# Analysis of critical fluid velocity and heat transfer in temperature-dependent nanocomposite pipes conveying nanofluid subjected to heat generation, conduction, convection and magnetic field

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**Abstract.** In this paper, analysis of critical fluid velocity and heat transfer in the nanocomposite pipes conveying nanofluid is presented. The pipe is reinforced by carbon nanotubes (CNTs) and the fluid is mixed by  $AL_2O_3$  nanoparticles. The material properties of the nanocomposite pipe and nanofluid are considered temperature-dependent and the structure is subjected to magnetic field. The forces of fluid viscosity and turbulent pressure are obtained using momentum equations of fluid. Based on energy balance, the convection of inner and outer fluids, conduction of pipe and heat generation are considered. For mathematical modeling of the nanocomposite pipes, the first order shear deformation theory (FSDT) and energy method are used. Utilizing the Lagrange method, the coupled pipe-nanofluid motion equations are derived. Applying a semi-analytical method, the motion equations are solved for obtaining the critical fluid velocity and critical Reynolds and Nusselt numbers. The effects of CNTs volume percent,  $AL_2O_3$  nanoparticles volume percent, length to radius ratio of the pipe and shell surface roughness were shown on the critical fluid velocity, critical Reynolds and Nusselt numbers. The results are validated with other published work which shows the accuracy of obtained results of this work. Numerical results indicate that for heat generation of  $Q = 10 \text{ MW/m}^3$ , adding 6%  $AL_2O_3$  nanoparticles to the fluid increases 20% the critical fluid velocity and 15% the Nusselt number which can be useful for heat exchangers.

Keywords: critical fluid velocity; nanocomposite pipes; nanofluid; heat generation; temperature-dependent

# 1. Introduction

The forces induced by fluid and temperature to the pipelines are very important factors in damage and instability of them. However, researchers study different ways to improve the quality and stiffness of the pipelines across the mentioned loads. One of the new and good ways for increasing the stiffness of the structure is using CNTs as reinforce for pipelines since the Yong modulus of CNTs are about 1 TPa. In addition, for improving the heat transfer in the pipelines, mixing the fluid with nanoparticles is a good choice. However, in this paper, we presented the instability and heat transfer in nanocomposite pipelines conveying nanofluid.

Heat transfer in the pipe is reported by several researchers. Chica and Morente (2008) presented a new model for transient heat transfer model on external steel elements. The experimental study was performed by Shi *et al.* (2010) on five eccentric radial heat pipes with two outer-tube diameters. A practical quasi three-dimensional numerical model was developed by Li and Peterson (2011) to investigate the heat and mass transfer in a square flat evaporator of a loop heat pipe with a fully saturated wicking structure. Convective heat transfer phenomenon was

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Copyright © 2019 Techno-Press, Ltd. http://www.techno-press.org/?journal=scs&subpage=6 investigated by Chandel et al. (2012) experimentally as well as numerically in a thick-walled pipe for laminar flow as well turbulent flow. Evaporative heat transfer analysis of a heat pipe with hybrid axial groove was presented by Bai et al. (2013). Analysis of a circular pipe heated internally with a cyclic expanding convection boundary condition was performed by Sun and Zhang (2015). Analysis of heat transfer through a high strength concrete with circular pipe in a safety vessel of reactor vault was studied by Anish et al. (2017). Moradi-Dastjerdi and Payganeh (2017) studied transient heat transfer analysis of functionally graded (FG) carbon nanotube reinforced nanocomposite (CNTRC) cylinders with various essential and natural boundary conditions. A functionally graded magneto-thermoelastic half space with memory-dependent derivatives heat transfer was presented by Ezzat and El-Bary (2017). To clearly understand the operation phenomena of thermosyphon heat pipes, Kim et al. (2017) experimentally investigated the visualization of the operation and limit conditions for a water-filled thermosyphon as well as its thermal performance. Ding et al. (2018) presented an experimental study on boiling heat transfer and flow characteristics in a separated heat pipe system. Experiments and numerical simulations were used by Li et al. (2018) to study the heat transfer characteristics of a heat exchange system. Single phase heat transfer in a partially-filled, rotating horizontal pipe with axial liquid (water) flow was studied by Chatterjee et al. (2018).

In none of the above works, the nanofluid has not been

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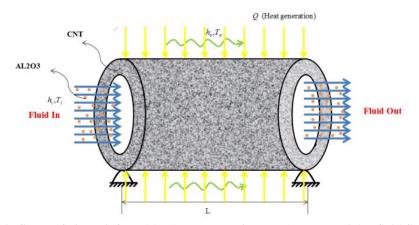


Fig. 1 Schematic figure of pipe reinforced by CNTs conveying AL<sub>2</sub>O<sub>3</sub> nanoparticles-fluid flow subjected to heat generation, convection and conduction

used by researchers. Massoudi et al. (1999) presented the governing equations for the flow of a dense particulate mixture in a pipe. The governing equations for the individual constituent as well as the mixture were provided based on continuum mechanics. Mixture theory was used by Massoudi and Johnson (2000) to develop a model for a flowing mixture of solid particulates and a fluid. Equations describing the flow of a two-component mixture consisting of a Newtonian fluid and a granular solid were derived. The effect of coal particle size distributions on rheology of coalwater slurries (CWS) was studied by Boylu et al. (2004). Experimental results on the steady-state viscosity of carbon nanotubes water-based nanofluids were presented by Halelfadl et al. (2013) considering the influence of particle volume fraction and temperature. A water-based TiO<sub>2</sub> nanofluid was studied by Colla et al. (2015) in order to evaluate the convective heat transfer under laminar forced and mixedflow conditions. Viscosity and thermal conductivity of the employed nanofluid were nearly identical with the equivalent values of the basefluid water. A numerical investigation of mixed convection was carried out by Al-asadi et al. (2017) to study the heat transfer and fluid flow characteristics in an inclined circular pipe using the finite volume method. A numerical investigation was carried out by Saha and Paul (2017) to investigate the transitional flow behaviour of nanofluids flow in an inclined pipe using both single and multi-phase models. Kang et al. (2017) studied visualization and thermal resistance measurements for a magnetic nanofluid pulsating heat pipe. In order to examine the laminar convective heat transfer of nanofluid, experiments were conducted by Hussein (2017) using a hybrid nanofluid through a double pipe heat exchanger. The experimental investigation was conducted by Vijayakumar et al. (2017) on the heat transfer characteristics of inclined copper sintered wick heat pipes using surfactant free CuO and Al<sub>2</sub>O<sub>3</sub> nanofluids.

