values of laminated annular plates (30/-30/30/-30) with C-C edges

Modes	Viswanathan <i>et al.</i> (2013)	Present DSC results (N <sub>s</sub> =9)			
		N <sub>x</sub> =9	N <sub>x</sub> =11	N <sub>x</sub> =13	N <sub>x</sub> =17
1	0.26977	0.2706	0.2703	0.2703	0.2703
2	0.689585	0.6918	0.6911	0.6911	0.6911
3	1.246933	1.2480	1.2473	1.2473	1.2473

Table 7 Frequency ( $\Omega = \omega a^2 \sqrt{\rho h / D}$ ) values of laminated (0/30/0) circular plates with clamped edges

h/a	Modes	Present DSC			
		9×11	13×11	13×13	15×13
0.2	1	6.5298	6.5294	6.5294	6.5294
	2	10.7335	10.7328	10.7328	10.7328
	3	13.5211	13.5207	13.5207	13.5207
	4	17.0040	17.0034	17.0034	17.0034
	5	18.1031	18.1025	18.1025	18.1025
	6	22.0074	22.0053	22.0051	22.0051
	Modes	Present DSC			
		11×11	13×11	13×13	15×13
0.1	1	7.3298	7.3295	7.3295	7.3295
	2	12.8911	12.8903	12.8903	12.8903
	3	16.4645	16.4637	16.4637	16.4637
	4	20.7156	20.7149	20.7149	20.7149
	5	22.7408	22.7397	22.7397	22.7397
	6	29.2314	29.2305	29.2303	29.2303

Modes		Present DSC			
		11×11	13×11	13×13	15×13
0.05	1	7.5891	7.5891	7.5891	7.5891
	2	13.7251	13.7247	13.7247	13.7247
	3	17.6043	17.6033	17.6033	17.6033
	4	22.7068	22.7056	22.7056	22.7056
	5	24.9377	24.9371	24.9369	24.9369
	6	33.0880	33.0864	33.0861	33.0861

Table 8 Frequency ( $\Omega = \omega a^2 \sqrt{\rho h / D}$ ) values of laminated (0/30/0) circular plates with simply supported edges

h/a	Modes	Present DSC			
		9×11	13×11	13×13	15×13
0.2	1	3.6424	3.6417	3.6417	3.6417
	2	7.8019	7.8012	7.8012	7.8012
	3	10.3705	10.3689	10.3689	10.3689
	4	13.6158	13.6146	13.6146	13.6146
	5	14.9583	14.9571	14.9571	14.9571
	6	17.3121	17.3108	17.3108	17.3108
	Modes	Present DSC			
		9×11	13×11	13×13	15×13
0.1	1	3.8011	3.8004	3.8004	3.8004
	2	8.7450	8.7442	8.7442	8.7442
	3	11.5351	11.5339	11.5339	11.5339
	4	16.0558	16.0547	16.0547	16.0547
	5	17.5911	17.5883	17.5883	17.5883
	6	23.4708	23.4691	23.4691	23.4691
	Modes	Present DSC			
		9×11	13×11	13×13	15×13
0.05	1	3.8269	3.8265	3.8265	3.8265
	2	9.0134	9.0127	9.0127	9.0127
	3	12.0341	12.0329	12.0329	12.0329
	4	16.9475	16.9467	16.9467	16.9467
	5	18.6019	18.6010	18.6008	18.6008
	6	24.7280	24.7265	24.7263	24.7263

Table 9 Fundamental frequency ( $\Omega = \omega a^2 \sqrt{\rho h / D}$ ) of laminated annular plates (b/a=0.1; a/h=5) with S-S edges

Lamina scheme	Khare and Mittal (2018)	Present DSC			
		9×11	11×11	13×13	15×13
0/15/0	10.0299	10.0675	10.0660	10.0657	10.0657
0/30/0	9.8554	9.8694	9.8687	9.8683	9.8683
0/45/0	9.6677	9.6848	9.6836	9.6832	9.6832
0/60/0	9.5606	9.5736	9.5728	9.5725	9.5725
0/75/0	9.5485	9.5580	9.5573	9.5569	9.5569

