Applications of Remote & Real-Time Sensing, Artificial Intelligence, and Edge Computing in Structural/Wind Engineering

**Thomas Kang** 

**Seoul National University** 



## Contents

- Concrete compressive strength prediction using ML
- Wind pressure coefficients prediction using LSTM RNN
- Determination of basic wind speed using machine learning method
- Smart NDT using DL & edge computing
- References



Condition	OPC w/o admixture	Concrete w/o AE	Concrete w/ AE	OPC	High early strength Portland Cement	Moderate heat Portland Cement
Estimation Equation	$\frac{w}{c} = \frac{215}{f_{28} + 210}$	$\frac{w}{c} = \frac{23}{f_{28} + 13.9}$	$\frac{w}{c} = \frac{16.2}{f_{28} + 7.4}$	$\frac{w}{c} = \frac{51}{\frac{f_{28}}{k} + 0.31}$	$\frac{w}{c} = \frac{41}{\frac{f_{28}}{k} + 0.17}$	$\frac{w}{c} = \frac{66}{\frac{f_{28}}{k} + 0.64}$
Reference	Korea Concrete Standard Specification (1999)	US ACI 21	1.1 (1993)	-	ction Standard Spe otes the strength c	

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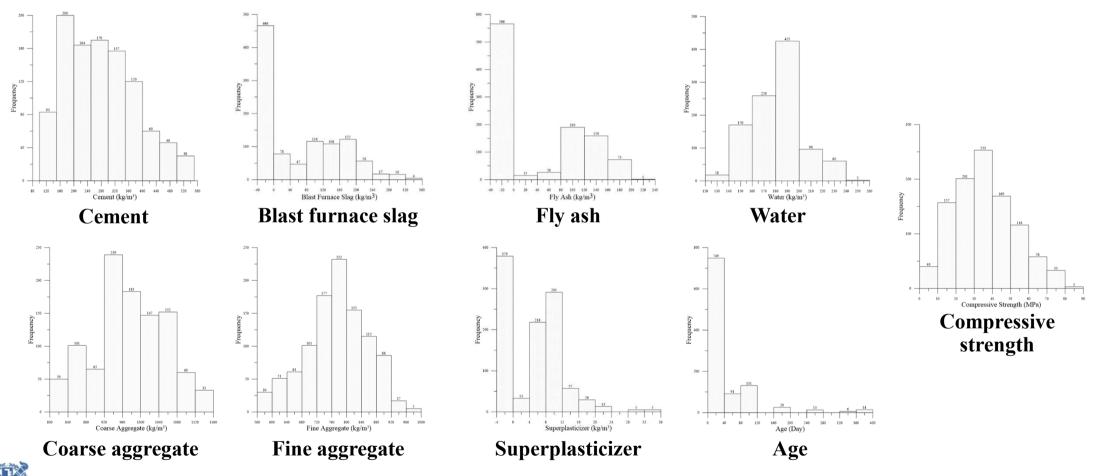


- Dataset was created by combining 38 data from experiments and 1030 data from open-source.
- Total dataset (1068) was divided into training set (748; 70%) and testing set (320; 30%).



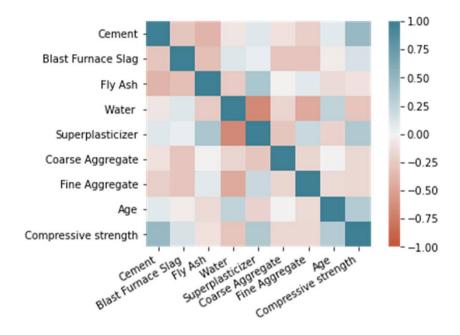
1	A	В	C	D	E	F	G	Н	I
1	Cement (component 1)(kg in a m^3 mixture)	Blast Furnace Slag (component 2)(kg in a m^3 mixture)	Fly Ash (component 3)(kg in a m^3 mixture)	Water (component 4)(kg in a m^3 mixture)	Superplastici zer (component 5)(kg in a m^3 mixture)	Coarse Aggregate (component 6)(kg in a m^3 mixture)	Fine Aggregate (component 7)(kg in a m^3 mixture)	Age (day)	Concrete compressive strength(MPa, megapascals)
2	540.0	0.0	0.0	162.0	2.5	1040.0	676.0	28	79.99
3	540.0	0.0	0.0	162.0	2.5	1055.0	676.0	28	61.89
4	332.5	142.5	0.0	228.0	0.0	932.0	594.0	270	40.27
5	332.5	142.5	0.0	228.0	0.0	932.0	594.0	365	41.05
6	198.6	132.4	0.0	192.0	0.0	978.4	825.5	360	44.30
7	266.0	114.0	0.0	228.0	0.0	932.0	670.0	90	47.03
8	380.0	95.0	0.0	228.0	0.0	932.0	594.0	365	43.70
9	380.0	95.0	0.0	228.0	0.0	932.0	594.0	28	36.45
10	266.0	114.0	0.0	228.0	0.0	932.0	670.0	28	45.85
11	475.0	0.0	0.0	228.0	0.0	932.0	594.0	28	39.29
12	198.6	132.4	0.0	192.0	0.0	978.4	825.5	90	38.07
13	198.6	132.4	0.0	192.0	0.0	978.4	825.5	28	28.02
14	427.5	47.5	0.0	228.0	0.0	932.0	594.0	270	43.01
15	190.0	190.0	0.0	228.0	0.0	932.0	670.0	90	42.33
16	304.0	76.0	0.0	228.0	0.0	932.0	670.0	28	47.81
17	380.0	0.0	0.0	228.0	0.0	932.0	670.0	90	52.91
18	139.6	209.4	0.0	192.0	0.0	1047.0	806.9	90	39.36
19	342.0	38.0	0.0	228.0	0.0	932.0	670.0	365	56.14
20	380.0	95.0	0.0	228.0	0.0	932.0	594.0	90	40.56
21	475.0	0.0	0.0	228.0	0.0	932.0	594.0	180	42.62
22	427.5	47.5	0.0	228.0	0.0	932.0	594.0	180	41.84
23	139.6	209.4	0.0	192.0	0.0	1047.0	806.9	28	28,24
24	139.6	209.4	0.0	192.0	0.0	1047.0	806.9	3	8.06
25	139.6	209.4	0.0	192.0	0.0	1047.0	806.9	180	44.21
26	380.0	0.0	0.0	228.0	0.0	932.0	670.0	365	52.52
27	380.0	0.0	0.0	228.0	0.0	932.0	670.0	270	53.30
28	380.0	95.0	0.0	228.0	0.0	932.0	594.0	270	41.15
29	342.0	38.0	0.0	228.0	0.0	932.0	670.0	180	52.12
30	1275	175	0.0	228.0	0.0	032.0	504.0	28	37 / 3







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### • Heat map visualization

# **Compressive strength (target)**

1) Positive effect

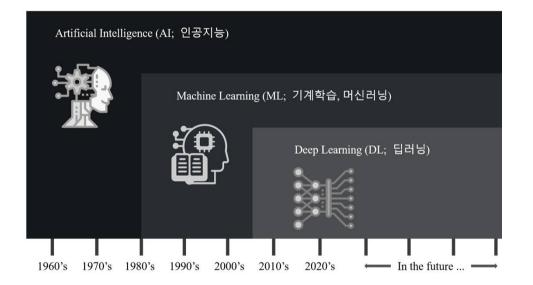
: Cement, blast furnace slag, superplasticizer, and age

### 2) Negative effect

: Fly ash, water, coarse aggregate, and fine aggregate



• In this study, several machine learning models were introduced to compare regression performance.

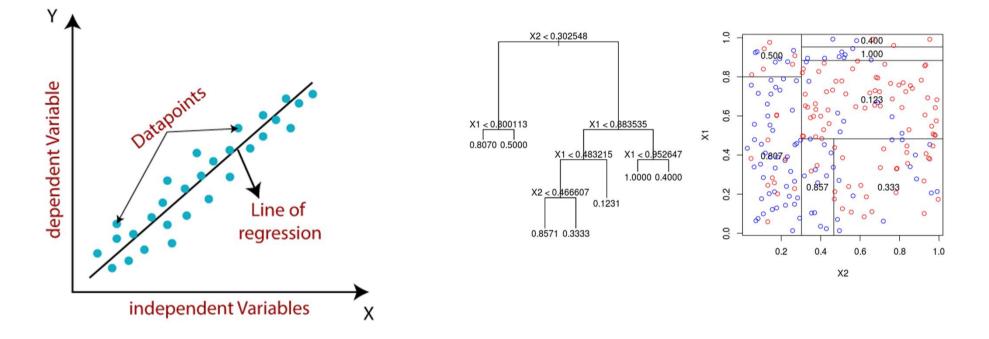


- Linear Regression
- Decision Tree
- Ensemble Tree
- Support Vector Machine
- Gaussian Process Regression
- Neural Network (Deep Learning)