To the best author's knowledge, no study on instability and heat transfer of nanocomposite pipes conveying nanofluid has been found in the literature. Hence, in this work, a mathematical model is used for nanocomposite pipes conveying nanofluid subjected to heat generation, conduction and convection. The pipe is reinforced by CNTs and the fluid is mixed by  $AL_2O_3$  nanoparticles. The material properties of the nanocomposite pipe and nanofluid are considered temperature-dependent and the structure is subjected to magnetic field. Coupling the momentum equation of the fluid, balance energy of the pipe and FSDT, the motion equations are derived utilizing the Lagrange method. Using a semi-analytical method, the critical fluid velocity and critical Reynolds and Nusselt numbers are obtained. The effects of different parameters such as CNTs volume percent,  $AL_2O_3$  nanoparticles volume percent, length to radius ratio of the pipe and shell surface roughness were shown on the critical fluid velocity, critical Reynolds and Nusselt numbers.

#### 2. Mathematical modeling of structure

In Fig. 1, a pipe reinforced by CNTs conveying  $AL_2O_3$  nanoparticles-fluid flow is shown subjected to heat generation, convection and conduction. The geometrical parameters of the pipe are length *L*, radius *R* and thickness *h*.

The coordinate axis of the pipe is located in the middle surface of left corner with the components of x,  $\theta$  and z along the axial, circumferential and transverse directions, respectively.

There are many new theories for modeling of different structures. Some of the new theories have been used by Tounsi and co-authors (Bessaim *et al.* 2013, Bouderba *et al.* 2013, Belabed *et al.* 2014, Meziane *et al.* 2014, Zidi *et al.* 2013, Belabed *et al.* 2014, Meziane *et al.* 2014, Zidi *et al.* 2014, Bourada *et al.* 2015, Bousahla *et al.* 2016a, b, Beldjelili *et al.* 2016, Boukhari *et al.* 2016, Draiche *et al.* 2016, Bellifa *et al.* 2015, Attia *et al.* 2015, Mahi *et al.* 2015, Bennoun *et al.* 2016, El-Haina *et al.* 2017, Menasria *et al.* 2017, Chikh *et al.* 2017, Zemri *et al.* 2015, Larbi Chaht *et al.* 2015, Belkorissat *et al.* 2015, Ahouel *et al.* 2016, Bounouara *et al.* 2016, Bouafia *et al.* 2017, Besseghier *et al.* 2017, Bellifa *et al.* 2017, Mouffoki *et al.* 2017, Khetir *et al.* 2017).

In this section, first order shear deformation theory is used. Based on this theory, the displacement field of the pipe can be written as (Reddy 2002)

$$u_{x}(x,\theta,z,t) = u(x,\theta,t) + z\psi_{x}(x,\theta,t), \qquad (1)$$

$$u_{\theta}(x,\theta,z,t) = v(x,\theta,t) + z\psi_{\theta}(x,\theta,t),$$
  

$$u_{z}(x,\theta,z,t) = w(x,\theta,t),$$
(1)

where  $(u_x, u_{\theta}, u_z)$  show the displacement components of any arbitrary point  $(x, \theta, z)$  in the shell. Also, (u, v, w) denote the displacement of a material point at  $(x, \theta)$  on the mid-plane (i.e., z = 0) of the shell in direction of the x-,  $\theta$ -, and z- axes, respectively. Furthermore,  $\psi_x$  and  $\psi_{\theta}$  indicate the rotations of the normal to the mid-plane about x- and  $\theta$ - axes, respectively. Using the above relation, the straindisplacement relation can be expressed as

$$\begin{bmatrix} \varepsilon_{xx} \\ \varepsilon_{\theta\theta} \\ \gamma_{\thetaz} \\ \gamma_{xz} \\ \gamma_{x\theta} \end{bmatrix} = \begin{bmatrix} \varepsilon_{xx}^{0} \\ \varepsilon_{\theta\theta}^{0} \\ \gamma_{\thetaz}^{0} \\ \gamma_{xz}^{0} \\ \gamma_{xz}^{0} \end{bmatrix} + z \begin{bmatrix} \varepsilon_{1x}^{1} \\ \varepsilon_{\theta\theta}^{1} \\ \gamma_{1z}^{1} \\ \gamma_{x\theta}^{1} \end{bmatrix} = \begin{bmatrix} \frac{\partial u}{\partial x} + \frac{1}{2} \left( \frac{\partial w}{\partial x} \right)^{2} \\ \frac{\partial v}{R \partial \theta} + \frac{w}{R} + \frac{1}{2} \left( \frac{\partial w}{R \partial \theta} \right) \\ \frac{\partial w}{R \partial \theta} - \frac{v}{R} + \psi_{\theta} \\ \frac{\partial w}{\partial x} + \psi_{x} \\ \frac{\partial u}{R \partial \theta} + \frac{\partial v}{\partial x} + \frac{\partial w}{R \partial \theta} \end{bmatrix} + z \begin{bmatrix} \frac{\partial \psi_{x}}{\partial x} \\ \frac{\partial \psi_{\theta}}{R \partial \theta} \\ \frac{\partial \psi_{\theta}}{R \partial \theta} \\ 0 \\ \frac{\partial \psi_{x}}{R \partial \theta} + \frac{\partial \psi_{\theta}}{\partial x} + \frac{\partial w}{R \partial \theta} \end{bmatrix} .$$
(2)

The stress-strain relations of the pipe can be expressed as follows based on Mori-Tanaka model (Shi and Feng 2004)

$$\begin{cases} \sigma_{xx} \\ \sigma_{\theta\theta} \\ \sigma_{zz} \\ \sigma_{\thetaz} \\ \sigma_{zz} \\ \sigma_{xz} \\ \sigma_{xz} \\ \sigma_{x\theta} \end{cases} = \begin{bmatrix} k+m & l & k-m & 0 & 0 & 0 \\ l & n & l & 0 & 0 & 0 \\ k-m & l & k+m & 0 & 0 & 0 \\ 0 & 0 & 0 & p & 0 & 0 \\ 0 & 0 & 0 & 0 & m & 0 \\ 0 & 0 & 0 & 0 & m & 0 \\ 0 & 0 & 0 & 0 & 0 & p \end{bmatrix} \begin{bmatrix} \varepsilon_{xx} - \alpha_{xx}T \\ \varepsilon_{\theta\theta} - \alpha_{\theta\theta}T \\ \varepsilon_{zz} \\ \gamma_{\thetaz} \\ \gamma_{xz} \\ \gamma_{x\theta} \end{bmatrix} , \quad (3)$$