Table 10 Fundamental frequency ( $\Omega = \omega a^2 \sqrt{\rho h / D}$ ) of laminated annular plates (b/a=0.5) with C-C edges

a/h	Lamina scheme	Present DSC results				
		9×11	11×11	13×11	13×13	15×13
5	0/15/0	35.1020	35.1018	35.1009	35.1009	35.1009
	0/30/0	34.6868	34.6857	34.6857	34.6857	34.6857
	0/45/0	33.9338	33.9334	33.9325	33.9325	33.9325
	0/60/0	33.5375	33.5371	33.5362	33.5362	33.5362
10	0/15/0	57.0262	57.0254	57.0250	57.0250	57.0250
	0/30/0	56.0035	56.0030	56.0028	56.0028	56.0028
	0/45/0	54.8942	54.8934	54.8931	54.8931	54.8931
	0/60/0	53.8175	53.8172	53.8168	53.8167	53.8167
20	0/15/0	76.0491	76.0482	76.0482	76.0482	76.0482
	0/30/0	73.6420	73.6417	73.6410	73.6409	73.6409
	0/45/0	71.6643	71.6635	71.6634	71.6634	71.6634
	0/60/0	70.2846	70.2834	70.2831	70.2831	70.2831

Furthermore, some detailed performance of the present DSC method based on two different kernels, some further convergence analyses are also made and accuracy of the two different kernels is examined for laminated plate. For this, the method of DSC based on the two different kernels, FEM (Civalek 1998), and DQM are performed. It is also known (Wei 2000, Wei 2001) that the range of some parameters arises in comparing the numerical efficiency of DSC method such as  $r$ ,  $N$  and kernel types and some of them can be significant for some ranges. In this study, three different error measures are taken into consideration to evaluate the accuracy and convergence of the kernels and quality of the present transformation rules via DSC method. These are as follows

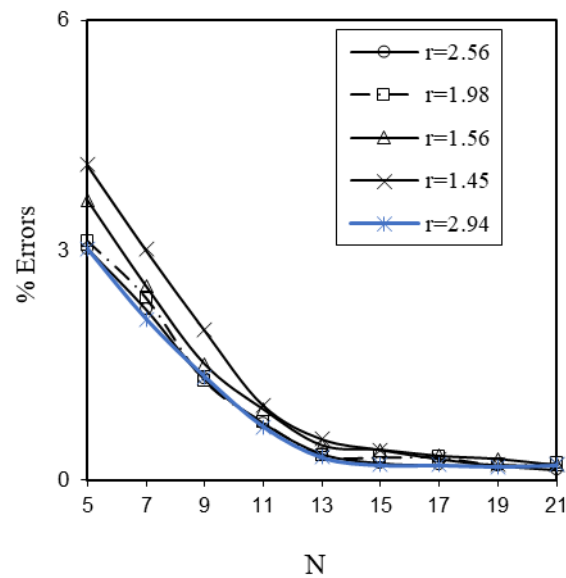
$$L_1 = \frac{1}{(N+1)^2} \sum_{i=0}^N \sum_{j=0}^N |S_{ij} - \bar{S}_{ij}| \quad (52)$$

$$L_2 = \frac{1}{(N+1)^2} \sqrt{\sum_{i=0}^N \sum_{j=0}^N |S_{ij} - \bar{S}_{ij}|^2} \quad (53)$$

$$E_r = \left| \frac{S_{ij} - \bar{S}_{ij}}{\bar{S}_{ij}} \right| \quad (54)$$

Table 11 Fundamental frequency ( $\Omega = \omega a^2 \sqrt{\rho/E_2 h^2}$ ) of laminated circular plates ( $h/a=0.1$ ) with clamped edge