• Linear regression

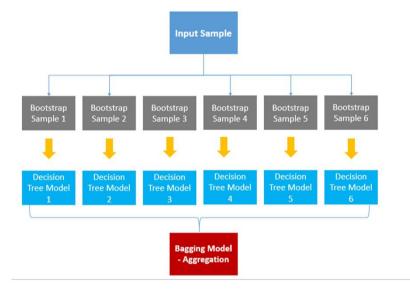
#### • Decision tree

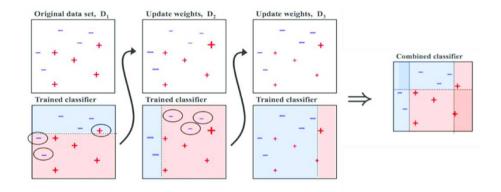




**Ensemble (Bagged trees)** ٠

• Ensemble (Boosted trees)





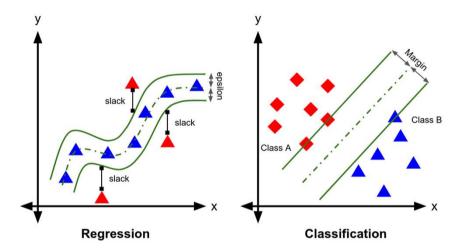


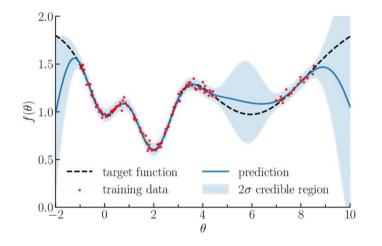
https://bkshin.tistory.com/entry/%EB%A8%B8%EC%8B%A0%EB%9F%AC%EB%8B%9D-11-%EC%95%99%EC%83%81%EB%B8%94-%ED%95%99%EC%8A%B5-Ensemble-Learning-%EB%B0%EA%B9%85Bagging%EA%B3%BC-%ED%95%99%EC%8A%B5-Ensemble-Learning-%EB%B0%EA%B9%85Bagging%EA%B3%BC-%ED%95%99%EC%8A%B5-Ensemble-Learning-%EB%B0%EA%B9%85Bagging%EA%B3%BC-%ED%95%99%EC%8A%B5-Ensemble-Learning-%EB%B0%EA%B9%85Bagging%EA%B3%BC-%ED%95%99%EC%8A%B5-Ensemble-Learning-%EB%B0%EA%B9%85Bagging%EA%B3%BC-%ED%95%99%EC%8A%B5-Ensemble-Learning-%EB%B0%EA%B9%85Bagging%EA%B3%BC-%ED%95%99%EC%8A%B5-Ensemble-Learning-%EB%B0%EA%B9%85Bagging%EA%B3%BC-%ED%95%99%EC%8A%B5-Ensemble-Learning-%EB%B0%EA%B9%85Bagging%EA%B3%BC-%ED%95%99%EC%8A%B5-Ensemble-Learning-%EB%B0%EA%B3%B5-%ED%95%99%EC%8A%B5-%ED%95%99%EC%8A%B5-%ED%95%99%EC%8A%B5-%ED%95%99%EC%8A%B5-%ED%95%99%EC%8A%B5-%ED%95%99%EC%8A%B5-%ED%95%99%EC%8A%B5-%ED%95%99%EC%8A%B5-%ED%95%99%EC%8A%B5-%ED%95%99%EC%8A%B5-%ED%95%99%EC%8A%B5-%ED%95%99%EC%8A%B5-%ED%95%99%EC%8A%B5-%ED%95%99%EC%8A%B5-%ED%95%9%EC%8A%B5-%ED%95%9%EC%8A%B5-%ED%98%EC%8A%B5%EC%8A% %EB%B6%80%EC%8A%A4%ED%8C%85Boosting

swallow.github.io / Medium (Boosting and Bagging explained with examples)

• Support Vector Machine

Gaussian process regression

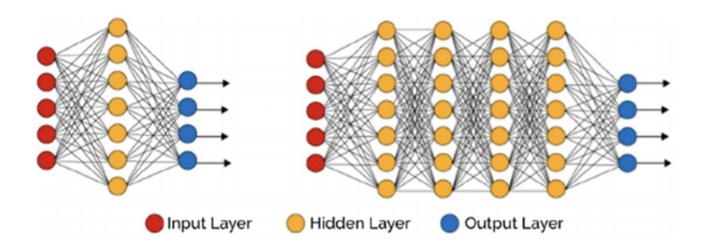






https://medium.com/it-paragon/support-vector-machine-regression-cf65348b6345 https://www.researchgate.net/figure/Illustration-of-Gaussian-process-regression-in-one-dimension-for-the-target-test\_fig1\_327613136

### • Neural network





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- Data preprocessing (normalization)
- : Min-max scaler

$$x_{scaled} = rac{x-x_{min}}{x_{max}-x_{min}}$$

• How to evaluate model performance?

1) RMSE

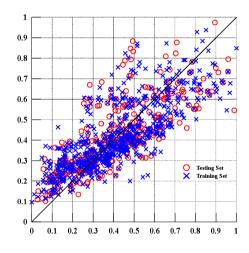
2) R-square

**3) MAE** 

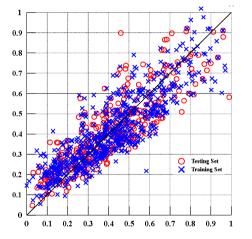
$$MAE = \frac{1}{N} \sum_{i=1}^{N} |y_i - \hat{y}| \qquad R^2 = 1 - \frac{\sum(y_i - \hat{y})^2}{\sum(y_i - \bar{y})^2}$$
$$MSE = \frac{1}{N} \sum_{i=1}^{N} (y_i - \hat{y})^2 \qquad \qquad \text{Where,}$$
$$\hat{y} - predicted value of y$$
$$\bar{y} - mean value of y$$
$$RMSE = \sqrt{MSE} = \sqrt{\frac{1}{N} \sum_{i=1}^{N} (y_i - \hat{y})^2}$$



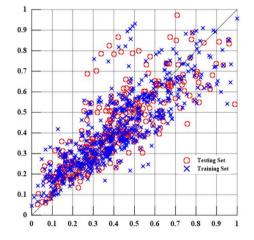
• Linear Regression (LR)

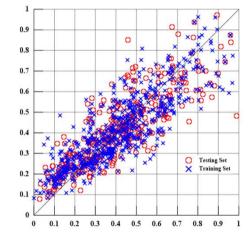


Simple LR



Interactions LR





Robust LR

Stepwise LR

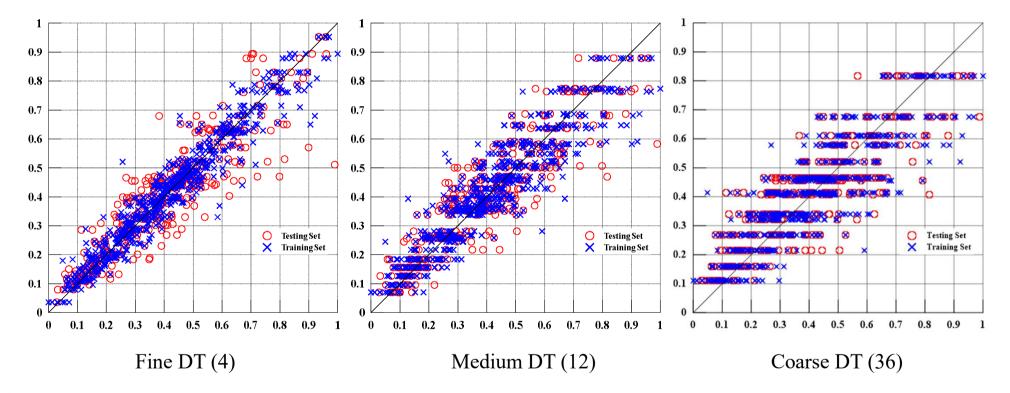


Types of Machine		RMSE		Coefficient of Determination		MAE	
Learnin	Learning Model		Testing	Training	Testing	Training	Testing
Linear Regression (LR)	Simple LR	0.1286	0.1325	0.6236	0.5926	0.1006	0.1035
	Interactions LR	0.1051	0.1085	0.7554	0.7269	0.0821	0.0858
	Robust LR	0.1109	0.2119	0.8326	-0.0415	0.1060	0.1190
	Stepwise LR	0.1095	0.1116	0.7296	0.6850	0.0848	0.0894

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• Decision Tree (DT)



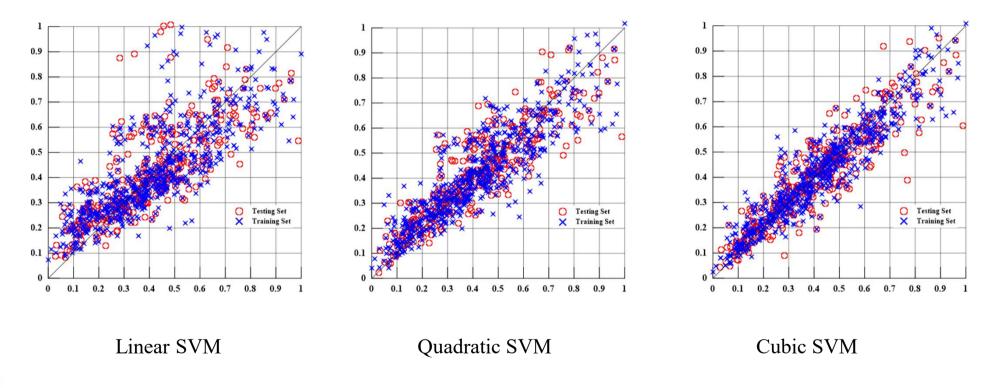


Types of Machine Learning Model		RMSE		Coefficient of Determination		MAE	
		Training	Testing	Training	Testing	Training	Testing
Decision Tree (DT)	Fine DT	0.0539	0.0894	0.9329	0.8147	0.0381	0.0640
	Medium DT	0.0802	0.0933	0.8515	0.7983	0.0598	0.0729
	Coarse DT	0.1072	0.1160	0.7348	0.6980	0.0828	0.0925