in which k, m, n, l, p represent the stiffness coefficients of the CNTs-reinforced pipe which can be written as

$$k = \frac{E_m \{E_m c_m + 2k_r (1 + v_m)[1 + c_r (1 - 2v_m)]\}}{2(1 + v_m)[E_m (1 + c_r - 2v_m) + 2c_m k_r (1 - v_m - 2v_m^2)]}$$

$$l = \frac{E_m \{c_m v_m [E_m + 2k_r (1 + v_m)] + 2c_r l_r (1 - v_m^2)]\}}{(1 + v_m)[E_m (1 + c_r - 2v_m) + 2c_m k_r (1 - v_m - 2v_m^2)]}$$

$$n = \frac{E_m^2 c_m (1 + c_r - c_m v_m) + 2c_m c_r (k_r n_r - l_r^2)(1 + v_m)^2 (1 - 2v_m)}{(1 + v_m)[E_m (1 + c_r - 2v_m) + 2c_m k_r (1 - v_m - 2v_m^2)]}$$

$$+ \frac{E_m [2c_m^2 k_r (1 - v_m) + c_r n_r (1 + c_r - 2v_m) - 4c_m l_r v_m]}{E_m (1 + c_r - 2v_m) + 2c_m k_r (1 - v_m - 2v_m^2)}$$

$$p = \frac{E_m [E_m c_m + 2p_r (1 + v_m)(1 + c_r)]}{2(1 + v_m)[E_m (1 + c_r) + 2c_m p_r (1 + v_m)]}$$

$$m = \frac{E_m [E_m c_m + 2m_r (1 + v_m)(3 + c_r - 4v_m)]}{2(1 + v_m)\{E_m [c_m + 4c_r (1 - v_m)] + 2c_m m_r (3 - v_m - 4v_m^2)\}}$$

where the subscripts m and r are related to matrix and reinforcement, respectively;  $E_m$  and  $v_m$  are Yong modulus and Poisson's ration of the pipe;  $k_r$ ,  $l_r$ ,  $n_r$ ,  $p_r$ ,  $m_r$  represent the Hills elastic modulus for the CNTs;  $c_m$  and  $c_r$  denote the volume fractions of the matrix and the nanoparticles, respectively.

#### 2.1 Temperature distribution

The thermal conditions assumed in this paper are, the convection of inside fluid in the pipe, convection of outer air over the pipe, the conduction of the pipe in the thickness direction and the constant heat generation ( $\dot{q}$ ). Based on the mentioned assumptions, the energy balance equation in the (x,  $\theta$ , z) coordinate can be simplified as follows

$$\frac{d^2T}{dz^2} + \frac{\dot{q}}{k_e} = 0,$$
 (5)

Solution of the above relation yields

$$T = -\frac{Qz^{2}}{2k_{e}} + C_{1}z + C_{2}, \qquad (6)$$

The boundary conditions are

$$z = -\frac{h}{2} @ k_e \frac{\partial T}{\partial z} = -h_i (T_i - T), \qquad (7)$$

$$z = \frac{h}{2} @ k_e \frac{\partial T}{\partial z} = h_o \left( T_o - T \right) + \mathbf{Q}, \tag{8}$$

where  $h_i$  and  $h_o$  are convective heat transfer coefficients in the inner and outer fluids, respectively;  $T_i$  and  $T_o$  are temperature of the inner and outer fluids, respectively; Q is heat source. Noted that the temperature of the fluid can be obtained by the energy equation (Eq. (13)).

#### 2.2 Energies of the pipe

The potential energy of the pipe can be presented as follows

$$U_{P} = \frac{1}{2} \int_{0}^{2\pi} \int_{0}^{L} \int_{-h/2}^{h/2} \left( \frac{\sigma_{xx} \varepsilon_{xx} + \sigma_{\theta\theta} \varepsilon_{\theta\theta} + \sigma_{x\theta} \gamma_{x\theta}}{+ \sigma_{xz} \gamma_{xz} + \sigma_{\thetaz} \gamma_{\thetaz}} \right) dz dx R d \theta.$$
(9a)

The kinetic energy of the pipe can be expressed as follows

$$T_{P} = \frac{\rho_{P}}{2} \int_{0}^{2\pi} \int_{0}^{L} \int_{-h/2}^{h/2} \left( \left( \frac{\partial u_{x}}{\partial t} \right)^{2} + \left( \frac{\partial u_{\theta}}{\partial t} \right)^{2} + \left( \frac{\partial u_{z}}{\partial t} \right)^{2} \right) dz dx R d \theta.$$
(9b)

The external work in the pipe can be expressed as follows

$$W_{P} = \int_{0}^{2\pi} \int_{0}^{L} \left( \eta H_{x}^{2} \frac{\partial^{2} w}{\partial x^{2}} + \frac{N_{x}^{T}}{2} \left( \frac{\partial w}{\partial x} \right)^{2} + \frac{N_{\theta}^{T}}{2} \left( \frac{\partial w}{R \partial \theta} \right)^{2} \right) dx R d\theta,$$
(10)

where  $\eta$  and  $H_x$  are magnetic permeability and magnetic field, respectively;  $N_x^T$  and  $N_{\theta}^T$  are thermal forces in the axial and circumferential directions, respectively.

# 3. Fluid-structure interaction

In this section, the cylindrical coordinates r,  $\theta$  and z is used with the origin located at the center of shell's section. With the assumption of Newtonian fluid, steady state, incompressible flow and turbulent flow regime, the governing equations for the fluid are as follows:

Continuity

$$\frac{1}{r}\frac{\partial v_r}{\partial r} + \frac{\partial v_{\theta}}{r\partial \theta} + \frac{\partial v_x}{\partial x} = 0$$
(11)