Lamina scheme	Present DSC (Regularized Shannon's delta-RSD kernel)				
	9×9	11×11	13×11	13×13	15×13
0/-0/-0/0	23.0193	23.0161	23.0158	23.0158	23.0158
15/-15/-15/15	24.5801	24.5748	24.5739	24.5739	24.5739
30/-30/-30/30	25.5076	25.5066	25.5063	25.5063	25.5063
45/-45/-45/45	25.0095	25.0084	25.0081	25.0081	25.0081
Lamina scheme	Present DSC Lagrange delta sequence-LDS kernel				
	9×9	11×11	13×11	13×13	15×13
0/-0/-0/0	23.1156	23.1073	23.1076	23.1073	23.1073
15/-15/-15/15	24.5968	24.5867	24.5871	24.5867	24.5867
30/-30/-30/30	25.5231	25.5135	25.5135	25.5135	25.5135
45/-45/-45/45	25.0213	25.02446	25.02450	25.02446	25.02446
Lamina scheme	Present DQ				
	9×9	11×11	13×11	13×13	15×13
0/-0/-0/0	23.0261	23.0243	23.0243	23.0243	23.0243
15/-15/-15/15	24.6023	24.6012	24.6012	24.6012	24.6012
30/-30/-30/30	25.5108	25.5094	25.5094	25.5094	25.5094
45/-45/-45/45	25.0120	25.0112	25.0107	25.0107	25.0107

Fig. 2 Convergence and accuracy of clamped annular laminated (30/-30/30/-30) plates for 6<sup>th</sup> mode frequency (Lagrange delta sequence-LDS kernel) with grid numbers



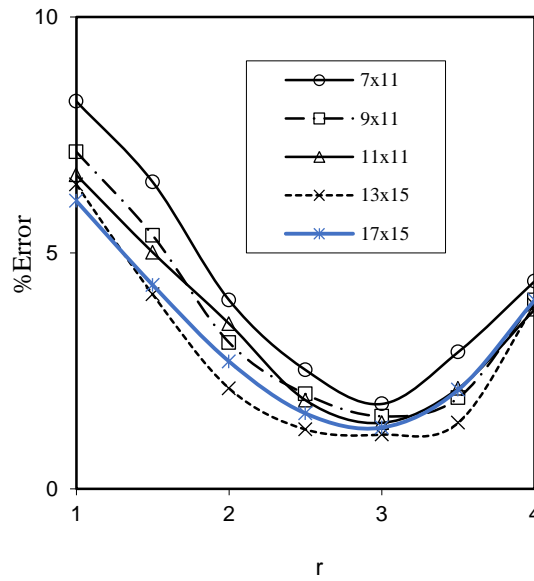


Fig. 3 Convergence of simply supported circular laminated (45/-45/45/-45) plates for 7<sup>th</sup> mode frequency (Shannon kernel) with DSC regularization

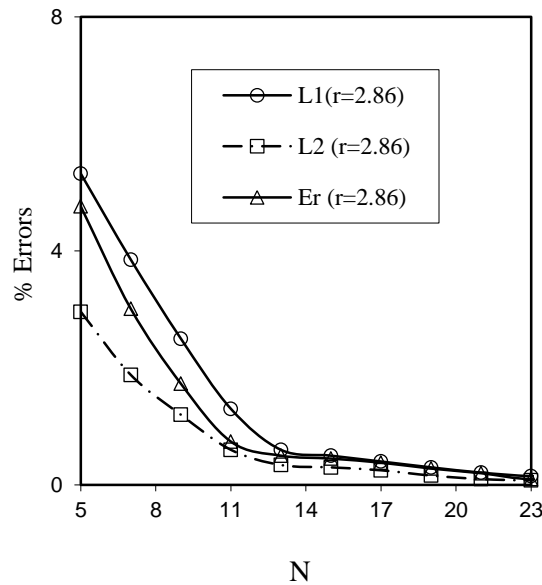


Fig. 4 Error analysis of clamped annular laminated (30/-30/30/-30) plates for 6<sup>th</sup> mode frequency (Regularized Shannon's delta-RSD kernel;  $r=2.86$ )

where  $S_{ij}$  and  $\tilde{S}_{ij}$  are the results calculated by DSC method via different kernels and exact/analytic or reference solution and  $E_r$  denotes the relative errors.