-0

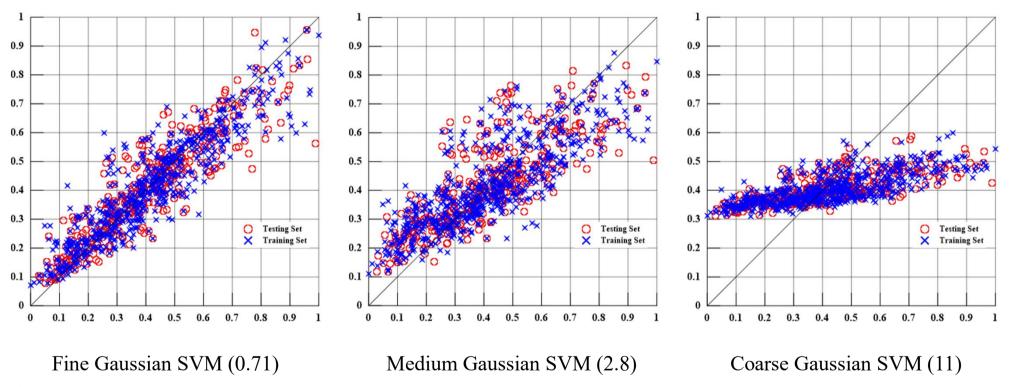


• Support Vector Machine (SVM)





• Support Vector Machine (SVM)



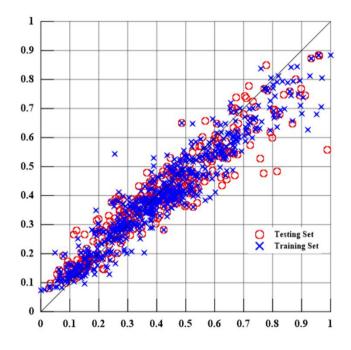


Types of Machine Learning Model		RMSE		Coefficient of Determination		MAE	
		Training	Testing	Training	Testing	Training	Testing
	Linear SVM	0.1341	0.1474	0.5850	0.4964	0.0985	0.1048
	Quadratic SVM	0.0948	0.0963	0.7926	0.7847	0.0707	0.0717
Support	Cubic SVM	0.0738	0.0851	0.8745	0.8319	0.0534	0.0622
Support Vector Machine	Fine Gaussian SVM	0.0825	0.0882	0.8430	0.8197	0.0595	0.0652
(SVM)	Medium Gaussian SVM	0.1207	0.1253	0.6637	0.6362	0.0947	0.0987
	Coarse Gaussian SVM	0.1731	0.1740	0.3085	0.2976	0.1391	0.1396

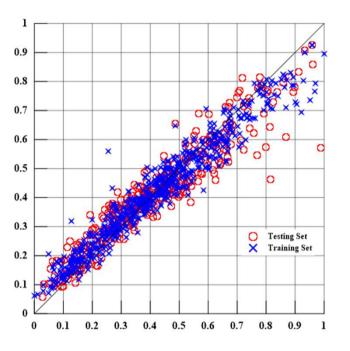
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• Ensemble (EN)



Boosted Trees EN



Bagged Trees EN

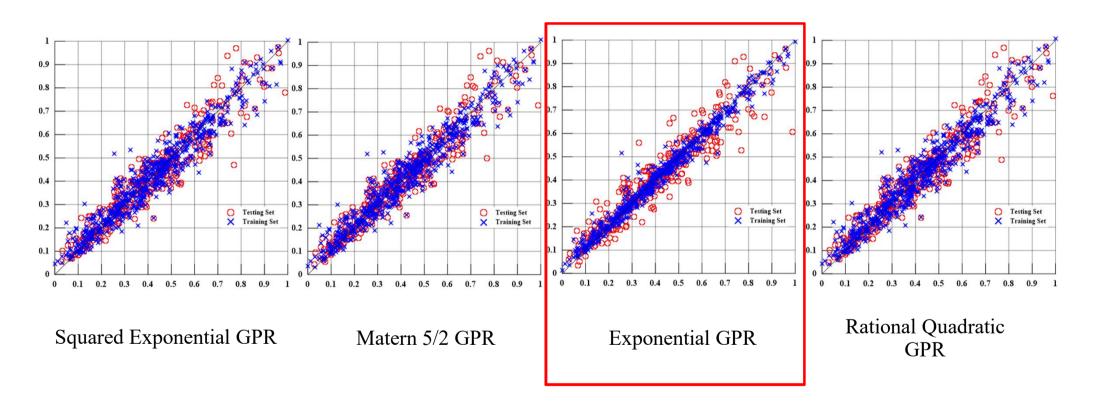


Types of Machine Learning Model		RMSE		Coefficient of Determination		MAE	
		Training	Testing	Training	Testing	Training	Testing
Ensemble (EN)	Boosted Trees EN	0.0671	0.0786	0.8963	0.8569	0.0508	0.0584
	Bagged Trees EN	0.0553	0.0717	0.9293	0.8807	0.0410	0.0536

-0



• Gaussian Process Regression (GPR)

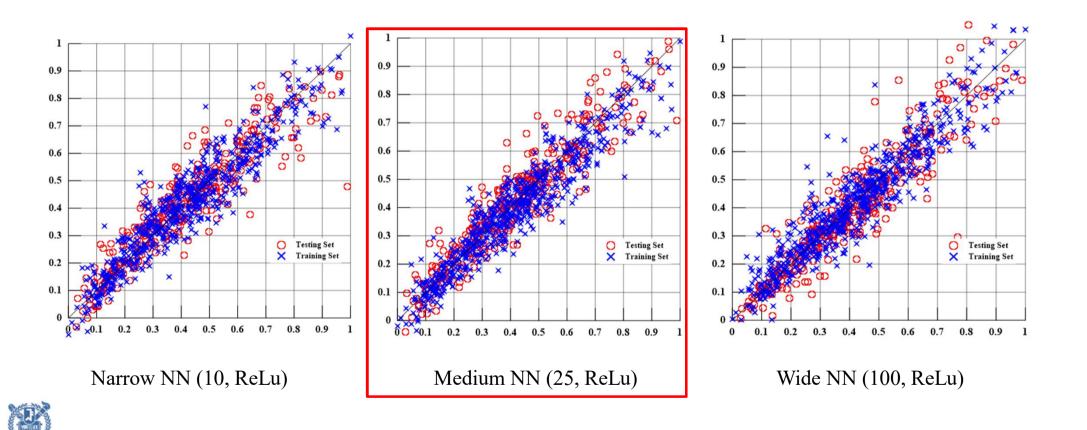


Types of Machine		RMSE		Coefficient of Determination		MAE	
Learnin	Learning Model		Testing	Training	Testing	Training	Testing
	Squared Exponential GPR	0.0544	0.0665	0.9318	0.8976	0.0406	0.0509
Gaussian Process	Matern 5/2 GPR	0.0517	0.0646	0.9383	0.9033	0.0382	0.0488
Regression (GPR)	Exponential GPR	0.0315	0.0661	0.9771	0.8988	0.0211	0.0473
	Rational Quadratic GPR	0.0540	0.0658	0.9326	0.8997	0.0403	0.0505

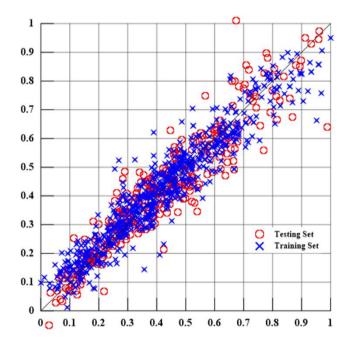
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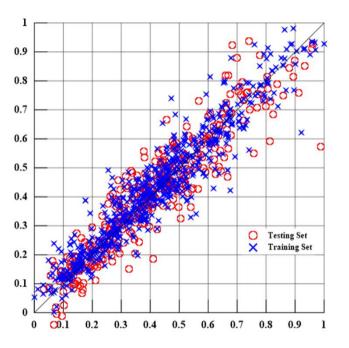
• Neural Network (NN)



• Neural Network (NN)



Bi-layered NN ([10, 10], ReLu)



Tri-layered NN ([10, 10, 10], ReLu)



Types of Machine Learning Model		RMSE		Coefficient of Determination		MAE	
		Training	Testing	Training	Testing	Training	Testing
Neural Network (NN)	Narrow NN	0.0652	0.0874	0.9020	0.8229	0.0484	0.0663
	Medium NN	0.0610	0.0699	0.9140	0.8867	0.0435	0.0526
	Wide NN	0.0721	0.0863	0.8802	0.8274	0.0528	0.0598
	Bi-layered NN	0.0747	0.0702	0.8714	0.8858	0.0577	0.0543
	Tri-layered NN	0.0711	0.0783	0.8833	0.8579	0.0537	0.0604

-0

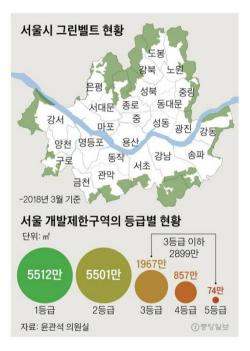


# Summary

- For concrete compressive strength prediction, cement, blast furnace slag, fly ash, water, superplasticizer, coarse aggregate, fine aggregate, and age were used as input variables.
- As shown in the results, GPR (Gaussian Process Regression) and ANN (Artificial Neural Network) models outperformed other machine learning models.
- By considering more variables such as curing temperature, humidity, and detailed aggregate size information, the prediction accuracy of machine learning models can be improved in the future.