Momentum

$$v_{x} \frac{\partial v_{x}}{\partial x} + v_{r} \frac{\partial v_{x}}{\partial r} + \frac{v_{\theta}}{r} \frac{\partial v_{x}}{\partial \theta} = -\frac{1}{\rho_{e}} \frac{\partial P}{\partial x}$$

$$-\left(\frac{\partial}{\partial x} \left(\bar{v_{x}}\right)^{2} + \frac{1}{r} \frac{\partial}{\partial r} r \bar{v_{x}} \bar{v_{r}} + \frac{1}{r} \frac{\partial}{\partial \theta} \bar{v_{x}} \bar{v_{\theta}}\right) + \frac{\mu_{e}}{\rho_{e}} \nabla^{2} v_{x}$$

$$v_{x} \frac{\partial v_{r}}{\partial x} + v_{r} \frac{\partial v_{r}}{\partial r} + \frac{v_{\theta}}{r} \frac{\partial v_{r}}{\partial \theta} - \frac{\left(v_{\theta}\right)^{2}}{r} =$$

$$-\frac{1}{\rho_{e}} \frac{\partial P}{\partial r} - \left(\frac{\partial}{\rho} \bar{v_{x}} \bar{v_{x}} + \frac{1}{\rho} \frac{\partial}{\rho} r \left(\bar{v_{x}}\right)^{2}\right)$$
(12)

$$-\frac{\rho_{e}}{\rho_{e}}\frac{\partial r}{\partial r} - \left(\frac{\partial x}{\partial x}v_{x}v_{r} + \frac{1}{r}\frac{\partial}{\partial r}r^{r}(v_{r})\right)$$

$$+\frac{1}{r}\frac{\partial}{\partial \theta}\overline{v_{r}}\overline{v_{\theta}} - \frac{\left(\overline{v_{\theta}}\right)^{2}}{r} + \frac{\mu_{e}}{\rho_{e}}\left(\nabla^{2}v_{r} - \frac{v_{r}}{r^{2}} - \frac{2}{r^{2}}\frac{\partial v_{\theta}}{\partial \theta}\right)$$

$$(13)$$

$$v_{x} \frac{\partial v_{\theta}}{\partial x} + v_{r} \frac{\partial v_{\theta}}{\partial r} + \frac{v_{\theta}}{r} \frac{\partial v_{\theta}}{\partial \theta} - \frac{v_{\theta}v_{r}}{r} = - \frac{1}{r\rho_{e}} \frac{\partial P}{\partial \theta} - \left(\frac{\partial}{\partial x} \overline{v_{x}} \overline{v_{\theta}} + \frac{\partial}{\partial r} \overline{v_{\theta}} \overline{v_{r}} \right) + \frac{1}{r} \frac{\partial}{\partial \theta} (\overline{v_{\theta}})^{2} - \frac{2\overline{v_{r}} \overline{v_{\theta}}}{r} + \frac{\mu_{e}}{\rho_{e}} \left(\nabla^{2} v_{\theta} - \frac{v_{\theta}}{r^{2}} + \frac{2}{r^{2}} \frac{\partial v_{\theta}}{\partial \theta}\right)$$
(14)

Energy

$$\frac{\partial T}{\partial t} + v_r \frac{\partial T}{\partial r} + v_\theta \frac{\partial T}{r \partial \theta} + v_x \frac{\partial T}{\partial x} = \frac{k_e}{c_{pe} \rho_e} \left( \frac{1}{r} \frac{\partial}{\partial r} \left( r \frac{\partial T}{\partial r} \right) + \frac{\partial^2 T}{r^2 \partial \theta^2} + \frac{\partial^2 T}{\partial x^2} \right),$$
(15)

where  $\overline{v_r}$ ,  $\overline{v_{\theta}}$ ,  $\overline{v_x}$  are the turbulent fluctuating velocity components in the *r*,  $\theta$  and *x* directions, respectively; *T* is the temperature distribution;  $k_e$ ,  $c_{pe}$ ,  $\rho_e$  and  $\mu_e$  are the thermal conductivity, heat capacity, density and fluid viscosity of the AL<sub>2</sub>O<sub>3</sub>-water nanofluid, respectively which can be expressed as (Buongiorno 2006, Maiga *et al.* 2005, Nguyen *et al.* 2007, Khanafer and Vafai 2011)

$$\rho_e = (1 - \phi)\rho_f + \phi\rho_p, \qquad (16)$$

$$c_{pe} = \frac{\left(1 - \phi\right)\rho_f c_f + \phi\rho_p c_p}{\rho_e},\tag{17}$$

$$\mu_e = \left(1 + 39.11\phi + 533.9\phi^2\right)\mu_f, \qquad (18)$$

$$\frac{k_e}{k_f} = 0.9843 + 0.398\phi^{0.7383} \left(\frac{1}{d_p}\right)^{0.2246}$$

$$\left(\frac{\mu_e}{\mu_f}\right)^{0.0235} - 3.9517\frac{\phi}{T} + 34.034\frac{\phi^2}{T^3} + 32.509\frac{\phi}{T^2},$$
(19)

where  $\phi$  and  $d_p$  are AL<sub>2</sub>O<sub>3</sub> volume percent and diameter in nano meter dimension, respectively; *T* is in Celsius. The viscosity of water in different temperatures is obtained by

$$\mu_f = 2.414 \times 10^{-5} \times 10^{\frac{247.8}{T-140}}$$
(20)

where T is in Kelvin.

#### 3.1 Fluid viscosity forces

In a fully developed turbulent pipe flow,  $v_r = v_\theta = 0$ ,  $\frac{\partial}{\partial 0} = 0$  and the velocity field is independent of the coordinate *x*. With the mentioned simplification, the timemean Navier–Stokes equations can be expressed as (Paak *et al.* 2014)

$$\frac{1}{\rho_e}\frac{\partial P}{\partial x} = -\frac{1}{r}\frac{\partial}{\partial r}\left(r\overline{v_x}\overline{v_r}\right) + \frac{\mu_e}{r\rho_e}\frac{d}{dr}\left(r\frac{dv_x}{dr}\right),\tag{21}$$

$$\frac{1}{\rho_e}\frac{\partial P}{\partial r} = -\frac{1}{r}\frac{\partial}{\partial r}r\left(\bar{v_r}\right)^2 + \frac{\left(\bar{v_\theta}\right)^2}{r},\tag{22}$$

$$0 = -\frac{\partial}{\partial r} \bar{v}_{\theta} \bar{v}_{r} - \frac{2\bar{v}_{r} \bar{v}_{\theta}}{r}, \qquad (23)$$

After lengthy mathematical manipulations, the pressure distribution can be written as

$$\overline{p}(\mathbf{x},\mathbf{r}) = -2\frac{\rho_e}{R}U_r^2 x - \rho_e \left(\overline{v_r}\right)^2 + \rho_e \int_R^r \frac{\left(\overline{v_\theta}\right)^2 - \left(\overline{v_r}\right)^2}{r} dr + \overline{p}(0,R),$$
(24)

where  $U_{\tau}$  is the shear velocity which can be defined as

$$U_{\tau}^{2} = \left(\frac{\mu_{e}}{\rho_{e}}\right) \left(\frac{dv_{x}}{dr}\right)\Big|_{r=R} = \frac{\tau_{w}}{\rho_{e}} = \left(\frac{1}{8}fv_{x}^{2}\right), \quad (25)$$

where  $\tau_w$  is the fluid frictional force per unit area on the pipe and *f* is the Darcy friction factor which may be calculated using Colebrook's implicit expression as follows (White 1986)

$$\frac{1}{\sqrt{f}} = -2\log_{10}\left(\frac{\varepsilon/D}{3.7} + \frac{2.51}{\text{Re}\sqrt{f}}\right),$$
 (26)

where  $\varepsilon$ , *D* and *Re* are respectively, pipe surface roughness, pipe diameter and Reynolds number. The initial value for *f* can be obtained from the following relation