Firstly, the errors for 6<sup>th</sup> frequency values of S-S annular plate with angle-ply laminated scheme with respect to the results given by Viswanathan *et al.* (2013) are figured in

Figs. 2 and 3, respectively for two different kernels. It is shown from these figures that the results are efficient for  $N=11$  in each direction. Also, results are very good for Regularized Shannon's delta (RSD) and  $2.3 < r = \sigma/\Delta < 3.1$  parameter. In order to evaluate these parameters, the errors of the solution can be given as the three norms and are

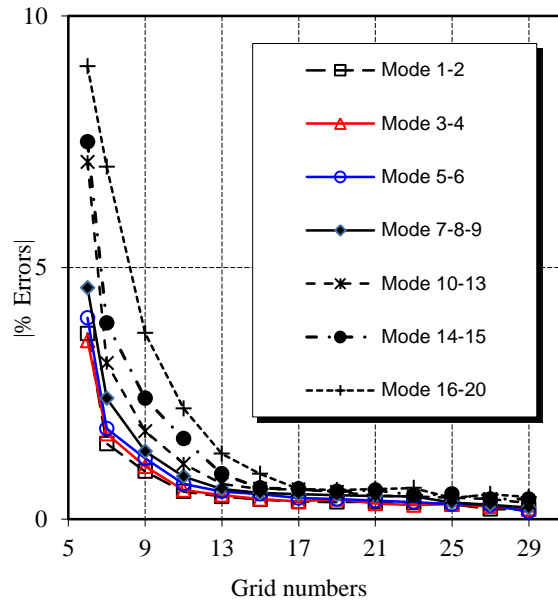


Fig. 5 Convergence of laminated annular plates for different modes with clamped edges with different grid numbers (Regularized Shannon's delta-RSD kernel)

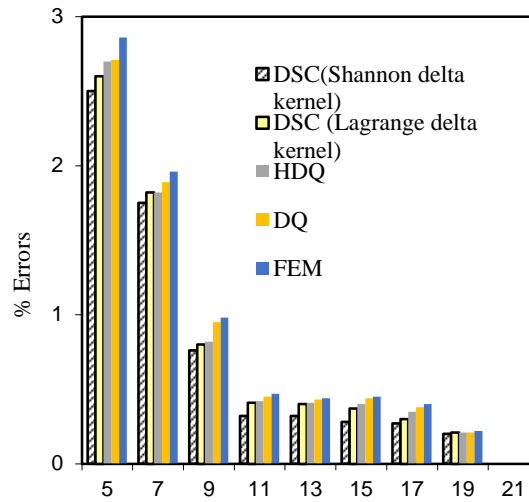


Fig. 6 Error analysis of angle-play laminated circular plates for 9<sup>th</sup> mode frequency with simply supported edges with different grid numbers

illustrated in Fig. 4. Also, in Figs. 5 and 6, convergence is tested for different modes and methods. It is found that as the grid numbers increase the percentage error also decreases. For DSC regularized parameter,  $r$ , DSC method provides acceptable results with a maximum discrepancy of 1.15% for  $r=2.86$  and  $N=11$ . Namely, a biggest value  $r$  is required, to obtain the convergence for higher frequency component of errors function. However, for  $N=15$ , this error is reduced to 0.70% for same regularized parameter. So, the DSC parameters can be more suitable as  $N=15$  and  $\sigma/\Delta = 2.86$  using Regularized Shannon's delta (RSD) kernel. It is also shown from these figures that only 11 grid points can

yield accurate results for frequency in lower modes. However, in higher modes, the method of DSC requires 13 grids in each direction for accurate results. In order to compare with other methods and to test the performance of the DSC method, clamped annular laminated plate vibration problem (Viswanathan *et al.* (2013) is selected and solved by three different methods. It is shown that DSC results using 13 grid points are more accurate than harmonic differential quadrature (HDQ) and FE methods for higher modes. A reasonably converged solution may be achieved for 15 grids by FEM. In addition to this, a reasonably converged solution may be obtained for 13 grid points using HDQ.