## **Research Background**



Lack of Lands to Develop



**Increasing City Density** 

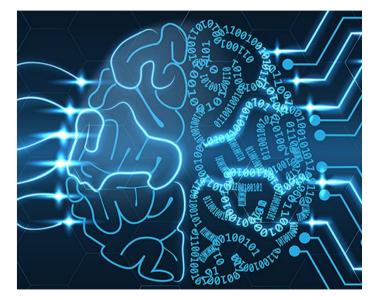


**Emerging High-rise Building** 

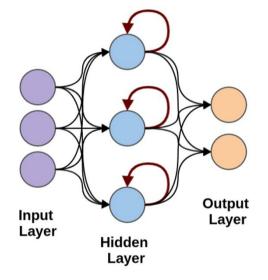


#### **Problem Statement & Research Objective**

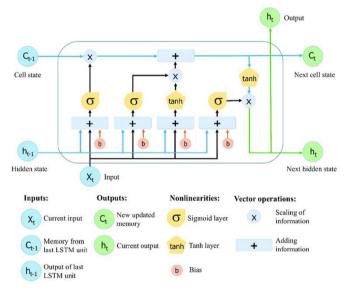
# "How to Evaluate Wind Load More Smartly?"



**Deep Learning** 



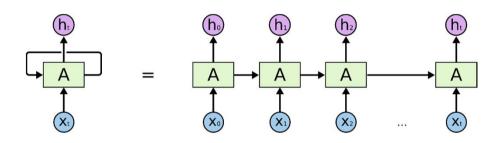
**Recurrent Neural Network** 



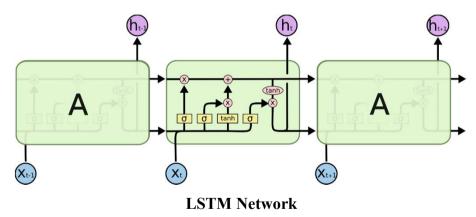
#### Long Short Term Memory Cell Model

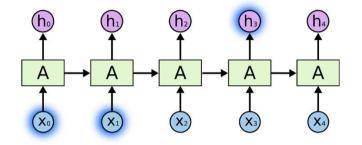


# **Theoretical Background**

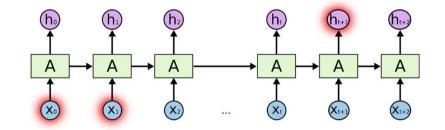


**Recurrent Neural Network** 





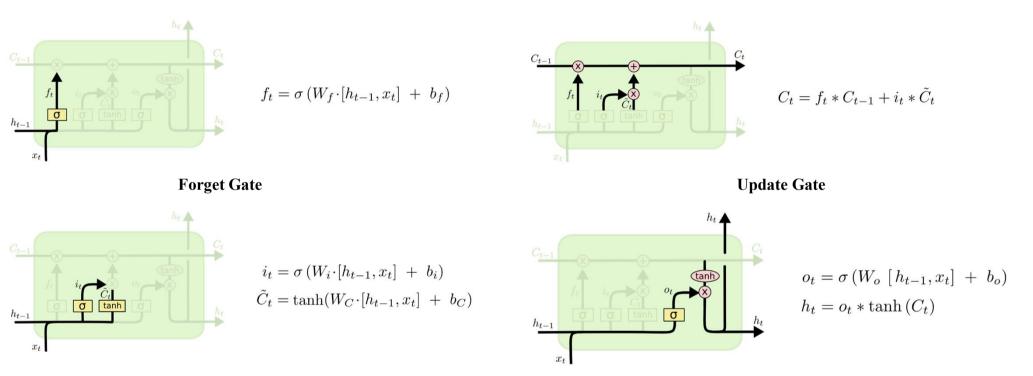
Predict Output Using Previous and Current Data



**Problem of Long Term Dependency** 



**Theoretical Background** 

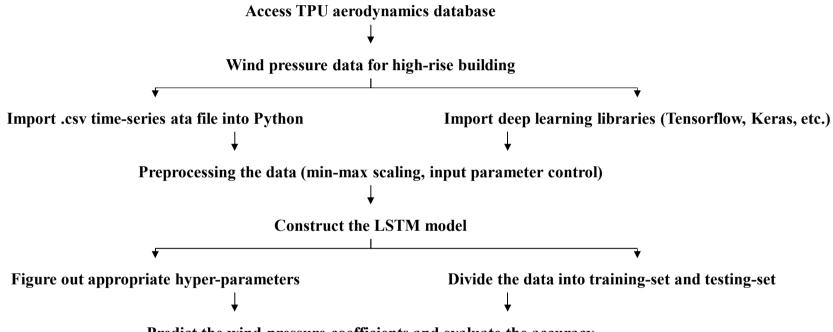


Input Gate

**Output Gate** 



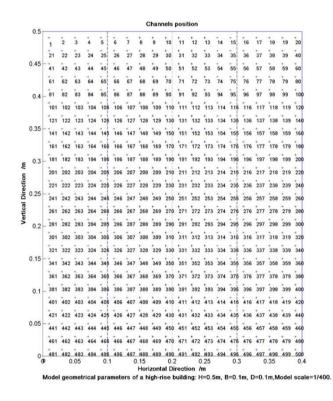
#### **Research Framework**



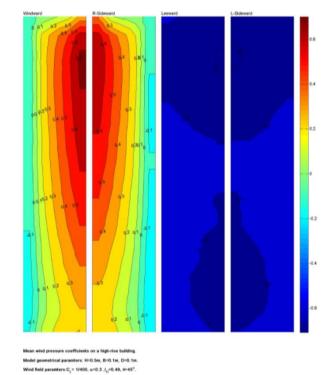
Predict the wind-pressure coefficients and evaluate the accuracy



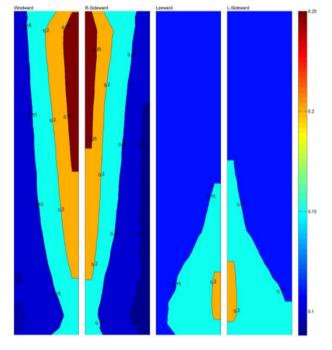
#### **Data Exploration**



**Pressure Tap Locations** 



45 degree – Mean value



RMS wind pressure coefficients on a high-rise building. Model geometrical paramters: H=0.5m, B=0.1m, D=0.1m Wind field paramters:Ct\_= 1/400, u=0.3, lt\_=0.49, 0=45°.

45 degree – RMS value



### Methodology

#### **Time-Series Data**

Wind Attack Angles : 11 angles 0, 5, 10, 15, 20, 25, 30, 35, 40, 45, 50 degrees

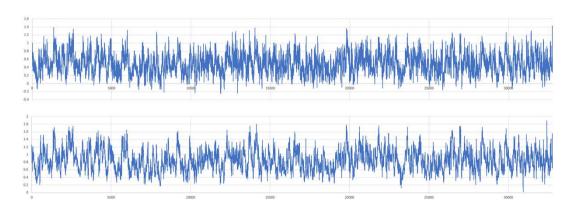
Each data has 32768 points during 32.768 sec. Training Set : 26214 points (80%) Testing Set : 6554 points (20%)

500 pressure taps : 500 time-series x 32768 points

 $\ensuremath{\overset{\scriptstyle \leftrightarrow}{\scriptstyle}}$  All data are normalized with min-max scaler

#### **Hyper-parameters**

Epoch : 100 Drop-out Ratio : 0.05 Batch Size : 10





# Wind Pressure Coefficients Prediction Using LSTM RNN

#### **Model Development**

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In [57]:	<pre>imodel = tf.keras.Sequential() model.add(tf.keras.layers.LESIN(128, input_shape = (win_length, num_features), return_sequences = True)) model.add(tf.keras.layers.LesIN(128, return_sequences = True)) model.add(tf.keras.layers.LESIN(128, return_sequences = True)) model.add(tf.keras.layers.Dropot(0.05)) model.add(tf.keras.layers.Dropot(0.05))</pre>			<pre>In [59]: early_stopping = tf.keras.callbacks.EarlyStopping(monitor='val_loss',</pre>
In [58]:	]: model.summary()			validation_data=test_generator,
	Model: "sequential_4"			shuffle=False, callbacks=[early_stopping])
	Layer (type)	Output Shape	Param #	Epoch 1/100
	lstm_12 (LSTM)	(None, 2, 128)	302080	2622/2622 [==================================
	leaky_re_lu_8 (LeakyReLU)	(None, 2, 128)	0	Epoch 2/100 2622/2622 [==================================
	Istm_13 (LSTM)	(None, 2, 128)	131584	solute_error: 0.1372
	leaky_re_lu_9 (LeakyReLU)	(None, 2, 128)	0	Epoch 3/100 2622/2622 [==================================
	dropout_8 (Dropout)	(None, 2, 128)	0	solute_error: 0.1394 Epoch 4/100
	Istm_14 (LSTM)	(None, 64)	49408	2622/2622 [=======] - 15s 6ms/step - loss: 0.0285 - mean_absolute_error: 0.1355 - val_loss: 0.0298 - val_mean_ab solute_error: 0.1333
	dropout_9 (Dropout)	(None, 64)	0	Epoch 5/100
	dense_4 (Dense)	(None, 1)	65	2622/2622 [==================================
	Total params: 483,137 Trainable params: 483,137 Non-trainable params: 0			Epoch 6/100 2622/2622 [========] - 15s 6ms/step - loss: 0.0266 - mean_absolute_error: 0.1321 - val_loss: 0.0293 - val_mean_ab solute_error: 0.1324 Epoch 7/100