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$$\frac{1}{\sqrt{f}} = -1.8 \log_{10} \left( \left( \frac{\varepsilon / D}{3.7} \right)^{1.11} + \frac{6.9}{\text{Re}} \right),$$
(27)

The distribution of mean pressure inside the pipe can be written as

$$P_r = 2\frac{\rho_e}{R}U_\tau^2 L,$$
(28)

$$P_{x} = \rho_{e} U_{\tau}^{2}, \qquad (29)$$

The work done due to viscosity effect can be expressed as

$$W_{FV} = \int_{0}^{2\pi} \int_{0}^{L} (P_{r}w + P_{x}u) dx R d \theta.$$
 (30)

#### 3.2 Perturbation pressure

The fluid structure interaction is described by linear potential flow theory. The flow velocity V may be expressed as (Amabili *et al.* 2009)

$$\boldsymbol{V} = -\nabla \boldsymbol{\Psi},\tag{31}$$

where  $\psi$  is a potential function including two components due to mean undisturbed flow velocity  $v_x$  and the shell motions. Hence

$$\Psi = -v_x x + \Phi, \tag{32}$$

The potential of the unsteady component  $\Phi$  satisfies the Laplace equation

$$\nabla^2 \Phi = \frac{\partial^2 \Phi}{\partial x^2} + \frac{\partial^2 \Phi}{\partial r^2} + \frac{1}{r} \frac{\partial \Phi}{\partial r} + \frac{1}{r^2} \frac{\partial \Phi}{\partial \theta^2} = 0, \quad (33)$$

In order to obtain the perturbed pressure (P) in term of velocity potential, the Bernoulli's equation is used as

$$-\frac{\partial\Phi}{\partial t} + \frac{1}{2}V^{2} + \frac{\overline{P} + p}{\rho_{e}} = \frac{\overline{P} + 1/2\rho_{f}\left(v_{x}\right)^{2}}{\rho_{e}},\qquad(34)$$

where  $\overline{P}$  and p are the mean pressure and perturbation pressure, respectively and for small perturbations we have

$$V^{2} = \left(v_{x}\right)^{2} - 2v_{x}\frac{\partial\Phi}{\partial x},$$
(35)

However, combining Eqs. (34) and (35) yields the perturbation pressure as follows

$$p = \rho_e \left( \frac{\partial \Phi}{\partial t} + v_x \frac{\partial \Phi}{\partial x} \right)$$
(36)

Assuming that there is no cavitation at the fluid-pipe interface, the boundary condition between the pipe wall and the flow is

$$\left(\frac{\partial \Phi}{\partial r}\right)_{r=R} = \left(\frac{\partial w}{\partial t} + v_x \frac{\partial w}{\partial x}\right),\tag{37}$$

in which *w* is the transverse deflection of the structure. Using the method of variables separation for  $\Phi$ , we have

$$\Phi(\mathbf{x}, \mathbf{r}, \theta, \mathbf{t}) = \sum_{m=1}^{M} \sum_{n=0}^{N} \Phi_m(\mathbf{x}) \psi_{m,n}(\mathbf{r}) \cos(n\,\theta) \mathbf{f}_{m,n}(\mathbf{t}), \quad (38)$$

Substituting Eq. (38) into Eq. (33) and assuming regularity condition at r = 0 for the for potential of perturbation velocity yields

$$\Phi_{m} = \sin\left(\frac{m\pi x}{L}\right),$$

$$\psi_{m,n}(\mathbf{r}) = I_{n}\left(\frac{m\pi r}{L}\right),$$
(39)

where  $I_n$  is the first kind modified Bessel function in the order of *n*. Combining Eqs. (38) and (39) yields

$$\Phi(\mathbf{x},\mathbf{r},\boldsymbol{\theta},\mathbf{t}) = \sum_{m=1}^{M} \sum_{n=0}^{N} \frac{L}{m\pi} \frac{I_n(m\pi r/L)}{I_n(m\pi R/L)} \left(\frac{\partial w}{\partial t} + v_x \frac{\partial w}{\partial x}\right), \quad (40)$$

in which  $I'_n$  is first derivative of  $I_n$ .

## 3.3 Energies of the fluid flow

Based on Green's theorem, the total energy of the fluid flow can be expressed as

$$E_{F}^{T} = \frac{1}{2} \rho_{e} \iiint_{\Gamma} \vec{V_{f}} \vec{V_{f}} d\Gamma = \frac{1}{2} \rho_{e} \iiint_{\Gamma} \nabla \Psi \cdot \nabla \Psi d\Gamma$$
  
$$= \frac{1}{2} \rho_{e} \iiint_{\Gamma} \left( \Psi \frac{\partial \Psi}{\partial \chi} \right) |_{Y} d\Upsilon, \qquad (41)$$

where  $\Gamma$  is the cylindrical fluid volume inside the shell;  $\Upsilon$  is the boundary surface of this volume;  $\chi$  is the coordinate along the normal to the boundary which is positive outward. Integrating Eq. (41) on the three main surfaces yields

$$E_{F}^{T} = \frac{1}{2} \rho_{e} \int_{0}^{2\pi} \int_{0}^{L} \left( \Psi \frac{\partial \Psi}{\partial r} \right)_{r=R} dx R d\theta$$
  
+  $\frac{1}{2} \rho_{e} \int_{0}^{2\pi} \int_{0}^{R} \left( \Psi \frac{\partial \Psi}{\partial x} \right)_{x=L} r dr d\theta$  (42)  
-  $\frac{1}{2} \rho_{e} \int_{0}^{2\pi} \int_{0}^{R} \left( \Psi \frac{\partial \Psi}{\partial x} \right)_{x=0} r dr d\theta,$ 

Using Eqs. (32), Eq. (42) can be expressed as

$$E_{F}^{T} = \frac{1}{2} \rho_{e} \int_{0}^{2\pi} \int_{0}^{L} \left( \Phi \frac{\partial \Phi}{\partial r} \right)_{r=R} dx R d\theta$$
  