## 6. Conclusions

Frequency analyses of composite laminated circular plates are examined by DQ and DSC methods. FSDT shell theory is used for modeling of laminated circular plates. Effects of different angle/lamination on frequency values of laminated plates are investigated. The previous studies showed that Shannon's delta kernel gives the best result. Also, DSC is more suitable for higher modes (first 30 modes are obtained) even not reported in this study. Governing equations of motion of circular plates are reduced by the conical shell equations of motion. For computational calculation, two numerical methods are applied. It is concluded from the results that two methods have very good convergence. It is also concluded that the method of discrete singular convolution (DSC) based on Shannon's delta kernel is a promising and potential approach for computational mechanics of composite plates for free vibration of higher modes.

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## Appendix

The related differential operators are as follows

$$\begin{aligned}
L_{11} &= A_{11} \cdot U_{,xx} + \frac{A_{11}}{R(x)} \cdot \sin \alpha \cdot U_{,x} - \frac{A_{22}}{R^2(x)} \cdot U \cdot \sin^2 \alpha + \frac{A_{33}}{R^2(x)} \cdot U_{,ss} \\
L_{12} &= \frac{(A_{12} + A_{33})}{R(x)} \cdot \sin \alpha \cdot V_{,xs} - \frac{(A_{22} + A_{33})}{R^2(x)} \cdot \sin \alpha \cdot V_{,s} \\
L_{13} &= \frac{A_{12}}{R(x)} \cos \alpha \cdot W_{,x} - \frac{A_{22}}{R^2(x)} \cdot W \cdot \sin \alpha \cdot \cos \alpha \\
L_{14} &= B_{11} \cdot \Phi_{,x,xx} + \frac{B_{11}}{R(x)} \cdot \sin \alpha \cdot \Phi_{,x,x} - \frac{B_{22}}{R^2(x)} \cdot \Phi_{,s} \cdot \sin^2 \alpha + \frac{B_{33}}{R^2(x)} \cdot \Phi_{,s,ss} \\
L_{15} &= \frac{(B_{12} + B_{33})}{R(x)} \cdot \Phi_{,s,xx} - \frac{(B_{22} + B_{33})}{R^2(x)} \cdot \sin \alpha \cdot \Phi_{,s,s} \\
L_{21} &= \frac{(A_{12} + A_{33})}{R(x)} \cdot U_{,xs} + \frac{(A_{22} + A_{33})}{R^2(x)} \cdot \sin \alpha \cdot U_{,s} \\
L_{22} &= A_{33} \cdot V_{,xx} + A_{33} \frac{\sin \alpha}{R(x)} \cdot V_{,x} \\
&- \frac{A_{33}}{R^2(x)} \cdot V \cdot \sin^2 \alpha + \frac{A_{22}}{R^2(x)} \cdot V_{,ss} - \frac{A_{44}}{R^2(x)} \cdot V \cdot \cos^2 \alpha \\
L_{23} &= \frac{(A_{22} + A_{44})}{R^2(x)} \cdot \cos \alpha \cdot W_{,s} \\
L_{24} &= \frac{(B_{12} + B_{33})}{R(x)} \cdot \Psi_{,x,xx} + \frac{(B_{22} + B_{33})}{R^2(x)} \cdot \sin \alpha \cdot \Psi_{,x,s} \\
L_{25} &= B_{33} \cdot \Psi_{,s,xx} + B_{33} \cdot \frac{1}{R(x)} \cdot \sin \alpha \cdot \Psi_{,s,x} \\