#### **Building LSTM Model**

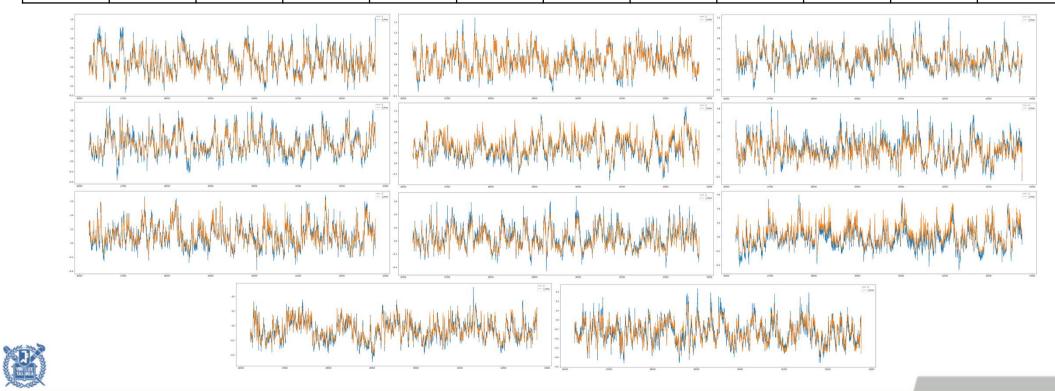
**Training Network** 



# Wind Pressure Coefficients Prediction Using LSTM RNN

#### Results

Attack Angle	0 deg	5 deg	10 deg	15 deg	20 deg	25 deg	30 deg	35 deg	40 deg	45 deg	50 deg
RMSE	0.04993	0.03380	0.04038	0.04504	0.04224	0.04564	0.03601	0.03911	0.05655	0.03961	0.04659



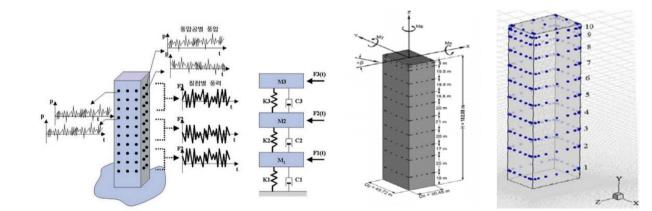
#### Wind Pressure Coefficients Prediction Using LSTM RNN

#### Discussion

Attack Angle	0 deg	5 deg	10 deg	15 deg	20 deg	25 deg	30 deg	35 deg	40 deg	45 deg	50 deg
RMSE	0.04993	0.03380	0.04038	0.04504	0.04224	0.04564	0.03601	0.03911	0.05655	0.03961	0.04659

Quite accurate wind pressure coefficients prediction with all attack angles

Needs more accuracy for peak estimation to use in the wind load calculation – adjustment factor may need to be analyzed separately.



0305.2.1 밀폐형건축물 밀폐형건축물의 주골조설계용 설계풍압  $p_F$ 는 다음 식으로 산정한다.  $p_F = G_D q_H (C_{e1} - C_{pe2})$  (N/m2) (0305.2.2) 단, 원형평면을 가진 건축물의 경우에는  $C_{e1} - C_{pe2}$  대신에  $C_D$ 를 적용한다. 여기서,  $q_H$  : 기준높이 H에 대한 설계속도압(N/m2) (0305.5에 따른다)  $G_D$  : 풍방향가스트영향계수(0305.6에 따른다)  $C_{pe1}$  : 풍상벽의 외압계수(0305.7.1에 따른다)  $C_{pe2}$  : 풍하벽의 외압계수(0305.7.1에 따른다)  $C_D$  : 풍력계수(0305.7.3의 (1)에 따른다)



# **Determination of Basic Wind Speed**

# **Using Machine Learning Method**



#### Consideration of terrain features from satellite imagery in machine learning of basic wind speed

#### Donghyeok Lee<sup>a</sup>, Seung Yong Jeong<sup>b,\*</sup>, Thomas H.-K. Kang<sup>b</sup>

<sup>6</sup> Dept. of Artificial Intelligence, Seoul National University, 1 Gwanak-ro, Gwanak-gu, Seoul, 08826, South Korea
<sup>b</sup> Dept. of Architecture and Architectural Engineering, Seoul National University, 1 Gwanak-ro, Gwanak-gu, Seoul, 08826, South Korea

A R T I C L E I N F O	A B S T R A C T
Kowards: Isaaic wind preed Isaaic imagery Machine terming K-NN SimCLR	Basic wind speed is a basis for calculating design wind loads (including wind environment evaluation) or structures at a specific site. Because structural design of high-rise buildings is typically governed by wind loads accurate estimation of basic wind speed, which has been done by converting observed data for a region to the imposed at a height of 10 m on flat open terrain, is important. Although equations within codes attempt to tak into accurat terrain features by considering effects such as surface roughness and topography, it is often difficul to apply them to real conditions due to terrain complexity. To overcome the limitation of engineering iudgment consideration of the terrain features forom stellite manageries using machine learning algorithm is proposed. Th number of selected weather stations, terrain similarity, distance from station, and machine learning algorithm is proposed. Th ombilityer perception (MLP) are also investigated as parameters or methodology. The estimation accurace y shown to be high in the order of the MLP method and methods of considering judgment tance, terrain similarity only, and distance only (traditional engineering judgment).

#### 1. Introduction

In the design of structures, one of the primary lateral loading conditions considered is seismic or wind load [1–5,49]. Wind load and its application largely depend on wind speed at the site. To determine wind load, design codes presently reference wind speed for a particular region, which is called basic wind speed. Determination of basic wind speed is constructed from decades of observed wind speed data from weather stations and reflects climate of the site. It is generalized by specific terrain conditions for an application in design practice. Significant research on the determination of basic wind speed has been conducted and advorted in desire no codes [6–10].

Except for averaging time and mean recurrence interval (MRI), the definition of basic wind speed in design codes such as ASCE 7–16 [11], Korean Building Code (KBC 2016) [12], ISO 4354 [13], and AIJ 2015 [14] is wind speed set at ten (10) meters above ground and in flat open terrain. The definition of flat open terrain in each code is not identical but similar. To convert observed wind speed to basic wind speed, the effect of height and topography is considered. Wind speed varies with surface roughness conditions of the surrounding site. And the roughness is classified with vertical wind speed profiles presented for each category. Within the atmospheric boundary layer (ABL), wind speed increases with height, and as surface roughness increases, wind speed at the same height decreases. Above the ABL, wind speed is not affected by surface roughness and remains constant. Change in wind speed associated with terrains, such as escarpments and hills, is simply addressed by topography factors for limited and simplified topography conditions in current design codes.

Check for updates

Surface roughness over a wide area affects both wind speed and turbulence intensity with height. In reality, the roughness conditions are combined. ASCE 7-16 presents determination criteria of roughness categories for combined cases. However, application is difficult in complicated conditions.

Research on the effect of topography has been carried out using wind tunnel tests and CFD analysis [15–18]. Limitations of these researches are that wind tunnel tests and CFD analyses were carried out for simplified topography. For multiple roughness changes, Abdi and Bitsuamlak [19] used computational fluid dynamics (CFD) analysis. However, computation time required for the analysis currently renders itself inaporopriate for determination of basic wind speeds.

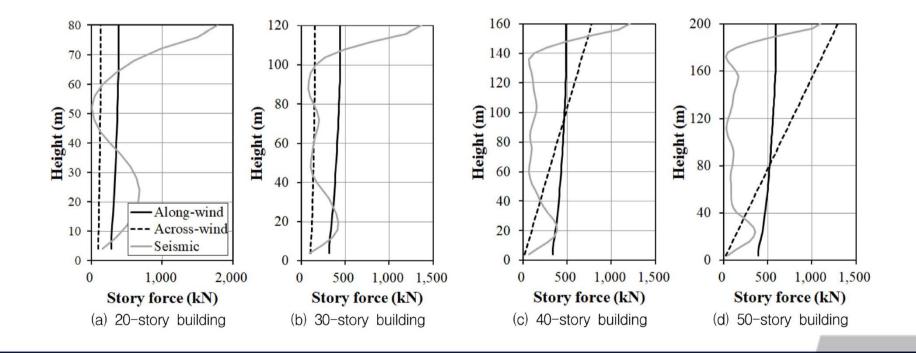
Although design codes and research papers present equations that consider effects of surface roughness and topography, there are

\* Corresponding author.