+  $\frac{1}{2} \rho_{e} \int_{0}^{2\pi} \int_{0}^{L} \left( v_{x} x \frac{\partial \Phi}{\partial r} \right)_{r=R} dx R d\theta$  (43)

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$$+\frac{1}{2}\rho_{e}\int_{0}^{2\pi}\int_{0}^{R}\left(\nu_{x}x\frac{\partial\Phi}{\partial x}\right)_{x=L}rdrd\theta$$

$$+\frac{1}{2}\rho_{e}v_{x}^{2}\pi R^{2}L,$$
(43)

Based on Amabili *et al.* (2009), the second, third and forth terms of above relation can be neglected. However, substituting Eq. (43) into Eq. (43) yields

$$E_{F}^{T} = \frac{1}{2} \rho_{e} \int_{0}^{2\pi} \int_{0}^{L} \left\{ \sum_{m=1}^{M} \sum_{n=0}^{N} \frac{L}{m\pi} \frac{I_{n}(m\pi r/L)}{I_{n}(m\pi R/L)} \right\} \left( \left( \frac{\partial w}{\partial t} \right)^{2} + v_{x} \left( \frac{\partial w}{\partial x} \frac{\partial w}{\partial t} \right) + v_{x}^{2} \left( \frac{\partial w}{\partial t} \right)^{2} \right) dxRd\theta,$$

$$(44)$$

The above equation can be distinguished into the three following terms

$$\boldsymbol{E}_{F}^{T} = \boldsymbol{T}_{F} + \boldsymbol{\mathrm{E}}_{G} - \boldsymbol{U}_{F}, \qquad (45)$$

where  $T_F$ ,  $E_G$  and  $V_F$  are kinetic, gyroscopic and potential energies of the fluid flow which can be expressed as follows

$$T_{F} = \frac{1}{2} \rho_{e} \int_{0}^{2\pi} \int_{0}^{L} \left\{ \sum_{m=1}^{M} \sum_{n=0}^{N} \frac{L}{m\pi} \frac{I_{n}(m\pi r/L)}{I_{n}(m\pi R/L)} \left(\frac{\partial w}{\partial t}\right)^{2} \right\} dxRd\,\theta, \quad (46)$$

$$E_{G} = \frac{1}{2} \rho_{e} \int_{0}^{2\pi} \int_{0}^{L} \left\{ \sum_{m=1}^{N} \sum_{n=0}^{N} \frac{L}{m\pi} \frac{I_{n}(m\pi r/L)}{I_{n}(m\pi R/L)} \right\}$$

$$\left( v_{x} \left( \frac{\partial w}{\partial x} \frac{\partial w}{\partial t} \right) \right) dxRd\theta,$$

$$(47)$$

$$U_{F} = \frac{1}{2} \rho_{e} \int_{0}^{2\pi} \int_{0}^{L} \left\{ \sum_{m=1}^{M} \sum_{n=0}^{N} \frac{L}{m\pi} \frac{I_{n}(m\pi r / L)}{I_{n}(m\pi R / L)} \right\} dx R d\theta,$$

$$(48)$$

#### 4. Motion equations and solution

The motion equations can be derived based on Lagrange equations as follows

$$\frac{d}{dt}\left[\frac{\partial(T_{P}+T_{F}+E_{G})}{\partial\dot{q}_{k}}\right] - \frac{\partial(T_{P}+T_{F}+E_{G})}{\partial q_{k}} + \frac{\partial(U_{P}+U_{F})}{\partial q_{k}} = \frac{\partial(W_{FV}+W_{P})}{\partial q_{k}}, \ k = 1,..,\mathrm{H}$$

$$(49)$$

where  $\{q\}$  is degree of freedoms (DOFs) and *H* is dimension of vector  $\{q\}$  which may be calculated as  $H = N^{DOF} + M$ . Assuming simply supported boundary conditions at the both ends of the pipe, the mode expansions can be expressed as follows (Amabili *et al.* 2009)

$$\{q\} = \sum_{m=1}^{M} \sum_{n=0}^{N} \sin\left(\frac{(2\,\mathrm{m}-1)\pi\,\mathrm{x}}{L}\right) \left[\{q_{mn}^{c}\}\cos(n\,\theta) + \{q_{mn}^{s}\}\sin(n\,\theta)\right],$$
(50)

in which m and n are longitudinal half wave number and circumferential wave number, respectively; M and N are maximum value of wave numbers;

 $\{q\} = \{u_{mn}^c, u_{mn}^s, v_{mn}^c, v_{mn}^s, w_{mn}^c, w_{mn}^s, \psi_{xmn}^c, \psi_{xmn}^s, \psi_{xmn}^c, \psi_{\theta m n}^s, \psi_{\theta m n}^c, \psi_{\theta m n}^s\} \text{ are time-dependent DOFs.}$ 

## 5. Numerical results and discussion

In this section, a pipe with the length to radius ration of L/R = 4, thickness to radius of h/R = 0.02 is considered. The pipe is made from Poly methyl methacrylate (PMMA) with constant Poisson's ratios of  $v_m = 0.34$ , temperature-dependent thermal coefficient of  $a_m = (1 + 0.0005T) \times 10^{-6}/K$ , and temperature-dependent Young moduli of  $E_m = (3.52 - 0.0034T)$  GPa in which  $T = T_0 + \Delta T$  and  $T_0 = 300 K$  (room temperature) (Kolahchi *et al.* 2016). In addition, the pipe is reinforced by CNTs with the Hill's constants of  $k_r = 30$  GPa,  $l_r = 10$  GPa,  $m_r = 1$  GPa,  $n_r = 450$  GPa and  $p_r = 30$  GPa (Shi and Feng 2004). The inside fluid is water mixed by AL<sub>2</sub>O<sub>3</sub> nanoparticles with the thermo-physical properties listed in Table 1 (Sheikhzadeh *et al.* 2013).

## 5.1 Temperature distribution

The temperature distribution in the thickness direction of the pipe is shown in Fig. 2. As can be seen, the temperature in the outer surface of the pipe is higher than the inner one since the heat generation source is in the outer surface of the pipe.