&- B_{33} \cdot \frac{1}{R^2(x)} \cdot \Psi_{,s} \cdot \sin^2 \alpha + B_{22} \cdot \frac{1}{R^2(x)} \cdot \Psi_{,s,ss} + A_{44} \cdot \frac{1}{R(x)} \cdot \Psi_{,s} \cdot \cos \alpha \\
L_{31} &= -A_{12} \cdot \frac{1}{R(x)} \cdot \cos \alpha \cdot U_{,x} - A_{22} \cdot \frac{1}{R^2(x)} \cdot U \cdot \sin \alpha \cdot \cos \alpha \\
L_{32} &= -\frac{(A_{22} + A_{44})}{R^2(x)} \cdot \cos \alpha \cdot V_{,s} \\
L_{33} &= A_{55} \cdot W_{,xx} + A_{55} \frac{1}{R(x)} \cdot \sin \alpha \cdot W_{,s} \\
&+ A_{44} \cdot \frac{1}{R^2(x)} \cdot W_{,ss} - A_{22} \cdot \frac{1}{R^2(x)} \cdot W \cdot \cos^2 \alpha \\
L_{34} &= A_{55} \cdot \Psi_{,x,x} - B_{12} \cdot \frac{1}{R(x)} \cdot \cos \alpha \cdot \Psi_{,x,x} \\
&+ A_{55} \cdot \frac{1}{R(x)} \cdot \Psi_{,x} \cdot \sin \alpha - B_{22} \cdot \frac{1}{R^2(x)} \cdot \Psi_{,x} \cdot \sin \alpha \cdot \cos \alpha \\
L_{35} &= A_{44} \cdot \frac{1}{R(x)} \cdot \Psi_{,s,s} - B_{22} \cdot \frac{1}{R^2(x)} \cdot \cos \alpha \cdot \Psi_{,s,s} \\
L_{41} &= B_{11} \cdot U_{,xx} + \frac{B_{11}}{R(x)} \cdot \sin \alpha \cdot U_{,x} - \frac{B_{22}}{R^2(x)} \cdot U \cdot \sin^2 \alpha + \frac{B_{33}}{R^2(x)} \cdot U_{,ss} \\
L_{42} &= \frac{(B_{12} + B_{33})}{R(x)} \cdot V_{,xs} - \frac{(B_{22} + B_{33})}{R^2(x)} \cdot \sin \alpha \cdot V_{,s} \\
L_{43} &= -A_{55} \cdot W_{,x} + B_{12} \cdot \frac{\cos \alpha}{R(x)} \cdot W_{,x} - \frac{B_{22}}{R^2(x)} \cdot W \cdot \sin \alpha \cdot \cos \alpha \\
L_{44} &= D_{11} \cdot \Psi_{,x,xx} + D_{11} \cdot \frac{\sin \alpha}{R(x)} \cdot \Psi_{,x,x} - \frac{D_{22}}{R^2(x)} \cdot \Psi_{,x} \cdot \sin^2 \alpha \\
&+ \frac{D_{33}}{R^2(x)} \cdot \Psi_{,s,ss} - A_{55} \cdot \Psi_{,x} \\
L_{45} &= \frac{(D_{12} + D_{33})}{R(x)} \cdot \Psi_{,s,xx} - \frac{(D_{22} + D_{33})}{R^2(x)} \cdot \Psi_{,s,s} \cdot \sin \alpha \\
L_{51} &= \frac{(B_{12} + B_{33})}{R(x)} \cdot U_{,xs} + \frac{(B_{22} + B_{33})}{R^2(x)} \cdot U_{,s} \cdot \sin \alpha \\
L_{52} &= B_{33} \cdot V_{,xx} + B_{33} \frac{\sin \alpha}{R(x)} \cdot V_{,x}
\end{aligned}$$

$$\begin{aligned}
&- B_{33} \cdot \frac{\sin^2 \alpha}{R^2(x)} \cdot V + \frac{B_{22}}{R^2(x)} \cdot V_{,ss} + \frac{A_{44}}{R(x)} \cdot V \cdot \cos \alpha \\
L_{53} &= -\frac{A_{44}}{R(x)} \cdot W_{,s} + \frac{B_{22}}{R^2(x)} \cdot \cos \alpha \cdot W_{,s} \\
L_{54} &= \frac{(D_{12} + D_{33})}{R(x)} \cdot \Psi_{,x,xx} + \frac{(D_{22} + D_{33})}{R^2(x)} \cdot \sin \alpha \cdot \Psi_{,x,s} \\
L_{55} &= D_{33} \cdot \Psi_{,s,xx} + D_{33} \cdot \frac{\sin \alpha}{R(x)} \cdot \Psi_{,s} - \frac{D_{33}}{R^2(x)} \cdot \Psi_{,s,x} \cdot \sin^2 \alpha \\
&+ \frac{D_{22}}{R^2(x)} \cdot \Psi_{,s,ss} - A_{44} \cdot \Psi_{,s}
\end{aligned}$$