E-mail addresses: dhlee0224@snu.ac.kr (D. Lee), vkjer2@snu.ac.kr (S.Y. Jeong), tkang@snu.ac.kr (T.H.-K. Kang).

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- According to the existing study, in Korea, the magnitude of wind load is higher than that of seismic load in case of RC buildings with more than 30 stories.
- Wind load is determined by wind speed at construction site, and wind speed is generally provided by design codes or standards.

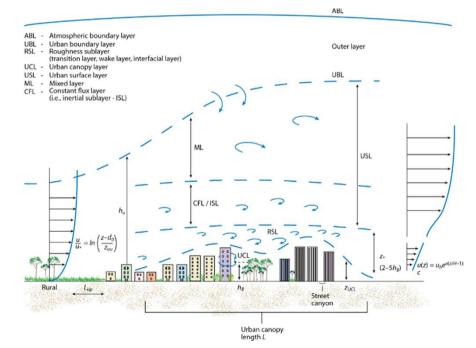




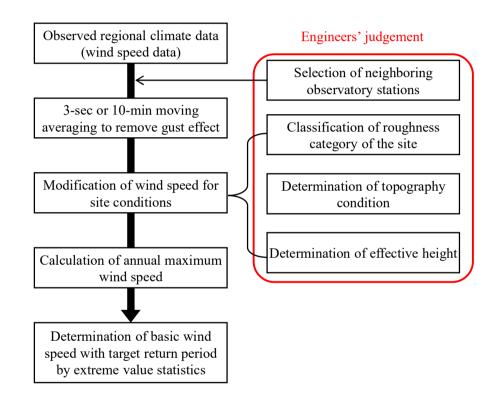
 $q_{H} = \frac{1}{2} \rho V_{H}^{2} [\text{N/m}^{2}]$  $V_{H} = V_{0} K_{zr} K_{zt} I_{w}$ 

- $\rho = \text{Air density} (1.22 \text{kg/m}^2)$
- $V_{H}$  = Design wind speed at height H [m/s]
- $V_0$  = Basic wind speed [m/s]
- $K_{zr}$  = Mean wind speed profile factor at height H
- $K_{zt}$  = Topography factor
- $I_w$  = Importance factor









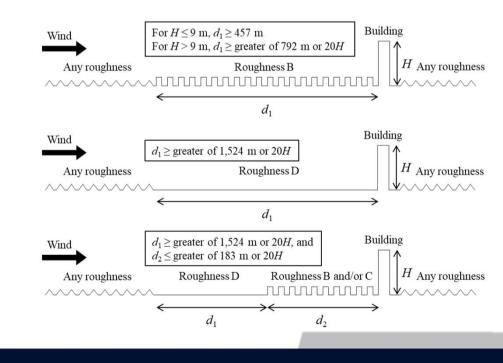
- KDS 41 10 15 and ASCE 7-22 present that the basic wind speed can be estimated based on observed wind speed data.
- However, the estimation of basic wind speed based on observed data requires several engineer's judgement.
  - ✓ <u>Selection of observatory stations</u>
  - ✓ <u>Classification of roughness category</u>
  - ✓ Determination of topographic condition
  - ✓ <u>Determination of effective height</u>
- In case of determination of ground roughness category, it may be inaccurate since it relies on the engineer's judgment based on satellite image or field observation

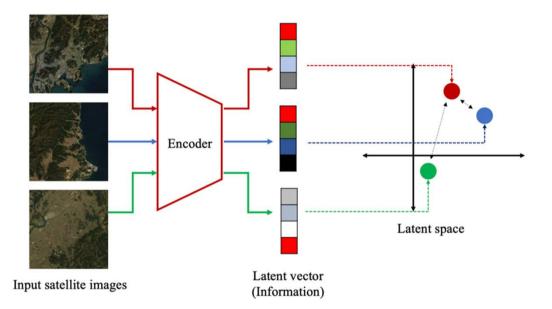




Surface Roughness	Description				
А	Large city center with closely spaced tall buildings higher than 10-story				
В	City with closely spaced residential houses with heights of 3.5 m or so or sc attered medium-rise buildings				
С	Open terrain with scattered obstructions with heights of $1.5 \sim 10$ m or so or scattered low-rise buildings				
D	Exposed open terrain with few obstructions or scattered obstructions less th an 1.5 m in height or grassland, beach, airport etc.				

- Depending on the wind direction, surface roughness category can be mixed and it is hard to make an unarguable decision.
- Since quantitative standard for surface roughness category does not exist, it is difficult to judge accurately.

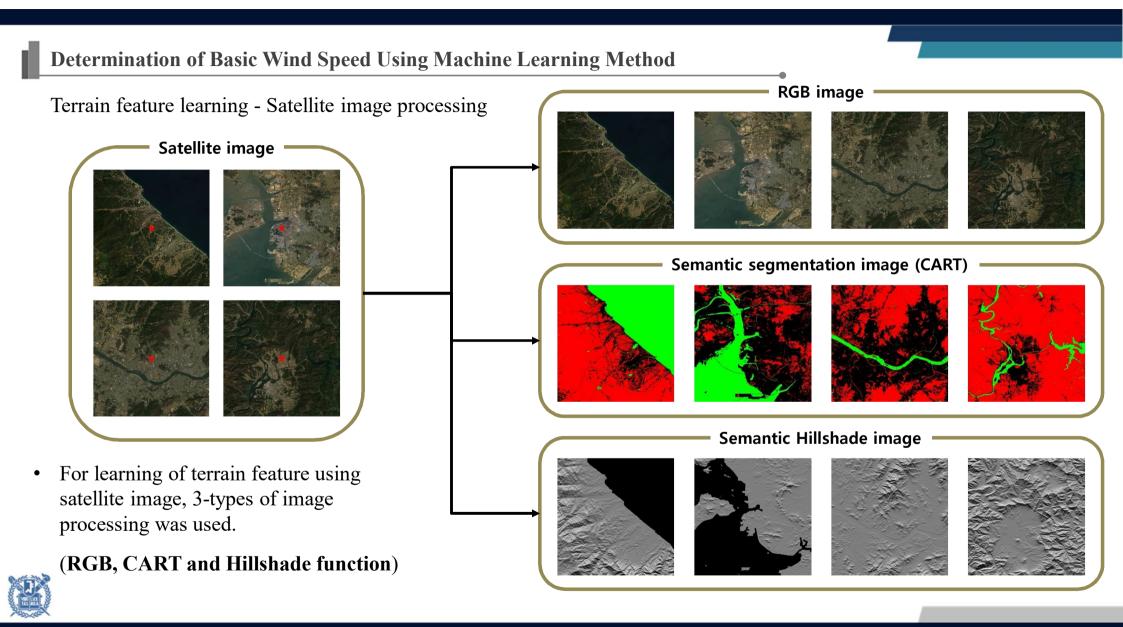


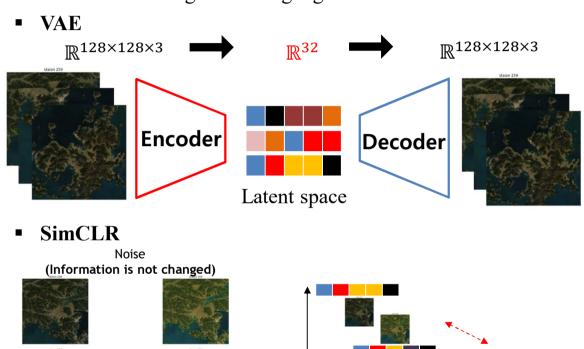


#### Quantitative representation of satellite images in latent space

- Machine learning has the advantage of being able to quantitatively determine high-dimensional data by decomposing high-dimensional data into low-dimensions.
- Deep learning as a method of machine learning, has advantages that it can handle high-dimension data, such as image.
- Since the topographical features expressed in satellite images are high-dimensional and abstract, they can be easily classified and quantitatively discriminated through machine learning.

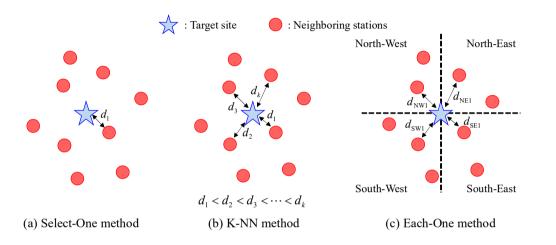






Terrain feature learning – Learning algorithm

- The encoder decomposes the satellite image into latent vector, and the decoder reconstructs the vector into original satellite image.
- Through this, the encoder is trained to store representative information of satellite images in a latent space.
- Adding artificial noise to input satellite image and training the learning model
- The model is trained to store representative terrain information of image in latent space <u>even</u> <u>if it has noise.</u>



Approach 1 - Prediction of basic wind speed by machine learning

#### ✓ Select-one method :

Select one nearest observatory station

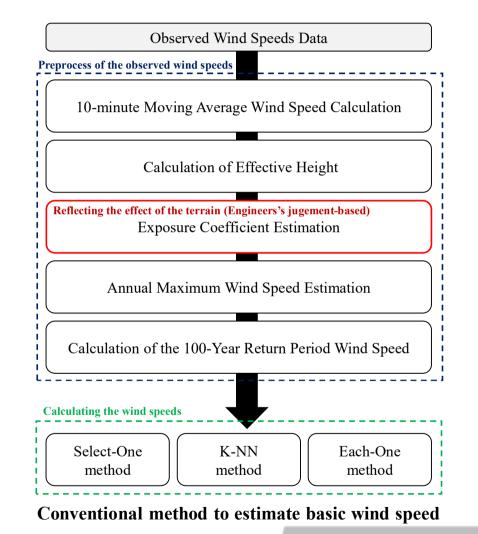
✓ K-NN method :