# 5.2 Defining the critical fluid velocity

In Figs. 3(a) and (b), the imaginary and real parts of

Table 1 Thermophysical properties of water and AL<sub>2</sub>O<sub>3</sub> nanoparticles

	<i>k</i> (W/mK)	$c_p$ (J/kg K)	ho (kg/m <sup>3</sup> )	<i>T</i> (K)
Water	0.59	4182	998.2	293
$AL_2O_3$	0.85	765	3970	293

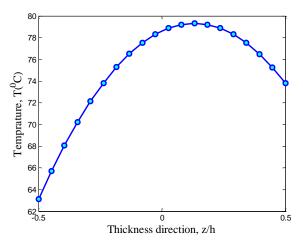


Fig. 2 The temperature distribution in the thickness direction of the pipe

eigenvalue versus fluid are shown. The imaginary and real parts of eigenvalue are frequency (Im( $\Omega$ )) and damping (Re( $\Omega$ )) of the structure, respectively. As can be seen, frequency decreases with increasing fluid velocity, while the damping remains zero. These imply that the system is stable. When the frequency becomes zero, critical velocity is reached, which the system loses its stability due to the divergence via a pitchfork bifurcation. Hence, the Re( $\Omega$ ) have the positive real parts, which the system becomes unstable. In this state, both real and imaginary parts of frequency become zero at the same point. In this point (critical fluid velocity), the critical Reynolds (Re =  $\rho_e v_x D / \mu_e$ ) and Nusselt numbers can be happened. In this paper, the Nusselt number is calculated by *St* Pr<sup>2/3</sup> = f/8 where St and Pr are Stanton and Prandtl numbers, respectively.

#### 5.3 Validation

At the first for results validation of this work, the Al<sub>2</sub>O<sub>3</sub> nanoparticles and CNTs as well as thermal load are neglected and the critical fluid velocity in a pipe conveying fluid is studied. The structure parameters of the classical shell assumed as h/R = 0.01, L/R = 2, E = 206 GPa, v = 0.3,  $\rho = 7850$  Kg/m<sup>3</sup> and the water density  $\rho_f = 1000$  Kg/m<sup>3</sup>. A non-dimensional fluid velocity is defined as  $u_f = V/{\{\pi^2/L[D/\rho h]\}}^{0.5}$ , with  $D = Eh^3/[12(1 - v^2)]$ , and a non-

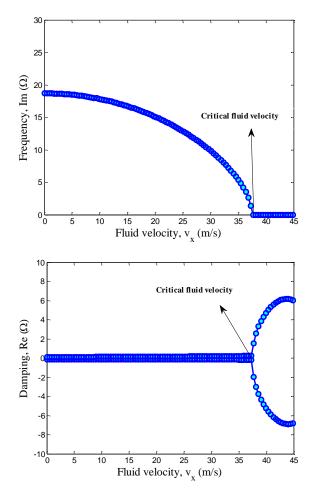


Fig. 3 (a) Imaginary part of frequency versus flow velocity; (b) Real part of frequency versus flow velocity

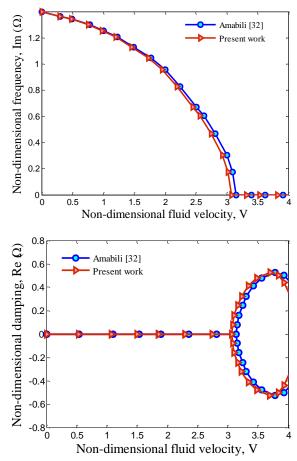


Fig. 4 (a) Imaginary part of frequency versus dimensionless flow velocity; (b) Real part of frequency versus dimensionless flow velocity

dimensional eigenvalue is also defined as  $\omega = \lambda/\{\pi^2/L^2[D/\rho h]\}^{0.5}$ , where  $\lambda$  is the eigenvalue. Figs. 4(a) and (b) illustrate the imaginary and real parts of frequency versus dimensionless flow velocity, respectively. As can be seen, the obtained results are close with the results of Amabili (2008), indicating validation of our work.

#### 5.4 The effect of different parameters

The effect of CNTs volume percent on the critical fluid velocity, critical Reynolds number and critical Nusselt number is shown in Figs. 5(a)-(c), respectively as a function of heat generation. As can be seen, with increasing the heat generation, the critical fluid velocity is decreased about 49% since the stiffness of the structure reduces and in lower fluid velocity, the pipe becomes unstable. With respect to the direct relation between Reynolds number and fluid velocity, the critical Reynolds number is also decreased with increasing the heat generation value. In addition, the Nusselt number has a direct relation with the Reynolds number. Hence, with decreasing the critical Reynolds number, the critical Nusselt number is also declining. It also concluded that the critical fluid velocity, critical Reynolds number and critical Nusselt number of the pipe without CNTs as reinforce  $(c_r = 0)$  are higher than those of the nanocomposite pipe ( $c_r \neq 0$ ). In other words, with increasing

the CNTs volume percent, the critical fluid velocity, critical Reynolds number and critical Nusselt number will be increased. In other words, for heat generation of Q = 10 MW/m<sup>3</sup>, reinforcing the pipe with 0.04% CNTs, the critical fluid velocity improves about 25% which means the instability will be happened at higher fluid velocity. In addition, the critical Nusselt number and consequently the heat transfer are increased about 20% with adding 0.04% CNTs to the pipe which is very useful in heat exchanges.

The critical fluid velocity, critical Reynolds number and critical Nusselt number are presented in Figs. 6(a)-(c), respectively versus the heat generation for different AL<sub>2</sub>O<sub>3</sub> nanoparticles volume percents. The critical fluid velocity, critical Reynolds number and critical Nusselt number for Q = 0 and  $\phi = 6\%$  are respectively, 46.48 m/s, 1.925e6 and 3572 while these values for Q = 50 MW/m<sup>3</sup> are respectively, 23.74 m/s, 0.98e6 and 2087. This means that with applying heat generation of Q = 50 MW/m<sup>3</sup>, the

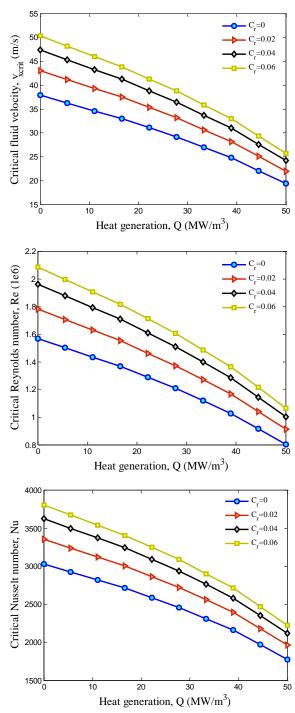


Fig. 5 The effect of heat generation and CNTs volume percent on the (a) critical fluid velocity; (b) critical Reynolds number; (c) critical Nusselt number