Select K number of nearest observatory station

✓ Each-one method:



Select one observatory station at each quarter



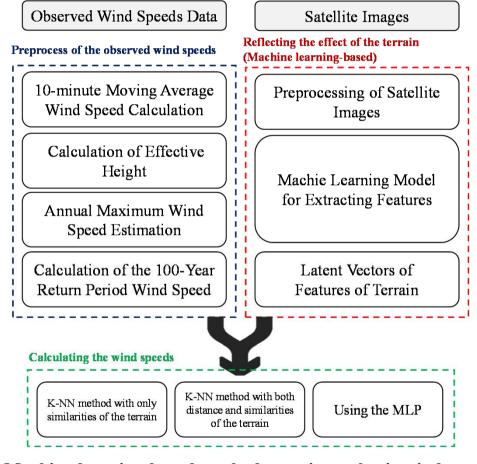
Approach 1 - Prediction of basic wind speed by machine learning

	All data (3	18 stations)	Except top 10 errors	Except top 20 errors
Method	Mean of errors	Standard deviation	Mean of errors	Mean of errors
	$(\mu_{error}), m/s$	of error ( $\sigma_{error}$ ), m/s	$(\mu_{error}), m/s$	$(\mu_{error}), m/s$
Select-Randomly	5.364	4.350	-	-
Select-One	4.252	3.405	3.928	3.669
K-NN (k = 5)	3.466	2.712	3.187	2.987
K-NN (k = 10)	3.368	2.660	3.087	2.900
K-NN (k = 15)	3.258	2.610	2.984	2.803
Each-One	3.556	2.773	3.271	3.072



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Approach 1 - Prediction of basic wind speed by machine learning



✓ K-NN method :

Select K number of nearest observatory stations.

 $\Rightarrow$  Best result in baseline experiment

- K-NN method with similarity of terrain : <u>Select K number of observatory station having only</u> <u>similar terrain feature with target site.</u>
- ✓ K-NN method with both distance & similarity : Select K number of nearest observatory station having similar terrain feature with target site.
- ✓ MLP (Multi-Layer Perceptron) :
  - Flexible artificial neural network
  - $\Rightarrow$  Trained model judges all.



Machine learning-based method to estimate basic wind speed

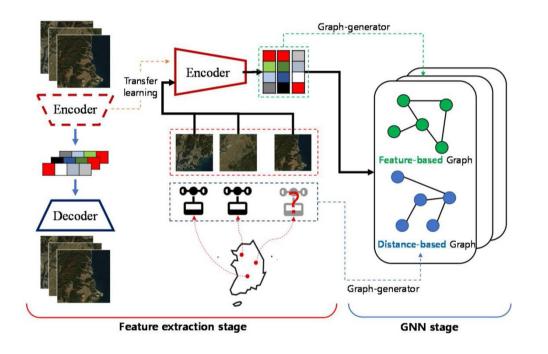
Approach 1 - Prediction of basic wind speed by machine learning

	All data (3	18 stations)	Except top 10 errors	Except top 20 errors	
Method	Mean of errorsStandard deviation $(\mu_{error})$ , m/sof error ( $\sigma_{error}$ ), m/s		Mean of errors $(\mu_{error})$ , m/s	Mean of errors $(\mu_{error})$ , m/s	
K-NN (k = 15) (Based on distance only)	3.258	2.610	2.984	2.803	
K-NN (k = 15) with machine learning (based on terrain similarity)	3.194	2.657	2.923	2.734	
K-NN (k = 15) with machine learning (based on both distance and terrain similarity)	3.182	2.640	2.908	2.725	
MLP (Multi-Layer Perceptron)	2.917	2.300	2.697	2.539	
Each-One	3.556	2.773	3.271	3.072	

• Result using artificial neural network showed the best accuracy

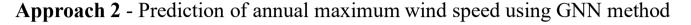


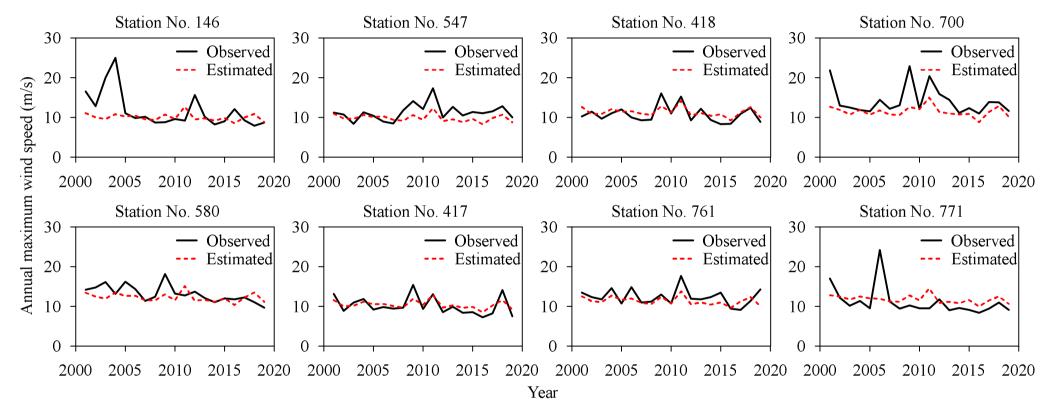
Approach 2 - Prediction of annual maximum wind speed using GNN method



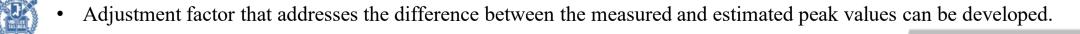
- In Approach 1, prediction performance using neural networks (MLP) is higher than the performance of other methods.
- However, Approach 1 could only be deriving a single value of the basic wind speed.
- Approach 2 uses Graph Neural Network (GNN) to predict the annual maximum wind speed for multi-years based on terrain information from satellite images.
- Results were compared with actual observed annual maximum wind speed data.







• Tendency of prediction and observed data was quite similar, but the accuracy of the peak value was insufficient.



#### Summary

- Terrain similarity can be considered through the terrain feature learned through machine learning.
- MLP model (deep learning), which predicts wind speed directly from the location information and terrain feature of the target site, showed the best accuracy.
- As a result of predicting the annual maximum wind speed using GNN (**Approach 2**), the tendency of prediction and observed data was quite similar, but the accuracy of the peak value was insufficient yet.
- The pattern of the predicted annual maximum wind speed was similar among the stations, but it was judged to be a characteristic of the wind load itself, not an overfitting problem.
- Additional research is needed on predictive models that can reflect wind direction and seasonal influences as well as terrain features.





# **Collapse Disaster**

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Seongsu Bridge Collapse (1994)



Gyeongju Mauna Resort Collapse (2014)



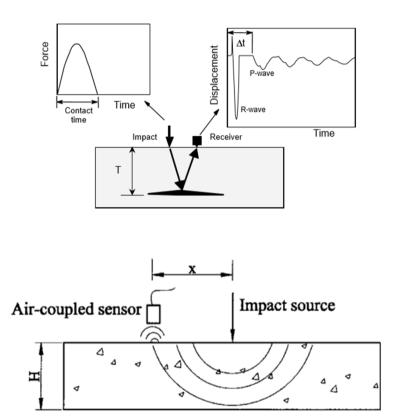
Sampoong Department Store Collapse (1995)

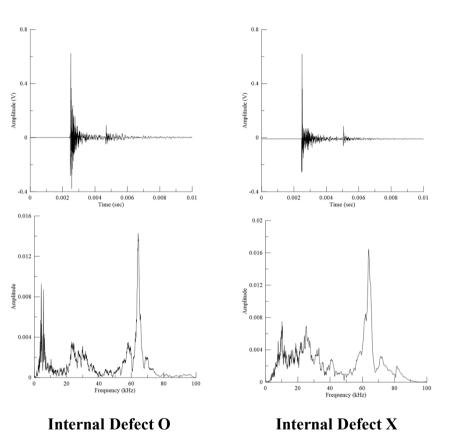


Gwang-ju Apartment Collapse (2022)



# Impact Echo System







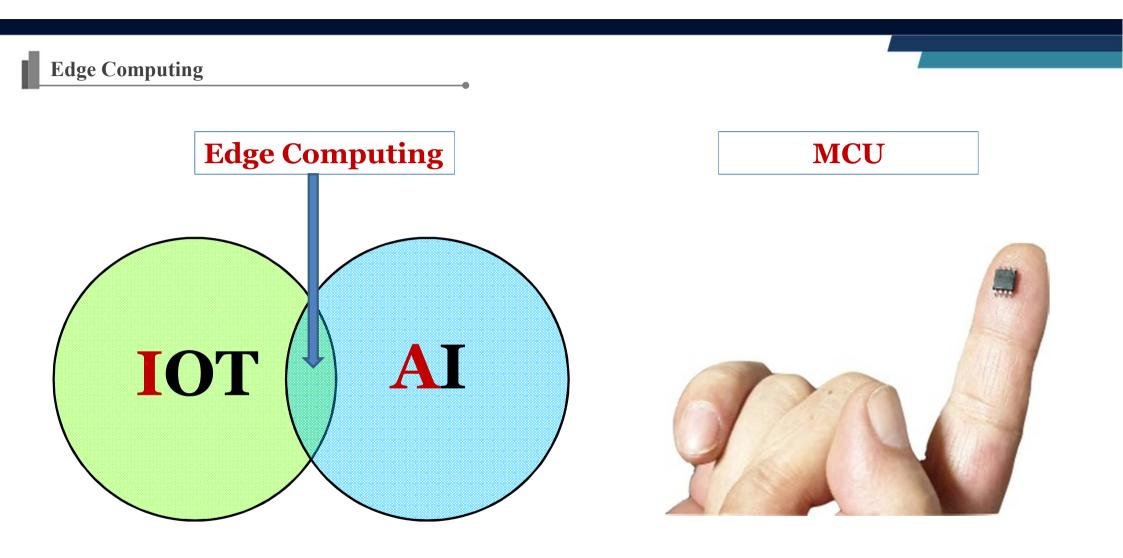




Why Edge Computing? Cloud Becomes Crowded.

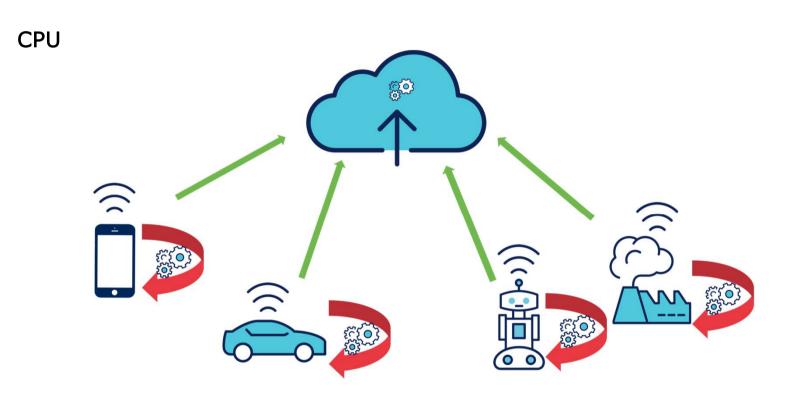










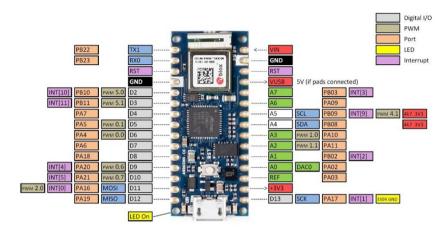




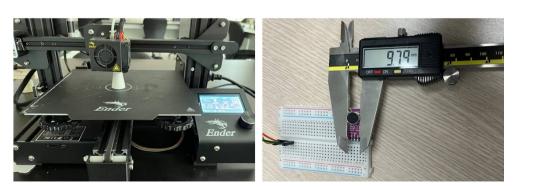
MCU

Catching right moment



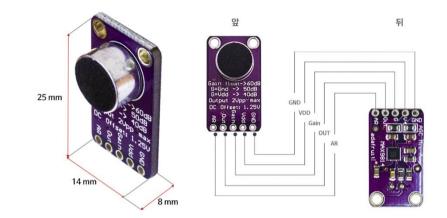


Arduino Nano 33 IoT (MCU)





3D Printed Sound Cone



MAX 9814 Microphone with Amplifier



Circuit & Manufacturing (Two Sensors)

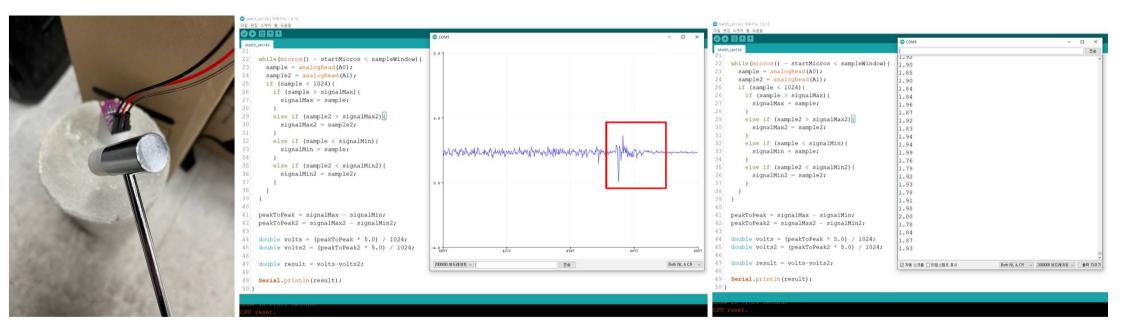
```
1 const int sampleWindow = 50; //Sample window width in microsec (50micros = 20kHz)
 2 unsigned int sample;
 3
 4 void setup() {
 5 Serial.begin(2000000);
 6 }
 7
 8 void loop() {
    unsigned long startMicros = micros(); //Start of sample window
 9
10
    unsigned int peakToPeak = 0; //Peak to peak level
11
     unsigned int peakToPeak2 = 0;
12
    unsigned int signalMax = 0;
13
14
    unsigned int signalMin = 1024;
15
16
    unsigned int signalMax2 = 0;
    unsigned int signalMin2 = 1024;
17
18
19
    int sample;
20
     int sample2;
21
22
    while(micros() - startMicros < sampleWindow) {</pre>
                                                                          💿 보드 매니저
23
       sample = analogRead(A0);
                                                                          EH2 AII
24
       sample2 = analogRead(A1);
25
       if (sample < 1024) {
26
         if (sample > signalMax) {
                                                                           Online Help
More Info
                                                                          버젼 선택 🗸 설치
27
           signalMax = sample;
28
         1
```

```
29
         else if (sample2 > signalMax2) {
           signalMax2 = sample2;
30
31
        }
32
         else if (sample < signalMin) {</pre>
33
           signalMin = sample;
34
         }
35
         else if (sample2 < signalMin2) {</pre>
36
           signalMin2 = sample2;
37
38
39
40
41
    peakToPeak = signalMax - signalMin;
    peakToPeak2 = signalMax2 - signalMin2;
42
43
44
    double volts = (peakToPeak * 5.0) / 1024;
45
    double volts2 = (peakToPeak2 * 5.0) / 1024;
46
47
    double result = volts-volts2;
48
49
    Serial.println(result);
50 }
```



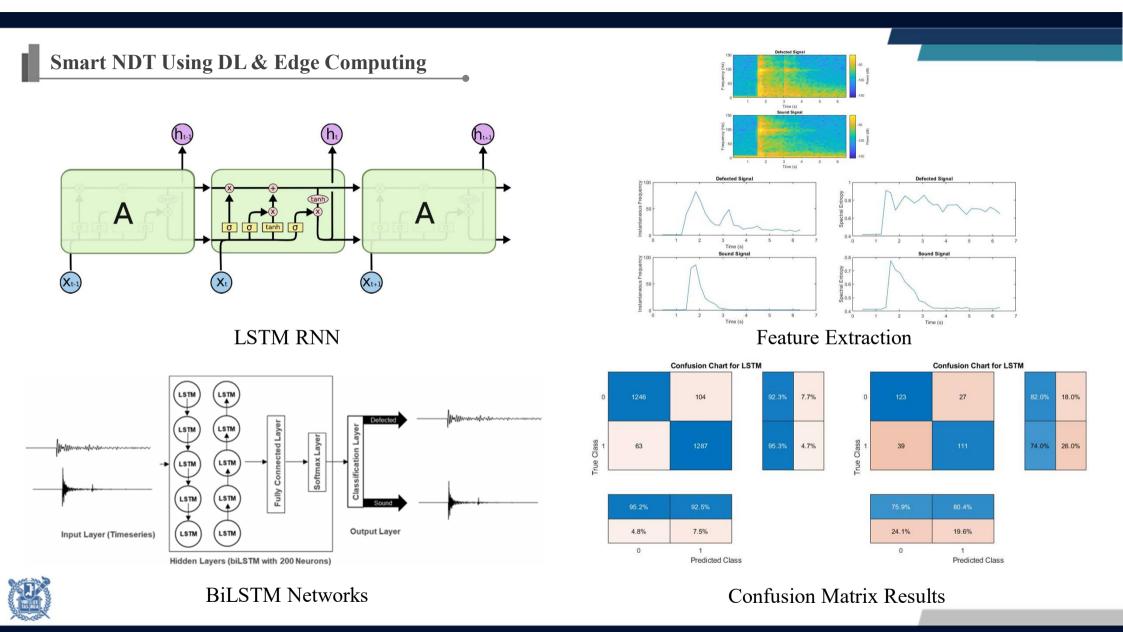






#### Data Reading / Recording with IDE





#### Summary

- Non-destructive testing is a critical maintenance method for ensuring the safety of structures, but it takes a highly competent individual with a great deal of knowledge as well as a significant investment of money and time.
- Internet of Things (IoT) device that enables impact-echo measurement was developed.
- For the classification of impact-echo time series data, bi-directional long-short term memory neural network was used.
- A pre-trained AI model was embedded in the MCU to implement real-time classification-capable edge computing.