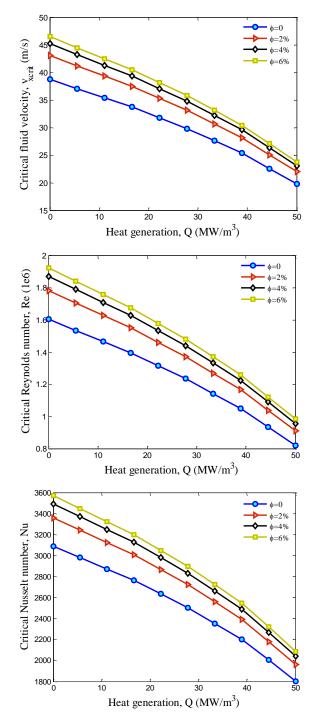


Fig. 6 The effect of heat generation and AL<sub>2</sub>O<sub>3</sub> nanoparticles volume percent on the (a) critical fluid velocity; (b) critical Reynolds number; (c) critical Nusselt number

critical fluid velocity, critical Reynolds number and critical Nusselt number are decreased about 49%, 49% and 41%. This is physically reasonable since applying heat generation leads to lower stiffness in the pipe and consequently, the pipe becomes instable at lower fluid velocities. About the effect of  $AL_2O_3$  nanoparticles volume percent, it should be noted that with increasing the  $AL_2O_3$  nanoparticles volume percent in the fluid, the critical fluid velocity, critical Reynolds number and critical fluid velocity, critical Reynolds number and critical fluid velocity, critical Reynolds

number and critical Nusselt number for the fluid without the nanoparticles are 35.39 m/s, 1.466e6 and 2872 while these values are 42.47 m/s, 1.759e6 and 3323, respectively. Consequently, adding 6%  $AL_2O_3$  nanoparticles to the fluid increases 20% the critical fluid velocity and 15% the Nusselt number. It physically means that the  $AL_2O_3$  nanoparticles improve the heat transfer in the fluid which can be useful for heat exchangers.

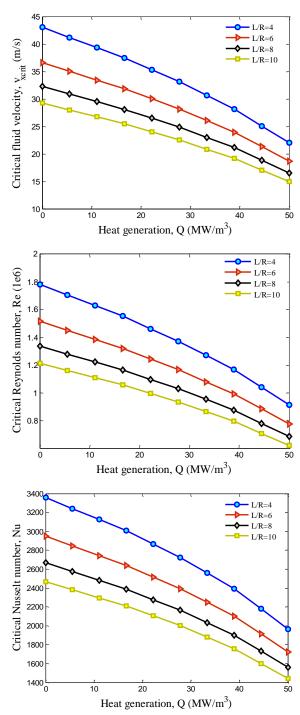


Fig. 7 The effect of heat generation and length to radius ratio of pipe on the (a) critical fluid velocity; (b) critical Reynolds number; (c) critical Nusselt number

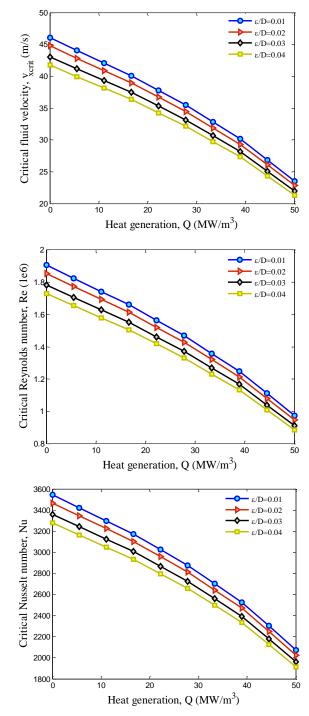


Fig. 8 The effect of heat generation and shell surface roughness to diameter ratio of pipe on the (a) critical fluid velocity; (b) critical Reynolds number; (c) critical Nusselt number

Figs. 7(a)-(c) illustrate the effect of length to radius ratio of the pipe on the critical fluid velocity, critical Reynolds number and critical Nusselt number, respectively versus the heat generation. It can be seen that with increasing the length to radius ratio of the pipe, the critical fluid velocity, critical Reynolds number and critical Nusselt number are decreased. This is due to this fact that with raising the length to radius ratio of the pipe, the stiffness of the pipe decreases and consequently, the pipe will be unstable at lower fluid velocities. Furthermore, with enhancing the length to radius ratio of the pipe, the heat transfer in the pipe decreases.

The effects of shell surface roughness to diameter ratio and heat generation are shown on the critical fluid velocity, critical Reynolds number and critical Nusselt number, respectively. It can be seen that as the shell surface roughness to diameter ratio increases, the critical fluid velocity decreases and the pipe becomes instable at higher fluid velocities. In addition, with raising the shell surface roughness to diameter ratio, the critical Nusselt number decreases and consequently the heat transfer of the inside fluid is declined.

# 6. Conclusions

Instability of the nanocomposite pipes conveying nanofluid was presented in this paper subjected to thermal loads. The pipe was reinforced by CNTs and the fluid was mixed by AL<sub>2</sub>O<sub>3</sub> nanoparticles. The structure was subjected to convection of inner fluid, convection of outer fluid, conduction of the pipe and heat generation. The material properties of the pipes were assumed temperaturedependent and structure was subjected to magnetic field. The inner fluid was considered turbulent and the forces of the viscosity and turbulent pressure were taken into account using momentum equations of the fluid. For modeling of the pipe, the FSDT theory in conjunction with energy method was used. In order to couple the equation of the nanofluid and nanocomposite pipe, the Lagrange method was used. Based on semi-analytical method, the critical fluid velocity and critical Reynolds and Nusselt numbers were calculated. The effects of CNTs volume percent, AL<sub>2</sub>O<sub>3</sub> nanoparticles volume percent, length to radius ratio of the pipe and shell surface roughness were shown on the critical fluid velocity and Reynolds and Nusselt numbers. The most findings of this paper were:

- With increasing the heat generation, the critical fluid velocity was decreased about 49% since the stiffness of the structure reduces and in lower fluid velocity, the pipe becomes unstable.
- For heat generation of  $Q = 10 \text{ MW/m}^3$ , With increasing the CNTs volume percent, the critical fluid velocity and critical Reynolds number as well as critical Nusselt number will be increased about 25% and 29%, respectively.
- Adding 6% AL<sub>2</sub>O<sub>3</sub> nanoparticles to the fluid increases 20% the critical fluid velocity and 15% the Nusselt number.

- With increasing the length to radius ratio of the pipe, the critical fluid velocity, critical Reynolds number and critical Nusselt number were decreased.
- As the shell surface roughness to diameter ratio increases, the critical fluid velocity decreases and the pipe becomes instable at higher fluid velocities. In addition, with raising the shell surface roughness to diameter ratio, the critical Nusselt number decreases and consequently the heat transfer of the inside fluid was declined.

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